The Logic of Uncertainty with Irrational Agents

Germano Resconi¹ and Boris Kovalerchuk²

¹Dept. of Mathematics and Physics, Catholic University Brescia, I-25121, Italy, resconi@numerica.it. ²Dept. of Computer Science, Central Washington University, Ellensburg, WA 98922, USA, borisk@cwu.edu.

Abstract

Modern axiomatic uncertainty theories (fuzzy logic, probability theory and others) provide a calculus for manipulating with probabilities, membership functions, and degrees of belief when the initial values such as probabilities of elementary events are already given. These theories do not include a mechanism for getting initial uncertainty values. The value of these theories is in computing uncertainties of complex events that follow a structure imposed by axioms of a specific uncertainty theory. The lack of internal mechanism for getting initial values often means in the end that the same mechanism is applied for getting initial probability values, fuzzy logic membership functions, and belief functions. This is a source of much confusion -- what is the real difference between all of these theories. A resolution of this confusion is critical from both theoretical and practical viewpoints. We argue that adding an internal mechanism of getting uncertainty values means adding irrational, conflicting and interacting agents along with their contexts.

Keywords: uncertainty theory, fuzzy logic, interacting agents, irrationality, modal logic, possible worlds.

1. Introduction

The freedom of individual agents and their groups is a source of irrationality, inconsistency, and semantic uncertainty that the fuzzy set theory, the evidence theory, the rough set and others intend to model. The agents have a freedom to select a context. A set of agents is not a set of ordinary sets, because of their self-evaluation abilities. An agent can tell: "I am a reasonable agent". Can we separate the agent as a source of the statement from the statement itself? When the statement is written then it is an independent entity and we make a link between the statement and the agent by saying that agent A made statement S. Modeling of self-evaluating sets has been a challenge in logic with several logic paradoxes discovered. Contexts often are personal for each agent and cannot be separated from the agents. In this paper we introduce a logic uncertainty theory in the context of evaluation of preferences of agents that includes a mechanism for getting initial uncertainty values as a part of the theory. This paper presents a further development of our previous works [Resconi, Jain, 2004; Kovalerchuk, 1990] that contain extensive references to related work. The fundamental analysis of relevant issues can be found in [Carnap Jeffrey, 1971; Halpern, 2005].

The paper is organized as follows: section 2 introduces agent logic evaluation in the preference system. Section 3 links it with fuzzy logic uncertainty and section 4 is devoted to links between agents modeled as worlds dealing with uncertainty. In this paper we show advantages of interpretation of fuzzy logic as an extension of the classical logic and probability theory with a mixture of rational and irrational agents. In this interpretation heuristic min max and others fuzzy logic operations can be naturally obtained and interpreted.

At first we provide a short review of the current situation in fuzzy logic that is depicted in table 1.

TABLE I.				
1. What	A simple universal way to get (1) un-			
do users	certainty values $m(a_i)$, $m(a_j)$ of entities			
want?	a_i and a_j and (2) combinations $m(a_i\&a_j)$			
	and $m(a_i v a_j)$ from $m(a_i)$ and $m(a_j)$.			
2. What	Complex dependency between a _i and a _i			
is in	and their contexts (including contra-			
reality ?	diction, irrationality and instability)			
3. What	A collection of simple heuristic opera-			
is	tions:			
offered	fered $m(a_i\&a_j) = min(w_i \cdot m(a_i), w_j \cdot m(a_j)),$			
to users?	$m(a_i\&a_j) = w_i \cdot m(a_i) \cdot w_j \cdot m(a_j)$ and other			
	t-norms;			
	$\mathbf{m}(\mathbf{a}_{i} \vee \mathbf{a}_{j}) = \mathbf{max}(\mathbf{w}_{i} \cdot \mathbf{m}(\mathbf{a}_{i}), \mathbf{w}_{j} \cdot \mathbf{m}(\mathbf{a}_{j})),$			
	$m(a_i \lor a_j) = w_i \cdot m(a_i) + w_j \cdot m(a_j)$ and other			
	t-conorms.			

The conclusion from this table is that now users have simple (not universal) operations without tools to capture complex dependencies. Obviously, this should be compensated. Engineers as users adjust weights w_i , w_j and t-norm or t-conorm. What was used to do this? It is *intuition* or available *data*. In the case of intuition, the final success should be attributed to users' engineering art rather than the tools and theory used. In the case when data are available we have now a productive neuro-fuzzy interpolation approach in fuzzy control. However, we should rather attribute the success to the fact data are available than to set of predefined fizzy logic operations. We need a theory that will go beyond current empirical way of adjusting coefficients w_i and operations by users.

This problem is not new [e.g., Elkan, 1993] and is very difficult. How to build an uncertainty theory that will be simple for use, universal enough and capture complex dependencies in the real world? We claim that there is *no shortcuts* that will allow do this. In reality this *naïve* desire of having a shortcut means passing the complexity of the real problem to the user

We claim that that a sound solution is in more complex *context-dependent operations*, that is m(a&b)can not be a function of only m(a),m(b), f(m(a),m(b) if want to deal with complexity of the real problems inside of the theory not outside of it.

The fundamental strength of the probability theory is that it does not look for shortcuts. However it does not provide a mechanism for getting initial uncertainty values inside of the theory. Our goal is to develop a logic of uncertainty that will do this inside of the theory. To do this we use concepts of irrational agents, modal logic, and contexts. We start from an example below to set up a realistic situation for further discussion.

2. Framework of Irrational Agents

Let us consider 100 agents G_i , two cars A and B and preference relation ">" between cars to be assigned by each of these agents (potential buyers). We define a Boolean variable X such that X=1 (True) if A>B else X=0 (False). Each agent G_i answered a questionnaire with two options offered: (1) A>B is true and (2) A>B is false. Say 70 agents out of 100 marked A>B is true giving a fuzzy logic membership function value m(A >B) = 70/100.

This is a classical relative frequency used in the probability theory, which normally implies the necessity of using probability theory operations that differ from fuzzy logic operations for computing uncertainty values of complex events. Thus, the question is: "Can fuzzy logic operations be justified in such situations?" We state that there is a way to do this. Implicitly we assumed that any agent that marks in the questionnaire "A > B is true" *does not mark an opposite preference* "B > A is true". This is a fundamental assumption of the probability theory – elementary events are disjoint and mutually exclusive and one of them needs to happen. (They must answer something and even nonmarking an option means something)

If an agent marks both options, his/her answers will be discarded, as non-valid and only agents with a single answer will be counted in relative frequencies. This is needed to keep fundamental additivity principle (assumption) of the probability theory at work and consequently to be able to use the probability theory operations.

Now the question is: "How often is this mutual exclusion assumption violated in modeling real world we processes?" Let us have 100 agents, 69 agents prefer A to B and only one agent out of 100 agents is irrational who marked both options. In this case for many practical tasks m(A>B)=69/100 does not differ significantly from 70/100 or 68/100 if his/her answers would be rational However, if 50 agents behave irrationally (use both alternatives) and if we discard their responses then we may get m(A>B)=(70-50)/(100-50)=0.4, which differs significantly from 0.7. The number of irrational agents is not known in advance and it makes sense to have a theory that will be able to deal with a mixture rational and irrational agents. In the case of customer preferences irrational behavior is quite common.

One of the ways to deal with such mixed situation is to modify a questionnaire (probability space) to make three alternatives: (1) "A>B is true", (2) "A>B is false", and (3) both "A>B is true and A>B is false". We will denote these alternatives $W_1 = \{T, F, T\&F\}$ that is an extension of a set of rational alternatives used the probability theory $W_0 = \{T, F\}$. The last contradictory alternative T&F is specifically designed for irrational agents. If we assume that alternatives in W₁ are mutually exclusive (each time the agent selects only one of them) then the probability theory can be applied. Thus, at first glance, we fixed a problem with a simple adjustment. However, implicitly we made an assumption that agents have a limited irrationality (we will call it **level 1 of irrationality**, L_l), that is having three alternatives T, F, T&F about preference statement, A>B, the agent will not violate mutual exclusion further. The agent will mark only one alternative out of these three alternatives and will not mark two or three of them simultaneously.

Now assume that we have all agents at the *level* L_1 with alternatives from W_1 such that $m(\mathbf{a})=0.7$ for $\mathbf{a} = A>B=$ true and $m(\mathbf{b})=0.3$ for $\mathbf{b}=(A>B=$ true) & (A>B=false). What is the value of $m(\mathbf{a} \& \mathbf{b})$? We have **b** nested in **a**, $\mathbf{a} \supset \mathbf{b}$, thus $m(\mathbf{a}\&\mathbf{b})=\mathbf{m}(\mathbf{b})=0.3$. In general terms for nested expressions we have $m(\mathbf{a} \& \mathbf{b})=\min(m(\mathbf{a}), m(\mathbf{b}))$, that is a well known fuzzy logic operation. Similarly we can justify max operation of disjunction, $m(\mathbf{a} \lor \mathbf{b}) = \max(m(\mathbf{a}), m(\mathbf{b}))$, that is 0.7 in our example.

If the agent wishes to mark, both T and T&F then this agent is more irrational than level L_1 allows. We will call such agent as an irrational agent at **level 2**, L_2 . To accommodate L_2 agents in the probability theory framework we need to expand the set of alternatives again and have $W_2=\{T, F, T\&F, T\&(T\&F)\}$ built consequently from $W_1=\{T, F, T\&F\}$ and $W_0=\{T,F\}$. Next we may get an agent at the level of irrationality L_3 that mark two alternatives from W_2 . This will force us to expand W_2 again to W_3 = {T, F, T&F, T&(T&F), T&(T&(T&F))} Next the same consideration can lead us to agents at level of irrationality L_4 and a set of alternatives W_4 . This process generating can continue indefinitely (regress to infinity) if we do not limit the level of agent's irrationality.

For highly irrational agents (large levels, L_i) the number of nested elements in W_i is large too and grows when the level of irrationality i grows. Thus, for many AND/OR expressions min max operations can be valid for such L_i and W_i , in contrast with the situation with rational agents working in W_0 .

This consideration shows the need in an uncertainty theory that will deal with such situation of mixture of rational and irrational agents as an extension of the probability theory. The additional challenge is that we may have agents with different and unknown levels of irrationality and we may not be able to limit agents' irrationality.

3. Logic of uncertainty framework

Below we outline a logic of uncertainty with contradictory agents to be able to give measures of uncertainty as an internal part of the theory.

The **Logic of Uncertainty** contains the following components that are explained below:

<{A},W, M, {Lw}, Ont_w, S(A), T(A,B), Com(A,B)>.

- {EA} is a set of *agents* <u>that</u> includes *Evaluation Agents* (EAs) that evaluate statements and *Ontology Agents* (OAs) that set up the structure and language.
- W={w} is a set of *Possible Worlds*,
- M: $\{EA\} \rightarrow \Gamma(W)$ and $\Gamma(W)$ is s set of all subsets of W.
- L_w is a *Language* that is used to describe world w.
- Ont_w is an *Ontology* of the w expressed in L_w. It includes the level of agent's *irrationality*. The ontology agent sets up M, Ont_w, and L_w.
- S(A) is a *Irrationality Statement*, S(A) =1 if the agent A is irrational and S(A)=0 if the agent is rational.
- T(A,B) is a Contradiction Relation, S(A,B)=1 if worlds of agents A and B contradict to each others.
- Com(A,B) is a Communication Relation, Com(A,B)=1 if agents A and B communicate and A can change m(A, V) because A knows m(B,V), where m(A, V) and m(B, V) are truth values assigned by agents A and B to statement V in their worlds w_A and w_B.

The accessibility relation in modal logic influenced introduction of this relation.

The agent A is an entity whose internal knowledge and belief is the set W_A of worlds, (possible worlds) mapped to it by M: $M(A)=W_A$.

Each worlds W consist of statements in language L_w . (each world can be viewed as a model [Mal'cev, 1973], where the agent can assign only crisp values (true/false) to statements.

The contradiction between agents means that there exists a statement V in w_A and w_B such that V true in W_A and false in W_B . Thus, each agent can view another agent as is *irrational* if they communicate.

In the next section we present a mechanism to compute uncertainty values of statements in the preference system in line with this framework.

4. Logic of uncertainty in preference system

For a given set of products the preferences of agents (evaluators, customers) are given as a preference graph [Ishizu, Gehrmann, 2002]. Product G1 is connected by an arrow to another product G2 when the agent prefers G1 to G2. If an agent cannot compare them then there is no arrow between G1 and G2. Say, Car A is a sports car, car B is a family car, and car C is a car for transporting goods. The agent C1 may have a transitive preference graph shown in Fig. 1 for the attribute "fuel efficiency". A coincidence matrix shown in TABLE 2 represents this graph, where 1 (true) indicates that the agent prefers product X to product Y. The value 0 (false) means that agent prefers product Y to product X.



Fig. 1. Preference graph when the evaluator C_1 uses the attribute "fuel efficiency".

TABLE 2 AGENT'<u>S "FUEL EFFICIENCY" PREFERENC</u>E TABLE

	А	В	С
Α	1	0	1
В	1	1	1
С	0	0	1

The absence of the value in the table means the agent (1) did not evaluate preference yet, or (2) cannot evaluate the preference. In the first case for the rational agent the transitive closure of the preference relation can be obtained by reasoning (If B>A & A>C then B>C), where ">" denotes the preference relation. In the second case both preference relation A>C and C>A are false.

Different evaluators may have different graphs. Now we can introduce a *fuse operator*

$$\mu(X,Y) = \frac{C_1(X,Y) + C_2(X,Y) + \dots + C_N(X,Y)}{N}$$
(1)

where a pair of variables (X, Y) denotes two products X and Y connected by an arrow in the graph and $C_k(X, Y)$ is the evaluation value (0 or 1) for the agent C_k when the agent compares the product X with the product Y. For example, for car A and car B, and the attribute "car fuel efficiency" we may have

$$\mu(A,B) = \frac{C_1(A,B) + C_2(A,B) + \dots + C_N(A,B)}{N} = \frac{M}{N}$$
(2)

where $M \le N$ is the number of agents that prefer A to B and N is a total number of agents. Note that the fuse operator is not commutative. Now given two attributes p_1 ="car fuel efficiency" and p_2 ="car inner space" we can compose the $\mu(A,B)_{p_1 \land p_2}$, for two cars A and B:

$$\mu(A,B)_{p_1 \wedge p_2} = \frac{1}{N} \sum_{i=1}^{N} (C_i(A,B)_{p_1} \wedge C_i(A,B)_{p_2}) \quad (3)$$

Similarly we can define $\mu(A,B)_{p1Ap2A...Apk}$. This membership function indicates how consistent the preferences of all agents about cars A and B relative to attributes $p_1, p_2,...,p_k$. It is assumed here that "and" operator is defined is a standard way, $1 \land 0=0$, $1 \land 1=1$, and $0 \land 0=0$.

When the preference graph is a non-transitive graph or a graph with cycles, we have an irrational agent (with irrational preferences). A preference graph for a rational agent should be transitive: if for the agent car C is better than B and B is better than A then C should be better then A. But in Fig. 1 there is an arrow for which A is better than C. This generates a contradiction with respect to rational deduction that C is better than A. More formally, in a graph shown in we have P(C, B)=1 Figure 2(b), (true), P(B,A)=1(true), but non of relations P(A,C) and P(C,A) is true, P(A,C)=0 (false) and P(C,A)=0 (false), because the agent refused to compare A and C. Thus, \neg P(A,C)=1 and \neg P(C,A)=1. On the other hand a rational agent should assume transitivity of the preference relation. Thus this agent should be able to infer that P(C,A) is true, P(C,A)=1 and respectively, $\neg P(A,C)=0$. Combining properties P(C,A)=1 and $\neg P(C,A)=1$ we get a *logical contradiction* that is *true*,

$$P(C, A) \land \neg P(C, A) = True.$$
 (4)

Similarly combining P(A,C)=0 and $\neg P(A,C)$ we get a *false tautology*

$$P(A,C) \lor \neg P(A,C) = False$$
 (5)



Fig 2. Cycle graph (a). Non-transitive evaluation graph (b)

Figure 2 (b) shows that there is no direct comparison between A and C. How to explain this? One option is that the agent is irrational, i.e., in spite of normative transitivity the agent does not accept it. Another option is that the agent simply was not asked and if asked would agree with transitivity and change preferences accordingly.

To model irrational agents we propose a new logic uncertainty where contradiction can be true and tautology false for some statements of such irrational agents.

5. Operations with uncertainties

Let $E(X)=(X_1,X_2,...,X_p)$ and $E(Y)=(Y_1,Y_2,...,Y_p)$ be vectors of binary evaluations (true/false) of attributes X and Y by p agents. Given these X and Y we have the composition rule

$$\begin{aligned} & (X_1, .., X_p) \land (Y_1, ..., Y_p) = (Y_1 \land X_1, ..., Y_p \land X_p) \\ & (X_1, ..., X_p) \lor (Y_1, ..., Y_p) = (Y_1 \lor X_1, ..., Y_p \lor X_p) \end{aligned} \tag{6} \\ & \neg (X_1, ..., X_p) = (\neg X_1, ..., \neg X_p) \end{aligned}$$

We define the AND fuse operator of evaluations X_i of p agents of the attribute X and Y as

$$\mu(X) = \frac{m_1(X_1) + \dots + m_p(X_p)}{m_1 + m_2 + \dots + m_p}$$

$$\mu(Y) = \frac{m_1(Y_1) + \dots + m_p(Y_p)}{m_1 + m_2 + \dots + m_p}$$

$$\mu(YX) = \frac{m_1(Y_1X_1) + \dots + m_p(Y_pX_p)}{m_1 + m_2 + \dots + m_p}$$
(7)

where μ is the membership function, and m_1, \ldots, m_p are the importance (weights) of agents. When the agents are equal in importance we have the traditional fuse operator. The OR fuse operator is defined similarly by using $\mu(X \vee Y)$ instead of $\mu(XY)$ in Eq.(7) with the definition of $X \vee Y$ fro vectors from Eq. (6).

The new **negation** introduces an irrational term S_k that is responsible of the difference between the classical logic and logic of uncertainty. In fact we assume that

$$\begin{split} & (\overline{X}) = (X_1, X_2, ..., X_p) = \\ & (\overline{X_1} \oplus S_1), \overline{X_2} \oplus S_2,, \overline{X_p} \oplus S_p) \end{split}$$

where \oplus is the XOR operation. In this case we have

The new negation is the extension of the negation operation in the classical logic and can be used to give models for negation in the fuzzy logic.

6. Logic of uncertainty for interdependent worlds

In the classical Kolmogorov's definition of the probability [Shafer, Vovk, 2001; Halpern, 2005] it is assumed that the worlds are *independent* and *are not connected* with others. The introduction of *relations between worlds (agents)* via a communication relation Com (accessible relation R) can change the Kolmogorov's axioms as follows:

- 1) F is a *field* of sets. This means that if F contains E and G then F contains their intersection, union, and difference.
- 2) F contains the set Ω (sample space Ω or universal set). Together with axiom 1, this says that F is an algebra of sets. When F is closed under countable infinite intersection and union it is called a σ algebra.
- 3) Another set $W = \{w_i\}$ is given. Each element of W is called a *world*. Every element Ob_i of Ω is associated with one and only one world wi in W and with an accessible relation R in Ω . If $R(Ob_i, Ob_i) = T$ then element Ob_i can "access" element Ob_i, that is it can get information about element Ob_i. Having each Ob_i associated with some world w_i, it is possible to say that world w_i can "access" world w_i, that is it can get information about world w_i. In the simplest case Ob_i can be the same as w_i. Elements Ob_i also sometimes called objects or elementary events. Similarly set E of elementary events Ob_i is called a set of events. The predicate Q_i(Ob_i) is defined for each elementary event Ob_i . If $Q_i(Ob_i)$ =True then we say that event Ob_i is true (takes place). In essence, predicate Qi defines the concepts elementary events. The predicate Qi creates a structure of events. More generally, a set of predicates Qi and axioms that set up relations between these predicates provide a structure for the set of the worlds. An Ontology Agent (OA) can set up this structure

and language L and *evaluation agents* (EAs) can evaluate if $Q_j(Ob_i)$ is true or not for a world w_i that is associated with Ob_i .

- A non-negative real number P(E) is assigned to each set E in F. This number P(E) is called the *probability of the event (set) E*. Note: traditionally P(E) reflects the number of elementary events in E relative to total number of events in Ω [14].
- 5) P(Ω) = 1. This axiom reflects the intuitive idea that number of elementary events in Ω relative to itself is 1.
- 6) If E and G are disjoint ($E \cap G = \emptyset$) then P($E \cup G$) = P(E)+P(G).
- 7) Two non-negative real numbers P₁(E) and P₂(E) are assigned to each set E in F such that P₁(E) ≤ P(E) ≤ P₂(E), where P₁(E) is the *relative number* of worlds in E that are at least necessary true for one element in E, P₂(E) is the relative number of worlds that are at least possibly true for one element in E. Thus, P₁(E) and P₂(E) are lower and upper limits of probability p(E), also [P₁(E), P₂(E)] is an interval probability.
- The measure m(E) is the relative number of worlds that are possible true for all the elements in E and not possible true for other elements of F.

7. Conclusion

Fuzzy logic, probability theory, and other uncertainty theories compute uncertainties of complex events that follow a structure imposed by their axioms. These theories have no an internal mechanism for getting initial uncertainty values. We had shown how this mechanism can be built by incorporating irrational, conflicting and interacting agents and worlds. This approach can be applied to many tasks beyond the customer preference system we used for illustration.

References

- Carnap R., Jeffrey R, Studies in Inductive Logics and Probability, vol. 1, 35-165 Berkeley, CA, University of California Press, 1971.
- [2] Elkan,C., The paradoxical success of fuzzy logic. In proceeding of the National Conference on Artificial Intelligence, pp. 698-703, Washington D.C. August 1993
- [3] Halpern, J. Reasoning about uncertainty, MIT, 2005
- [4] Kovalerchuk B., Analysis of Ganes' logic of uncertainty, In Proceeding of NAFIPS '90 vol.2 edited by I.B. Turksen, Toronto Canada pp.293-295, 1990.
- [5] Malcev A.I. Algebraic Systems, Springer, 1973.
- [6] Resconi, G., Jain, L. Intelligent agents, Springer Verlag, 2004.
- [7] Ishizu S., Gehrmann, A., Attributes Structure of Complex Systems Evaluation, Proc of 2002 Conf. of Manufacturing Complexity Network, pp. 323-338, 2002.
- [8] Shafer, G., Vovk, V. Probability and Finance It's Only a Game!, Wiley Series in Probability and Statistics, 2001