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REVIEW

Optimality, cost minimization and the design of arterial networks



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Abstract The arterial circulation acts as a network to deliver nutrients and oxygen to cells. The design of the cardiovascular system is subject to a variety of constraints and costs. It has been postulated that the design of the arterial network might be understood in terms of the need to minimize competing 'costs' within the context of physical or material limits to the system. These designs can also be envisaged as being subservient to space filling or fractal considerations. The signalling mechanisms underlying these designs remain to be fully characterized although shear stress, wall tensile stress and metabolic stimuli are likely candidates. I will also review evidence that deviations from a minimal cost condition or optimal design may provide both a measure of disease severity and insights into the underlying disease mechanism.

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Introduction

In branching cones the living web expands^a

Lymphatic ducts, and convoluted glands;

Aortal tubes propel the nascent blood,

And lengthening veins absorb the reflux flood;

The aim of this paper is to review ideas regarding the design of arterial networks in relation to optimal design and cost minimization. I will also discuss some evidence that disease is associated with deviations from an 'optimal' design. I will

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^a From *The Temple of Nature: Or the Origin of Society: A Poem with Philosophical Notes* (1803) by Erasmus Darwin. (Darwin's notes) In *branching cones*, l. 259. The whole branch of an artery or vein may be considered as a cone, though each distinct division of it is a cylinder. It is probable that the amount of the areas of all the small branches from one trunk may equal that of the trunk, otherwise the velocity of the blood would be greater in some parts than in others, which probably only exists when a part is compressed or inflamed.

not review the genetic, epigenetic, or signalling mechanisms putatively involved in establishing and maintaining optimal design or issues related to optimal coupling of the heart and vascular system. For these topics readers are referred to other articles.^{1–6}

Design of arterial networks

The idea that morphology and function are causally inter-related can be traced back at least to Hellenistic philosophy^{7,8}; however attempts to make quantitative links between morphological design and function based on mechanistic arguments or analysis emerged in the Enlightenment, following the work of Galileo, Borelli, Newton and Harvey.⁹

In 1515 Leonardo da Vinci described tree boughs as preserving cross-sectional area at branches^b, but as far as I know the first attempt to quantify relationships between blood vessels at bifurcations in an arterial network was made by James Keill in 1708. Keill made anatomical measurements of arteries from dog, calf and man with the aim of calculating ‘*the Quantity of Blood in the Humane Body*’. He found that the ratio of vessel cross-sectional areas at a bifurcation was typically 41616:52126^c (i.e. 1: 1.25) and used this ratio in combination with geometric scaling laws to give crude estimates of total blood volume and blood flow velocity in capillaries. Woldenberg¹⁰ has provided a detailed critical description of Keill’s work on the arterial network, and his relationship to the English ‘iatromechanists’,^d and to other scientists, such as Hales and Young. Young refers to Keill’s data in his 1808 Croonian Lecture¹¹ where he assumes a consistent increase in area of 1:1.26 at each arterial bifurcation. Young makes no comment on the possible significance of this relationship (1:2^{1/3}), although it seems unlikely that it could have escaped his notice.¹² Roux, in his doctoral thesis later in the 19th century, undertook a detailed study of the relationships between diameters and the angles subtended by arteries at bifurcations.¹³ He concluded that ‘*the shape and direction of the lumen of the blood vessels at their branch points is mainly determined by the action of hydrodynamic forces*’. Roux is probably best known the founder of the *Entwicklungsmechanik*^e, a ‘Kantian Mechanist’ programme for embryology and development.¹⁴ Roux envisaged that

development was shaped by the interaction between forces and ‘Darwinian’ selection *within* an organism operating at a cellular level.¹⁵ Roux’s views were very influential in the late 19th and early 20th century and contributed to a greater integration of physics and mathematics into biological analysis.¹⁶ In 1901 Richard Thoma¹⁷ proposed that the size of arteries depended on the velocity of blood flow in the vessel. He proposed that the diameters between parent and offspring branches conformed to an exponential relationship

$$r_0^x = r_1^x + r_2^x$$

where r_0 , r_1 and r_2 are the radii of the parent, and offspring branches at a bifurcation and x is the branching exponent (also termed the bifurcation or junction exponent). Based on measurements in chick embryo and human aorta he suggested that x fell between 2.5 and 3, with values being closer to $x = 3$ in early embryonic life. In 1903 Hess¹⁸ extended Roux’s work on branching and suggested that a typical branching angle of around 70° could be explained by minimization of energy losses; stating that ‘*the most favourable branch angle is the angle whose cosine is equal to the ratio of the energy loss the blood undergoes in the parent vessel compared to a branch of the same length*’. Thompson¹⁹ referred to both Roux’s and Hess’ work and reproduced Hess’ diagrams and calculations in the first edition of his classic work ‘*On Growth and Form*’ published in 1917. Ultimately the most influential studies of this era were those of Murray who published three articles^{20–22} that are now widely viewed as the seminal early works on optimality principles in vascular design and gave rise to the eponymous ‘Murray’s Law’.

In the first pair of papers^{20,21} Murray aimed to find physical laws that described the organization of the vascular system in relation to oxygen transport and exchange at the capillary level. He envisaged this as ‘*a problem of maxima and minima*’ and employed the idea of two competing economic factors: the cost of blood flow (i.e. power^f expended) and the cost of the blood volume. Using an assumption of Poiseuille flow and that the cost of the blood volume per unit length was proportional to the area of the vessel, Murray calculated that for maximal efficiency (in terms of blood flow and volume) blood flow should be proportional to the cube of the radius of the vessel, r , hence for a bifurcating network minimization of cost would be achieved if

$$r_0^3 = r_1^3 + r_2^3$$

where 0, 1 and 2 denote parent and offspring branches respectively. Murray demonstrates that this gives reasonably plausible estimates of blood flow in small blood vessels; however he notes that this simple model does not hold for the aorta and ascribes this to the pulsatile nature of flow in this artery. In a third paper²² Murray extended his analysis to look at the angles subtended by branches with respect to the axis of the parent. Using the optimality arguments developed in his earlier paper he calculated that

^b “Every year when the boughs of a tree have made an end of maturing their growth, they will have made, when put together, a thickness equal to that of the main stem.” Leonardo da Vinci (1515).

^c Keill is vague on units but Woldenberg (Woldenberg MJ. James Keill (1708) and the morphometry of the microcosm. Geometric progression laws in arterial trees. In: Stoddart DR, ed. *Process and form in geomorphology*. London; New York: Routledge; 1997) suggests that these are square inches.

^d For further information on the iatromechanists in 17th century see Brown, T. M (1970). *The College of Physicians and the acceptance of iatromechanism in England, 1665-1695* Bulletin of the History of Medicine, 44(1), 12–30.

^e Literally translated as ‘Developmental Mechanics’; however Roux had a more causal perspective than this translation might imply.

^f Murray terms this factor work, but as Zamir (Zamir M. Optimality principles in arterial branching. *J Theor Biol.* 1976; 62:227–251) points out he is really describing power.

the optimal angle subtended by the major and minor branches should (θ_1 and θ_2 respectively)

$$\cos \theta_n = \frac{r_0^4 + r_i^4 - (r_0^3 - r_i^3)^{\frac{4}{3}}}{2r_0^2 r_i^2}$$

or for the combination of these angles ($\theta_1 + \theta_2$) – the branching angle

$$\cos(\theta_1 + \theta_2) = \frac{(r_1^3 + r_2^3)^{\frac{4}{3}} - r_1^4 - r_2^4}{2r_1^2 r_2^2}$$

Murray commented that Hess had neglected the conditions in the other branch (or continuing segment of the parent artery) on his analysis and that his conclusion was therefore incorrect.

Another comprehensive treatment based on the minimum energy principle was undertaken by Cohn^{23,24} in 1954. Cohn argued that four factors should be optimised: 1) the size of the aorta; 2) capillary dimensions and the volume of tissue supplied by a capillary; 3) the connecting system between the aorta and the capillaries, and 4) the total resistance of the system to flow. The size of the aorta was considered to be constrained by the need to avoid turbulence; the capillary dimensions and capillary density were determined by diffusional considerations and the size of the erythrocyte; while the connecting network was considered to be constructed to optimise space filling while minimising resistance. For simplicity, Cohn assumed that branches were symmetrical and minimized resistance on the basis of Poiseuille flow. He also assumed that the mass of the blood vessel wall was determined by Laplace's relationship for wall tension. Cohn then derived an 'optimal' relationship of

$$r_i = 2^{-\frac{1}{3}} r_1$$

where r_i is the radius of the i^{th} offspring of the parent vessel with radius, r_0 . This result is the same as Murray's when applied to symmetrical bifurcations (Cohn appears to have been unaware of Murray's papers). Cohn also used a space-filling argument to model the length of the offspring vessels which he predicted should conform to the relationship

$$l_i = l_0 / 2^{\frac{1}{3}}$$

where l_i is the length of the i^{th} offspring of the parent vessel with length, l_1 . Cohn compared his predictions with measurements of the aortic radius, the ratio of parent to offspring diameter, total blood flow and number of generations of branches in dog and found reasonable agreement.

Taylor²⁵ developed Cohn's arguments and applied them to pulsatile flow in elastic arteries in a rarely cited⁸ but interesting paper. Taylor accepted the assumptions of minimum energy expenditure in terms of blood flow and blood volume but also argued that it would too costly in terms of cardiac work to allow the small arterial terminations to be impedance matched to the proximal conducting elastic arteries; hence reflections were inevitable.

Essentially this constraint appears to be an extension of the minimum volume argument, although Taylor does not make it explicit. Taylor further assumed that optimality considerations required global impedance (the complex ratio of pressure to flow rate) to be stable over a range of frequencies and minimized. He drew two interesting and important conclusions from his analysis: 1) that if the distance to the "average reflecting site" of the scattered terminations were greater than the quarter wavelength of the fundamental harmonic then out of phase reflections from terminations would tend to cancel out and 2) if the wave speed of the network increased progressively outward along the paths connecting the heart to the terminations this would tend to 'uncouple' the termination and minimise the impact of reflections. Taylor concluded that the branched anatomical design of the arterial network allowed the heart to 'see' the proximal distensible region while keeping the overall compliance of the system low and minimizing the influence of reflections on the heart. Although not couched in these terms Taylor described a system that from the heart's perspective looks like a 'Windkessel' despite the presence of reflected waves. More recently Parker et al.²⁶ have used an analogous power minimization argument to propose that reservoir pressure, which roughly equates to Windkessel pressure, represents a minimum power condition for the circulation and that the difference between total and reservoir pressure (excess pressure) might be used as an indicator of non-optimal circulatory performance. Consistent with this suggestion excess pressure has been reported to predict cardiovascular events independent of conventional risk factors.²⁷

Zamir²⁸ recognised that the optimality approaches outlined above lacked any plausible mechanism by which global optimality could be implemented. In other words how could a single bifurcation sense what was going on in billions of other bifurcations or the total volume of blood in the system? Zamir²⁹ noted that under conditions of Poiseuille flow the shear stress, τ , was given by

$$\tau = \frac{4\eta Q}{\pi r^3}$$

where η is viscosity and Q is flow rate; hence there would be constant shear stress throughout a bifurcating network conforming to Murray's law. Given the known sensitivity of endothelial cells to shear stress and other work suggesting that shear stress influenced vascular calibre,³⁰ Zamir therefore proposed that shear stress acting on endothelial cells might prove to be the major mechanism maintaining blood vessel diameter around the Murray optimum. In other papers,^{28,31} Zamir described a range of possible optimality principles for arterial bifurcations (minimal lumen surface area, minimal volume, minimal power and minimal drag) in terms of the angle subtended by both branches (the branching angle) and the ratio of parent to offspring areas (β) and showed that if they conformed with Murray's law, surface area, volume, pumping power and the drag force would all be close to their respective minima if the bifurcation angle was within the range 75–100°. Uylings³² extended previous work to accommodate all types of steady flow including completely turbulent flow, non-cylindrical vessels and asymmetrical branches and

⁸ Taylor's paper has been cited twice since its publication in 1967 according to Scopus (accessed 10/09/2014).

employed a general flow relation that minimized power losses:

$$Q = kr^{j-2}$$

where $j = 4.0$ for laminar flow, $j = 5.0$ for turbulent flow and k is a constant. On this basis he calculated that the optimal branching exponents would range from 2.33 to 3.0 for completely turbulent to laminar flow respectively. He also calculated that the optimal junction exponents would range between the limits of 2 (unbranched vessel) to 3 (symmetrically branched vessel) with increasing branching symmetry assuming laminar flow. Roy and Woldenberg³³ and proposed a generalized model of optimal branching geometry that allowed relationships between angles and branching asymmetry to be determined for a range of junction exponents. This permitted the application of the approach to a wide range of biological and non-biological branching structures.

In 1981 Sherman¹² published an influential review that summarized much of the work up to that time and examined the extent to which Murray's law fitted experimental data. He concluded that the fit was good, although not perfect, and he made some important points: 1) Murray's law might apply to inanimate systems if a trade-off between power and volume were made at some point during construction or development; 2) Murray's law would only apply to systems where flow conductance was proportional to r^4 (i.e. Poiseuille flow); 3) changes in diameter would have to be coordinated across a large region in response to dynamic change.

Subsequent authors addressed the impact of turbulence³⁴ and viscosity across the network^{34,35}. Several studies looked at the predicted costs associated with deviation from optimality.^{34,36–38} These studies showed relatively shallow cost functions for small deviations from optimal which became much steeper with large deviations. In general the observed deviations seen in experimental data incurred costs that were small (<10%). Taken together these studies and others (reviewed in³⁹) provided fairly substantial broad support for Murray's law in a range of fluid conducting systems where Poiseuille flow was present and these data were consistent with a role for shear stress in maintaining this relationship.

West et al.⁴⁰ dealt with large arteries in an important but controversial^{41–43} paper on allometric scaling. They proposed that the branch exponent for large elastic arteries with pulsatile flow should be 2 (area preserving) and that there should be a rather abrupt 'step-like' transition to the area-increasing (shear-preserving) relationship predicted by Murray in smaller arteries. It was assumed that branching followed a fractal-like space filling paradigm (see below) and that capillaries were size-invariant units. Womersley's linearized solution to the Navier–Stokes equations was used with the assumption of a thin wall and incompressible fluid. Under these assumptions the impedance, Z is given by

$$Z \approx \frac{c_0^2 \rho}{\pi r^2 c}$$

where c_0 is the Moens-Korteweg wave speed, ρ is density and

$$\left(\frac{c}{c_0}\right)^2 \approx \frac{J_2(j^{3/2}\alpha)}{J_0(j^{3/2}\alpha)}$$

where J_n denotes the Bessel function of order n , and α is a dimensionless parameter known as the Womersley number. This model agrees better with experimental data,⁴⁴ although some of the assumptions and its implications for allometric scaling have been criticised.^{41,42,45,46} Savage et al.,⁴⁶ while critical of the West model in some respects, used a broadly similar approach to estimate that the transition from $x = 2$ to $x = 3$ might be expected to occur over arteries with diameters between 1 cm and 0.1 cm. Huo and Kassab^{47,48} formulated a scaling law for vascular trees that related cumulative vessel volume, length and diameter in arterial trees. This approach built on the approach used by West et al. but derived volume–diameter and flow–length scaling laws from conservation of mass without invoking the more controversial space-filling assumptions. Huo and Kassab considered the arterial tree as composed of multiple stem-crown units (Fig. 1) and excluded capillaries since they were not considered tree-like structures.⁴⁹ They derived volume–diameter, flow–length, diameter–length, flow–diameter and flow–volume scaling laws and showed good agreement with experimental data.⁴⁸ The estimated branching exponent varied with vessel size, being on average ~ 3 in small arteries and arterioles, ~ 2.3 in large arteries and ~ 2.6 averaged over all trees studied.⁴⁸

Mechanisms of optimality

Sherman¹² had considered that coordination of network behaviour would be difficult to achieve following dynamic

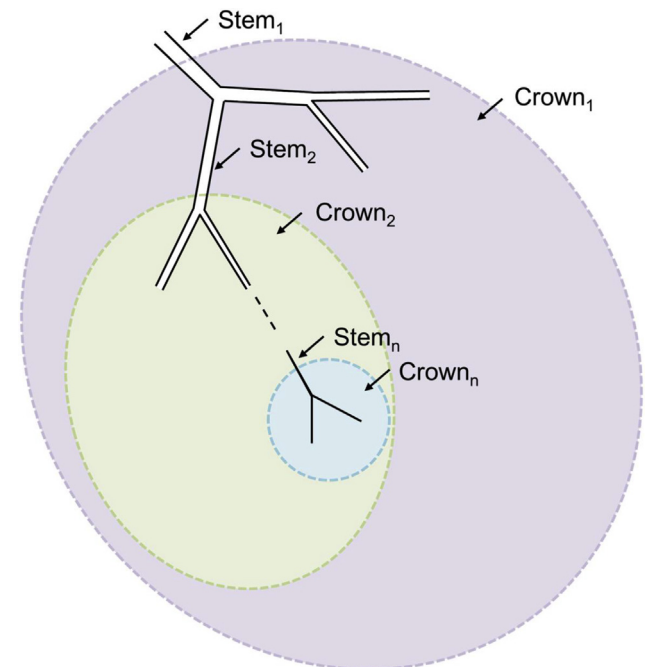


Figure 1 Illustration of the 'Stem and Crown' model of Huo and Kassab.^{47,48} Different crowns are shown in different colours. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

change in a network of arteries. Griffith and colleagues^{50,51} however provided experimental evidence of a mechanism that could account for this. They used perfused rabbit ears with five generations of branches (G0 to G4) visualised by microangiography. They showed that flow-dependent release of endothelium derived relaxing factor (EDRF; probably nitric oxide (NO) in this experimental system) maintained diameters of different generations of resistance arteries close to Murray's predicted optimum, either under resting conditions with myogenic tone, or following vasoconstriction with serotonin.^{50,51} When EDRF was inhibited with haemoglobin, branching exponents deviated markedly from 3 with the average junction exponent being ~ 6 in the presence of serotonin. Similar findings were made in the human retina under resting conditions *in vivo* when NO synthase was inhibited by NG-monomethyl-L-arginine (L-NMMA).⁵² These experimental findings are consistent with Zamir's original proposal that shear stress is a key influence on arterial network design, at least in arteries that experience Poiseuille flow. However the idea that microvascular networks could be understood *solely* in terms of a feedback-model mediated by endothelial shear stress has been criticised by several authors and they emphasize that other factors influence arterial structure (e.g. pressure, oxygen tension, and metabolic factors).^{53–55} Several models incorporating the effects of pressure, smooth muscle tone, non-Newtonian rheology and metabolism have been formulated.^{56–59} Pries and Secomb recently proposed a sophisticated model to describe microvascular remodelling.⁶⁰ They did not discount an important role for shear stress and the endothelium in the coordination and design of arterial networks but their model also incorporated the effects of circumferential wall stress, metabolic factors and conducted responses as important influences in network design and remodelling (Fig. 2).

The mechanisms that might account for the closer adherence of large elastic arteries to an area-preserving branch exponent ($x \sim 2$) are less well understood. However, one might speculate that limited access of NO and

other endothelium-derived mediators into the arterial wall,⁶¹ wall circumferential stress⁶² and/or the effects of flow separation and complex flow⁶³ could be important factors.

Fractals

Fractals were first applied to arterial design in the 1980's. At first sight fractal analysis appears to differ from cost-effectiveness analysis, although in fact the two can be linked through scaling considerations.^{40,64} The term fractal was coined by Mandelbrot to describe self-similar structures with a fractional (non-unity) dimension and devoted some discussion to vascular networks in his classic book, 'The Fractal Geometry of Nature'.⁶⁵ Vascular networks are not strictly fractal as they do not exhibit scale invariance over an infinite range of scales,⁶⁶ but they show sufficient self-similarity to be treated as fractal or pseudo-fractal. The fractal dimension (Hausdorff-Besicovitch dimension) is widely used as a measure of statistical self-similarity across scaling levels and can be viewed as a measure of the effectiveness of space filling. Thus for a two-dimensional branching network (e.g. the retinal vasculature) the upper limit of the fractal dimension should be the topological dimension (i.e. 2 since a flat surface is 2 dimensional) – the closer the fractal dimension is to 2 the better the space filling. Typically the fractal dimension of healthy 2-dimensional (or 3 dimensional vascular networks analysed as a 2-dimensional slice) falls within the range 1.3–2.0.⁶⁷ Fractal dimension can be viewed as complementary to older measures of vessel density⁶⁸; both approaches quantify space filling, but they do not necessarily correlate closely because differences in vessel diameter affect conventional measures of density.⁶⁹ Lacunarity is another measure that may be useful in describing fractal or quasi-fractal structures. Lacunarity quantifies the distribution of gap size, or lacunae, in the structure. Objects with similar fractal dimensions, may differ by lacunarity; however, as yet, lacunarity has seen only limited application to vascular networks.^{69–71}

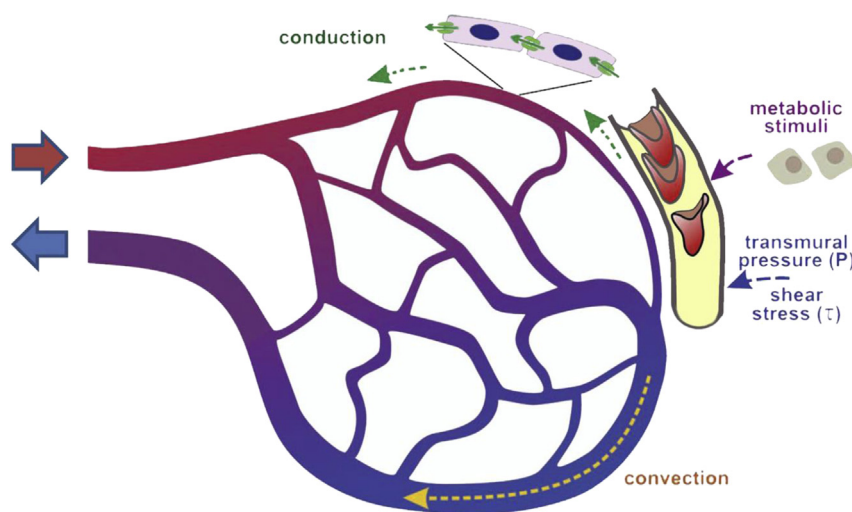


Figure 2 The model proposed by Pries and Secomb⁶⁰ illustrating various influences on microvascular remodelling (adapted from ⁶⁰).

Takahashi⁷² formulated an explicit link between the fractal dimension and Murray's law by assuming that capillaries are of uniform size and that relationship between vessel radius and length can be described by an allometric function:

$$l(r) = \beta r^\alpha$$

where the length exponent, α and the length coefficient, β are constants; this is consistent with fractal recursion, i.e. the branching structure is self-similar although scale differs.⁷³

Under these assumptions Takahashi shows that:

$$\left(\frac{r_t}{r_0}\right)^{-(D+\alpha)} = \left(\frac{r_t}{r_1}\right)^{-(D+\alpha)} + \left(\frac{r_t}{r_2}\right)^{-(D+\alpha)}$$

where r_t is the radius of the terminal vessel (or capillary) and D is the fractal dimension. So dividing throughout by r_t and taking the reciprocal

$$r_0^{(D+\alpha)} = r_1^{(D+\alpha)} + r_2^{(D+\alpha)}$$

This is similar in form to Murray's law and the branching exponent, x would be expected to be equal to $D + \alpha$. Takahashi predicted that $D + \alpha$ should be 2.88 and observed that this was consistent with literature values for the branching exponent. Morphological studies indicate that the value of α is on average close to unity (0.76–1.21) in healthy vasculature.⁷² This also provides a rationale for using length to diameter ratio as a scale-independent normalization of retinal vessel structure.⁷⁴ Fractal dimensions in the vasculatures range between 1.1 and 2.0,⁶⁷ so one would expect x to range between ~ 2 and 3 by this argument. Consistent with Takeda's suggestion lower branch exponents were associated with lower arteriolar microvascular density in the retinal arteriolar network.⁷⁵ More recently vascular networks have been treated as multifractal networks^{67,76} i.e. networks that show heterogeneity in scaling at different levels or regions of the network. Other approaches that have been applied to arterial networks include graph theory⁷⁷ and network topological measures.⁷⁸

Departures from optimal design in disease

If the normal network of small arteries is close to Murray's optimum then it seems plausible that disease may disturb that relationship. Hutchins et al. visualised *post mortem* coronary arteries using an angiographic technique.⁷⁹ They reported that in normal left main coronary arteries from 107 hearts the branching exponent was close to 3 (average $x = 3.2$) consistent with Murray's law, but declined progressively with more severe coronary artery disease with average $x = 2.2$ in 17 hearts with grade 3 or 4 atherosclerosis. However the resolution of their measurements was limited to 0.1 mm and extensive characterisation of the tree could not be achieved due to the limitations of the angiographic approach. More recent work in 253 patients undergoing coronary artery intravascular ultrasound reported that deviation from Murray's law was associated with increased coronary artery calcification.⁸⁰ In pigs Zhang and Kassab reported that hypertension and LV hypertrophy

was not associated with departure of coronary artery branching exponents from 3.⁸¹

The retinal circulation offers an excellent opportunity to assess branch exponents and microvascular architecture non-invasively in man.⁸² In a small study, Stanton et al.⁷⁵ examined retinal arterioles using fluorescein angiography and reported that branch exponents were similar for normotensives (mean $x = 2.7$) and hypertensive individuals (mean $x = 2.5$), but that increased age was associated with branch exponents < 3 . Bifurcation angles were more acute in hypertensives (74°) than in normotensives (84°) and declined with increasing age in both groups. Chapman et al. reported that the branch exponents measured from retinal arterioles in healthy men were close to optimal (mean $x = 3.1$), but were significantly reduced (mean $x = 2.6$) in men with atherosclerosis and peripheral vascular disease.⁸³ Witt et al. subsequently reported that increased deviation from an 'optimal' branch exponent of $x = 3$ was associated with increased future risk of coronary heart disease in an analysis of retinal photographs from the Beaver Dam Eye study.⁸⁴ Another study in stroke patients also found average area ratios at branches exceeded the optimal value predicted by Murray's Law and that more deviation from optimal was associated with ischaemic heart disease and increased periventricular white matter hyperintensities.⁸⁵ Patton et al. reported that non-optimal branching of retinal arteries associated with impaired general cognitive ability and verbal fluency, whereas non-optimal branching angles were associated with reduced logical memory.⁸⁶ Tillin et al. found that African-Caribbean people had less optimal retinal arteriolar branching exponents compared with Europeans⁸⁷; this was suggested to be relevant to the greater risk of stroke⁸⁸ and the more adverse cerebrovascular impact of high blood pressure⁸⁹ in this ethnic group. Greater deviation of the branch exponent (from 3) in arteries has also been reported to be associated with proliferative retinopathy⁹⁰ and peripheral neuropathy⁹¹ in adults with type 2 diabetes. Longer duration of Type 1 diabetes was also associated with an increased optimality deviation.⁹²

Non-optimal branching geometry has also been observed in relation to adverse risk factors in early life.⁸² Low birth weight, a risk factor for cardiometabolic disease in adult life was associated with increased deviation of branching exponents from optimal values in children aged 11.⁹³ Offspring of hypertensive parents (aged 9–14 y) have also been reported to have greater deviation of branch exponents from Murray's optimal value.⁹⁴

Fractal dimension has been used quite extensively to assess vascular networks in cardiometabolic and other diseases. Both reduced and increased fractal dimension has been seen in several conditions that affect the circulation (Table 1) and interpreted as indicative of a suboptimal circulatory network. Null associations have also been observed. There is some limited information regarding the relationship of fractal measures with outcomes. Low fractal dimension of the pulmonary arterial tree on CT angiography predicted poorer survival in one prospective study of people with pulmonary hypertension,⁹⁵ and low fractal dimension has also been associated with an increased risk of stroke.⁹⁶ Being in the higher or lower quarter of fractal dimension was associated with an increased risk of coronary

Table 1 Vascular fractal measures in cardiometabolic and other diseases. Abbreviations: CADASIL – Cerebral Autosomal Dominant Arteriopathy with Subcortical Infarcts and Leukoencephalopathy; CKD – chronic kidney disease; D_f – fractal dimension.

Circulation	Disease/Condition	Summary of findings	Comments	References
Retinal	Hypertension/High BP	Lower D_f	Arteries and veins not distinguished	105–110
	Ischemic stroke	Lower D_f	Both arteries and veins	111
	CADASIL	Lower D_f	Arteries and veins not distinguished	112
	Type 1 or Type 2 Diabetes	Inconsistent	Arteries and veins not distinguished	113–120
	Cognitive dysfunction	Lower D_f	Arteries and veins not distinguished	121
	Alzheimer's disease	Lower D_f	Both arteries and veins	122
	Human immunodeficiency virus (HIV) infection	D_f not different	Arteries and veins not distinguished	123
	Obesity	D_f not different	Arteries and veins not distinguished	124
	Glaucoma	Lower D_f	Arteries and veins not distinguished	125
	Renal dysfunction/CKD	Lower D_f		126,127
Renal	Congenitally abnormal kidneys	Lower D_f	Only 2 abnormal kidneys examined	128
Pulmonary	Pulmonary Hypertension	Inconsistent		129–131

heart disease mortality.⁹⁷ Greater retinal fractal dimension was independently associated with early retinopathy in a study of young people (aged 12–20 y) with type 1 diabetes,⁹⁸ but fractal dimension was not reported to be associated with incident retinopathy in another study of children and adolescents with type 1 diabetes.⁹⁹ In older adults with type 1 diabetes a lower retinal fractal dimension was associated with complications, including proliferative retinopathy, neuropathy and older age, but not macrovascular disease.^{100,101}

Conclusions

Application of a cost minimization approach has proved useful in the analysis of arterial networks, although it is not without limitations and a number of issues remain unresolved. Although progress has been made we need to know more about the stimuli which shape the network, how their effects are mediated, and to what extent they synergise. There is some evidence that shear stress and pressure interact,⁵⁵ and a range of interactions between diverse stimuli might permit a degree of 'weighting' or contextualization. For instance, it has been argued the circulation might be designed to attain highest efficiency during exercise,^{44,102} and by implication that it is slightly suboptimal under resting conditions – effectively allowing a reserve capacity. This is consistent with some evidence, at least in terms of minimization of wave reflection.¹⁰³ If this were true, the system would need to optimize its design in response to an intermittent physiological state, albeit one that may be critical for survival. How is this intermittent state sensed? One possibility might be that shear stress could have more effect on remodelling in the context of the stimuli that accompany exercise.

Finally, is optimal design desirable? It has recently been proposed (for the bronchial tree) that an optimal network is dangerous because of its vulnerability to imperfections or vessel constriction and that a 'safety margin' is required in design.¹⁰⁴ This seems difficult to reconcile with the comparative cost-insensitivity of arterial networks to small

deviations from optimum, but it does raise important questions about the appropriateness of optimality as an overriding factor in circulatory design – perhaps Murray's law should be viewed as 'more what you'd call guidelines than actual rules.'^h

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Conflicts of interest

None.

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^h Line from *Pirates of the Caribbean: The Curse of the Black Pearl* (2003).

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