

About Extension of Differential Realization of the Countable Beam of Nonlinear Processes Input-Output in a Hilbert Space

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Abstract—The study of algebraic extension of a countable family of controlled nonlinear dynamic processes having differential realization in the class of ordinary quasi-linear differential equations (with software-positional control and without) in a separable Hilbert space was conducted.

Keywords—nonlinear processes “input-output”, nonlinear differential realization, nonstationary $(A, B, B^\#)_2$ -model.

Further $(X, \|\cdot\|_X)$, $(Y, \|\cdot\|_Y)$, $(Z, \|\cdot\|_Z)$ – real separable Hilbert spaces (pre-Hilbert [1, p. 64] define norms $\|\cdot\|_X, \|\cdot\|_Y, \|\cdot\|_Z$), $U := X \times Y \times Z$ – Hilbert space with the norm $\|(x, y, z)\|_U := (\|x\|_X^2 + \|y\|_Y^2 + \|z\|_Z^2)^{1/2}$, $L(Y, X)$ – Banach space with the operator norm $\|\cdot\|_{L(Y, X)}$ of all linear continuous operators from the space Y to X (similar $(L(X, X), \|\cdot\|_{L(X, X)})$ and $(L(Z, X), \|\cdot\|_{L(Z, X)})$), $T := [t_0, t_1]$ – segment of the real line R with the Lebesgue measure μ and \wp_μ – σ -algebra of all μ -measurable subsets of the interval T . If below $(B, \|\cdot\|)$ – some Banach space, then as usual through $L_2(T, \mu, B)$ we will denote Banach quotient space of classes μ -equivalence of all integrable maps $f: T \rightarrow B$ of Bochner [1, p. 132] with the norm $(\int_T \|f(\tau)\|^2 \mu(d\tau))^{1/2}$. In addition everywhere further $AC(T, X)$ – linear set of all absolutely continuous on T functions (with respect to μ measure) with values in the space X , moreover $\Pi := AC(T, X) \times L_2(T, \mu, Y) \times L_2(T, \mu, Z)$.

Now we will distinguish for consideration controlled differential models of the form

$$dx(t)/dt = Ax(t) + Bu(t) + B^\# u^\#(x(t)), \quad (1)$$

where $(x, u, u^\#(x)) \in \Pi$, x – Carathéodory solution (C -solution), u and $u^\#(x)$ – software and positional control, $(A, B, B^\#) \in L_2(T, \mu, L(X, X)) \times L_2(T, \mu, L(Y, X)) \times L_2(T, \mu, L(Z, X))$; in purposes of terminological convenience triple of vector-functions $(x, u, u^\#(x))$ we will also call C -solution of equation (1) and triple of operator-functions $(A, B, B^\#)$, adhering the terminology from [2, 3] we will call $(A, B, B^\#)_2$ -model of differential system (1).

The task of elementary (singleton) extension of differential realization of the beam of dynamic processes: for a given (possibly nonlinear) law $x \mapsto u^\#(x)$: $AC(T, X) \rightarrow L_2(T, \mu, Z)$ and fixed families N, N^* of processes “input-output” such that $N, N^* \subset \{(x, u, q) \in \Pi: (x, u, q) = (x, u, u^\#(x))\}$, $1 \leq \text{Card } N \leq \aleph_0$ (aleph-zero), $\text{Card } N^* = 1, N^* \not\subset$

N , where N, N^* have differential realizations (1) to determine analytical conditions under which $N \cup N^*$ – family of C -solutions of some equation (1).

We endow the space $H_2 := L_2(T, \mu, X) \times L_2(T, \mu, Y) \times L_2(T, \mu, Z)$ with the topology of the norm

$$(\int_T \|(g(\tau), w(\tau), q(\tau))\|_\mu^2 \mu(d\tau))^{1/2}, (g, w, q) \in H_2;$$

H_2 – Hilbert space [1, p. 39]; we differ the element $(x, u, u^\#(x)) \in \Pi$ in the notations as class of equivalence (i.e. element H_2) from the specific representative (vector-function) $(x(\cdot), u(\cdot), u^\#(x(\cdot)))$ from this class.

We will denote through G_E arbitrary (but fixed and numbered) algebraic basis in $E := \text{Span } N$ and let $\{(x^*, u^*, u^\#(x^*))\} := N^*$, while $(x^*, u^*, u^\#(x^*)) \notin E$. It is obvious that at any point $t \in T$ expansion in the Hilbert space of U vector $(x^*(t), u^*(t), u^\#(x^*(t)))$ is possible on the projection in $\text{Span} \{(x(t), u(t), u^\#(x(t)))\}_i: (x, u, u^\#(x))_i \in G_E, i=1, 2, \dots\}$, which is denoted by $(x^*_-(t), u^*_-(t), u^\#_-(x^*_-(t)))$ and addition $(x^*_\perp(t), u^*_\perp(t), u^\#_\perp(x^*_\perp(t))) := (x^*(t), u^*(t), u^\#(x^*(t))) - (x^*_-(t), u^*_-(t), u^\#_-(x^*_-(t)))$.

Lemma 1. Vector-functions

$$t \rightarrow (x^*_-(t), u^*_-(t), u^\#_-(x^*_-(t))) : T \rightarrow U,$$

$$t \rightarrow (x^*_\perp(t), u^*_\perp(t), u^\#_\perp(x^*_\perp(t))) : T \rightarrow U$$

μ -measurable.

(By the separability of U weak and strong measurabilities coincide [1, p. 130]). \square

Lemma 2. Representation

$(x^*, u^*, u^\#(x^*)) = (x^*_-, u^*_-, u^\#_-(x^*_-)) + (x^*_\perp, u^*_\perp, u^\#_\perp(x^*_\perp))$ doesn't depend on the choice of algebraic basis G_E , while

$$(x^*_-, u^*_-, u^\#_-(x^*_-)), (x^*_\perp, u^*_\perp, u^\#_\perp(x^*_\perp)) \in H_2. \square$$

We denote through Ω_E and Ω^*_\perp circuits in the space H_2 respectively to linear manifolds $\text{Span}\{\chi: (x, u, u^\#(x)): \chi \in F, (x, u, u^\#(x)) \in E\}$ and $\text{Span}\{\chi: (x^*_\perp, u^*_\perp, u^\#_\perp(x^*_\perp)): \chi \in F\}$, where $F \subset L(T, \mu, R)$ – family of equivalence classes (mod μ) of all characteristic functions induced by elements of σ -algebra \wp_μ .

Lemma 3. Subspaces Ω_E, Ω^*_\perp are orthogonal, i.e. $\Omega_E \perp \Omega^*_\perp$. \square

Remark 1. Everywhere further for two closed subspaces from the space H_2 , such that their intersection is $\{0\} \subset H_2$, and the vector sum is closed in H_2 we agree to denote the

sign of their vector addition through \oplus , in particular, Theorem 14.C [4, p. 28] and Lemma 3 make note $\Omega_E \oplus \Omega_{\perp}^*$ correctly.

We ask the question: what are the analytical conditions imposed on the sets of controlled dynamic processes N and $\{(x^*, u^*, u^{\#}(x^*))\}$, “extended” family of processes $N \cup \{(x^*, u^*, u^{\#}(x^*))\}$ has a differential realization (1)? On one of the ways of geometric solution of this problem is construction of characteristic feature (see below Theorem 1) defining equality

$$\Omega_E + \Omega^* = \Omega_E \oplus \Omega_{\perp}^*, \quad (2)$$

where Ω^* – closure in the space H_2 of linear manifold $\text{Span}\{\chi \cdot (x^*, u^*, u^{\#}(x^*)) : \chi \in F\}$, while a particular form of equation (2), namely, of the type

$$\Omega_E \oplus \Omega^* = \Omega_E \oplus \Omega_{\perp}^*, \quad (3)$$

positively responds to the aforesaid issue about the realization of the expanded beam $N \cup \{(x^*, u^*, u^{\#}(x^*))\}$ in the context of approach to geometric solution of the task of expansion of differential realization based on the Theorem 14.C [4, p. 28] and theorem (3) [3] below Theorem 2 detects one characteristic property of equality (3).

Further $T_0 := \{t \in T : (x^*_{\perp}(t), u^*_{\perp}(t), u^{\#}_{\perp}(x^*(t))) = 0\}$, v^*_{\perp}, v^* – Lebesgue replenishments of measures

$$\int_S \|(x^*_{\perp}(\tau), u^*_{\perp}(\tau), u^{\#}_{\perp}(x^*(\tau)))\|_U^2 \mu(d\tau), S \in \wp_{\mu},$$

$$\int_S \|(x^*(\tau), u^*(\tau), u^{\#}(x^*(\tau)))\|_U^2 \mu(d\tau), S \in \wp_{\mu}.$$

Theorem 1. $\Omega_E + \Omega^* = \Omega_E \oplus \Omega_{\perp}^*$ only if

$$L_2(T, v^*_{\perp}, R) = \chi_{\perp} \cdot L_2(T, v^*, R),$$

where χ_{\perp} – characteristic function of the set $T \setminus T_0$.

Proof of Theorem 1 we reduce to the establishment of Lemmas 4 and 5.

Lemma 4. $\Omega_E + \Omega^* \subset \Omega_E \oplus \Omega_{\perp}^*$.

Proof. Let $\omega' \in \Omega^*$, then according to Lemma 4 [3] will be

$$\begin{aligned} \omega' &= \lambda' \cdot (x^*, u^*, u^{\#}(x^*)) = \\ &= \lambda' \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*)) + \lambda' \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*)), \end{aligned}$$

where $\lambda' \in L_2(T, v^*, R)$. Further, since for each function $\lambda \in L_2(T, v^*, R)$ we have

$$\begin{aligned} \lambda^2(t) \|(x^*(t), u^*(t), u^{\#}(x^*(t)))\|_U^2 &\geq \lambda^2(t) \\ \|(x^*_{\perp}(t), u^*_{\perp}(t), u^{\#}_{\perp}(x^*(t)))\|_U^2, \end{aligned}$$

then the following embedding of functional spaces is true

$$L_2(T, v^*, R) \subset L_2(T, v^*_{\perp}, R),$$

where $\lambda' \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*)) \in \Omega_{\perp}^*$ (based on the analytical structure of the subspace Ω_{\perp}^* , given in Lemma 4 [3]). Thus, by the arbitrariness of the choice of the element $\omega' \in \Omega^*$, the lemma will be proved as soon as we discover:

$$\lambda' \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*)) \in \Omega_E.$$

For this it is sufficient to show (Corollary [1, p. 109]) that $\langle \lambda' \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*)), \omega'' \rangle_{H_2} = 0$, where $\langle \cdot, \cdot \rangle_{H_2}$ – scalar product in H_2 , for all $\omega'' \in H_2$, such that $\langle \omega'', \omega \rangle_{H_2} = 0$, for any $\omega \in \text{Span}\{\chi \cdot (x, u, u^{\#}(x)) : \chi \in F, (x, u, u^{\#}(x)) \in E\}$, which is equivalent to install:

$\omega''(t) \perp \text{Span}\{(x(t), u(t), u^{\#}(x(t))) : (x, u, u^{\#}(x)) \in G_E, i=1, 2, \dots\}$ μ -almost everywhere in T , here \perp – relation of orthogonality in the structure of space U .

We expand vector-function $\omega''(\cdot)$ in each point $t \in T$ in the sum of

$$\omega''_{-}(t) + \omega''_{+}(t) := \omega''(t),$$

where $\omega''_{-}(t) \in \text{Span}\{(x(t), u(t), u^{\#}(x(t))) : (x, u, u^{\#}(x)) \in G_E, i=1, 2, \dots\}$ and $\omega''_{+}(t)$ – is orthogonal to $\text{Span}\{(x(t), u(t), u^{\#}(x(t))) : (x, u, u^{\#}(x)) \in G_E, i=1, 2, \dots\}$. Then if $\omega''_{-} \neq 0$, there exists such set $S^* \in \wp_{\mu}$, $\mu(S^*) > 0$, that $\omega''_{-}(t) \neq 0$, $\forall t \in S^*$, while in the basis G_E there is such vector $(x, u, u^{\#}(x))_i$, that is $(x(t), u(t), u^{\#}(x(t)))_i \neq 0$ μ -almost everywhere in S^* ; otherwise for μ -almost all $t \in S^*$ equalities will be “realized”

$$\text{Span}\{(x(t), u(t), u^{\#}(x(t))) : (x, u, u^{\#}(x)) \in G_E, i=1, 2, \dots\} = \{0\},$$

and therefore $\omega''_{-} = 0$ should be performed in this position.

Now we denote through S^*_+ and S^*_- subsets (partition) S^* equal

$$S^*_+ = \{t \in S^* : \langle \omega''_{-}(t), (x(t), u(t), u^{\#}(x(t))) \rangle_U \geq 0\},$$

$$S^*_- = \{t \in S^* : \langle \omega''_{-}(t), (x(t), u(t), u^{\#}(x(t))) \rangle_U < 0\}.$$

It is obvious that at least one of the sets S^*_+ or S^*_- has a nonzero measure. Let S^*_+ acts as such set. Then $\chi_{+} \cdot (x, u, u^{\#}(x))_i \in \text{Span}\{\chi \cdot (x, u, u^{\#}(x)) : \chi \in F, (x, u, u^{\#}(x)) \in E\}$ and $\langle \omega''_{-}, \chi_{+} \cdot (x, u, u^{\#}(x)) \rangle_{H_2} > 0$, where χ_{+} – characteristic function of a set S^*_+ . It is clear that we obtain $\langle \omega'', \chi_{+} \cdot (x, u, u^{\#}(x)) \rangle_{H_2} > 0$ whereby we arrive at a contradiction with the conditions defined above the construction of the functional ω'' . \square

The above proof provides a useful clarification:

Corollary 1. $L_2(T, v^*, R) \subset L_2(T, v^*_{\perp}, R)$. \square

Lemma 5. $\Omega_E + \Omega^* \supset \Omega_E \oplus \Omega_{\perp}^* \Leftrightarrow L_2(T, v^*_{\perp}, R) = \chi_{\perp} \cdot L_2(T, v^*, R)$.

Proof. (\Rightarrow). Let $\lambda_{\omega} \in L_2(T, v^*_{\perp}, R)$ and $\omega := \lambda_{\omega} \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*))$, where (Lemma 4 [3]) $\omega \in \Omega_E \oplus \Omega_{\perp}^*$, means (assumption \Rightarrow) $\omega \in \Omega_E + \Omega^*$. Then by $\omega \in \Omega_E \oplus \Omega_{\perp}^*$ vector ω has an expansion of (unique) form $\omega = \omega' + \lambda_{\omega} \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*))$, where $\omega' = 0 \in \Omega_E$, at this effect $\omega \in \Omega_E + \Omega^*$ representation is true:

$$\begin{aligned} \omega &= \omega'' + \lambda' \cdot (x^*, u^*, u^{\#}(x^*)) = \\ &= \omega'' + \lambda' \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*)) + \lambda' \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*)), \end{aligned}$$

where $\omega'' \in \Omega_E$, $\lambda' \in L_2(T, v^*, R)$. Since (reasonings are similar to the proof of Lemma 4 [3]) the inclusions take place $\lambda' \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*)) \in \Omega_E$, $\lambda' \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*)) \in \Omega_{\perp}^*$, then $\omega' = \omega'' + \lambda' \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*))$ и $\lambda_{\omega} \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*)) = \lambda' \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*))$. Thus, taking into account the presence of a linear isometry between $L_2(T, v^*_{\perp}, R)$ and Ω_{\perp}^* (Lemma 4 [3]) will be $\lambda_{\omega} = \chi_{\perp} \cdot \lambda'$, where in the end by the arbitrariness of the choice of function λ_{ω} , we obtain $L_2(T, v^*_{\perp}, R) \subset \chi_{\perp} \cdot L_2(T, v^*, R)$ or taking into account Corollary 1 $L_2(T, v^*_{\perp}, R) = \chi_{\perp} \cdot L_2(T, v^*, R)$.

(\Leftarrow). Let $\omega \in \Omega_E \oplus \Omega_{\perp}^*$. Then $\omega = \omega' + \lambda_{\omega} \cdot (x^*_{\perp}, u^*_{\perp}, u^{\#}_{\perp}(x^*))$, where $\omega' \in \Omega_E$, $\lambda_{\omega} \in L_2(T, v^*_{\perp}, R)$. Since (assumption \Leftarrow) $\lambda_{\omega} \in \chi_{\perp} \cdot L_2(T, v^*, R)$, then we have a bunch of equalities

$$\begin{aligned} \omega' + \lambda_{\omega} \cdot (x_{\perp}^*, u_{\perp}^*, u_{\perp}^{\#}(x^*)) &= \omega' + \lambda_{\omega} \cdot (x_{\perp}^*, u_{\perp}^*, u_{\perp}^{\#}(x^*)) + \\ &+ \lambda_{\omega} \cdot (x_{\perp}^*, u_{\perp}^*, u_{\perp}^{\#}(x^*)) - \lambda_{\omega} \cdot (x_{\perp}^*, u_{\perp}^*, u_{\perp}^{\#}(x^*)) = \\ &= \omega' - \lambda_{\omega} \cdot (x_{\perp}^*, u_{\perp}^*, u_{\perp}^{\#}(x^*)) + \lambda_{\omega} \cdot (x_{\perp}^*, u_{\perp}^*, u_{\perp}^{\#}(x^*)), \end{aligned}$$

therefore, $\omega \in \Omega_E + \Omega^*$ taking into account $(\omega' - \lambda_{\omega} \cdot (x_{\perp}^*, u_{\perp}^*, u_{\perp}^{\#}(x^*))) \in \Omega_E, \lambda_{\omega} \cdot (x_{\perp}^*, u_{\perp}^*, u_{\perp}^{\#}(x^*)) \in \Omega^*$. \square

Now we present a variant of characteristic conditions of equality (3).

Theorem 2. *If we implement $T_0 = \emptyset \pmod{\mu}$ offer is valid:*

$$\Omega_E \oplus \Omega^* = \Omega_E \oplus \Omega_{\perp}^* \Leftrightarrow L_2(T, v_{\perp}^*, R) = L_2(T, v^*, R).$$

Proof. That is $\Omega_E + \Omega^* = \Omega_E \oplus \Omega_{\perp}^* \Leftrightarrow L_2(T, v_{\perp}^*, R) = L_2(T, v^*, R)$ – a direct statement of Theorem 1. On the other hand, confirmation of equality $\Omega_E \cap \Omega^* = \{0\} \subset H_2$ follows from the assumption $\{t \in T: (x_{\perp}^*(t), u_{\perp}^*(t), u_{\perp}^{\#}(x^*(t))) = 0\} = \emptyset \pmod{\mu}$ and Corollary of Mazur's Theorem [1, p. 109]. \square

Theorem 1 (given the finding of Lemma 5) and Theorem 2 attracting Theorem 14.C [4, p. 28] and Theorem 3 [3] do a fair conclusion:

Corollary 2. *The following three properties are equivalent:*

$$\begin{aligned} L_2(T, v_{\perp}^*, R) \subset \chi_{\perp} L_2(T, v^*, R) &\Leftrightarrow \\ \Leftrightarrow L_2(T, v_{\perp}^*, R) = \chi_{\perp} L_2(T, v^*, R) &\Leftrightarrow \\ \Leftrightarrow \Omega_E \oplus \Omega_{\perp}^* = \Omega_E + \Omega^*, & \end{aligned}$$

and if $T_0 = \emptyset \pmod{\mu}$, then any signified property turns the beam $N \cup \{(x^*, u^*, u^{\#}(x^*))\}$ into the set of dynamic processes with the differential realization (1). \square

Remark 2. Corollary 2 allows to call Theorem 2 as “direct theorem” about elementary algebraic extension of differential realization while hypothesis: $T_0 = \emptyset \pmod{\mu}$, $N \cup \{(x^*, u^*, u^{\#}(x^*))\}$ has a realization (1) $\Rightarrow L_2(T, v_{\perp}^*, R) \subset L_2(T, v^*, R)$ in general case isn't confirmed that the following example illustrates.

Example 1. Let $X = Y = R, T = [-1, 1], u^{\#}(\cdot) = 0$ and

$$N = \{t \rightarrow (e^t, 0, 0): t \in T\},$$

$$\{(x^*, u^*, u^{\#}(x^*))\} = \{t \rightarrow (e^t + t^2/2, t, 0): t \in T\};$$

it is obvious that $T_0 = \emptyset \pmod{\mu}$ and the beam $N \cup \{(x^*, u^*, u^{\#}(x^*))\}$ has a realization (1); we note that $T_0 \neq \emptyset$. Then $L_2(T, v^*, R) = L_2(T, \mu, R)$ and $L_2(T, v_{\perp}^*, R), v_{\perp}^* = \int \tau^2 \mu(d\tau)$, because $(x_{\perp}^*(t), u_{\perp}^*(t), u_{\perp}^{\#}(x^*(t))) = (0, t, 0)$. It is clear that $1/t \in L_2(T, v_{\perp}^*, R), 1/t \notin L_2(T, \mu, R)$, where $L_2(T, v_{\perp}^*, R) \not\subset L_2(T, v^*, R)$; hence by Lemma 5 we also conclude that $\Omega_E \oplus \Omega_{\perp}^* \not\subset \Omega_E + \Omega^*$.

Next statement shows that the construction similar to Example 1 can't be realized in the functional class $AC(T, X) \times \{0\} \times \{0\} \subset \Pi$, i.e. for free trajectories (C -solutions) it can be said that for $N \subset AC(T, X) \times \{0\} \times \{0\}$ Corollary 3 in a known sense is opposite to Corollary 2 (see above Remark 2).

Corollary 3. *If $N \subset AC(T, X) \times \{0\} \times \{0\}, \text{Card } N < \infty$ and $N \cup \{(x^*, 0, 0)\}$ – set of trajectories with the realization (1) with $u = 0, u^{\#} = 0$, then the following relations are true:*

$$\begin{aligned} T_0 &= \emptyset, \\ L_2(T, v_{\perp}^*, R) &= L_2(T, v^*, R), \end{aligned}$$

$$\Omega_E \oplus \Omega^* = \Omega_E \oplus \Omega_{\perp}^*.$$

Proof. It is easy to see that $T_0 = \emptyset$, because otherwise there exists a period of time $t^* \in T$, which $x^*(t^*) = \Sigma \alpha_i x_{(i)}(t^*)$, where all constants α_i , except the finite number are zero, $x_{(i)}$ – the first component of the triple $(x, 0, 0)_i \in G_E$. Consequently, the trajectory $x^*(\cdot)$ has a representation $\Sigma \alpha_i x_{(i)}(\cdot)$ by the uniqueness of solution, extending at time t^* through the point $x^*(t^*)$, for the differential system (1) with $(A, 0, 0)_2$ -model, corresponding to a set of dynamic processes $N \cup \{(x^*, 0, 0)\}$; that is contrary to its earlier condition $(x^*, 0, 0) \notin E$.

Further, because of the continuity of the trajectory $x^*(\cdot)$ and the compactness of the interval T , there exist such real constants $c_1, c_2 > 0$, that equalities are true

$$\inf \{\|x^*(t)\|_X: t \in T\} = c_1, \quad \sup \{\|x^*(t)\|_X: t \in T\} = c_2,$$

similarly (including $T_0 = \emptyset, \text{Card } N < \infty$), for some $c_3, c_4 > 0$ will be

$$\inf \{\|x_{\perp}^*(t)\|_X: t \in T\} = c_3, \quad \sup \{\|x_{\perp}^*(t)\|_X: t \in T\} = c_4.$$

Consequently, the classes of real-valued functions summable with square on T on measures $v_{\perp}^* = \int \|x^*(\tau)\|_X^2 \mu(d\tau)$ and $v^* = \int \|x_{\perp}^*(\tau)\|_X^2 \mu(d\tau)$, or in other words $L_2(T, v^*, R) = L_2(T, v_{\perp}^*, R)$, and hence (see Theorem 2) $\Omega_E \oplus \Omega^* = \Omega_E \oplus \Omega_{\perp}^*$. \square

If we look at Theorem 2 under foreshortening of unmanaged trajectories of a differential system (1), we can see that the analyst of output condition $L_2(T, v^*, R) = L_2(T, v_{\perp}^*, R)$ in the proof of Corollary 3 enables us to strengthen this theorem to the characteristic feature of elementary algebraic extension of differential realization of a finite beam of unmanaged implementation processes $N \subset AC(T, X) \times \{0\} \times \{0\}$.

Theorem 3. *In the family of free K -solutions the problem of singleton expansion of differential realization of the finite beam of trajectories is solvable if and only if $T_0 = \emptyset$.*

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