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\section*{Free-field realizations of the \(W_{\mathcal{A}_{n, N}}\)-algebra}

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\title{
Free-field realizations of the \(W_{\mathscr{A}_{n}, N}\)-algebra
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}

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\[
\begin{aligned}
& \text { In this paper, we will construct free-field realizations of the } \mathrm{W}_{\mathscr{A}_{n}, N} \text { algebra associated to an } \mathscr{A}_{n} \text {-valued differ- } \\
& \text { ential operator } \\
& \qquad \mathscr{L}=\mathrm{I}_{n} \partial^{N}+U_{N-1} \partial^{N-1}+U_{N-2} \partial^{N-2}+\cdots U_{0}
\end{aligned}
\]
where \(\mathscr{A}_{n}\) is a Frobenius algebra with the uint \(\mathrm{I}_{n}\).
Keywords: \(\mathrm{W}_{\mathscr{A}_{n}, N}\) algebra; free-field realization.
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\section*{1. Introduction}

The source of the concept of W-algebras is the conformal field theory (CFT briefly) [2, 11, 23]. The main problem of the CFT is a description of fields having conformal symmetries. Only in the two-dimensional case is the group of conformal diffeomorphisms rich enough to build a meaningful theory on this base. All diffeomorphisms of a circle represent the core of the theory. Its related Lie algebra is a centerless Virasoro algebra, whose extension is the well-known Virasoro algebra. In the study of Virasoro algebra, there were various representations in terms of free fields, based on bosons, fermions and ghosts. In particular, the free-boson representation, including vertex operators, proved to be useful for particular calculations, especially for the evaluation of correlation functions.

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The CFT requires the extension of the Virasoro algebra as far as possible. The work by Zamolodchikov pioneered the concept of CFT. He gave an extension of the Virasoro algebra called the \(\mathrm{W}_{3}\) algebra. In that terminology, the Virasoro algebra was \(W_{2}\). At the end of the 1980 's, it was found that the mathematical framework for further extension of Virasoro algebra already existed as the theory of integrable systems. In other words, the classical realization of the W-algebra [23] appears naturally as the second Poisson bracket of KdV-type hierarchies. For example, the Virasoro algebra \(\mathrm{W}_{2}\) is realized as the Magri bracket for the KdV hierarchy [12,18], and the Zamolodchikov-FateevLukyanov \(\mathrm{W}_{m}\)-algebra as the second Adler-Gelfand-Dickey (AGD briefly) bracket for the \(m^{\text {th }}\)-order Gelfand-Dickey \(\left(\mathrm{GD}_{m}\right)\) hierarchy \([1,10,17,19]\). Free-field relations of W -algebras have also been obtained by constructing the related Miura maps, please see e.g. [7-9,14] and references therein for details.

In [5], A. Bilal proposed a non-local matrix generalization of the well-known \(\mathrm{W}_{m}\)-algebra, called the \(\mathrm{V}_{n, m}\)-algebra, by constructing the second AGD bracket associated with a matrix differential operator of order \(m\)
\[
\begin{aligned}
\mathfrak{L} & =-\mathrm{I}_{n} \partial^{m}+U_{1} \partial^{m-1}+U_{2} \partial^{m-2}+\cdots+U_{m} \\
& =-\left(\mathrm{I}_{n} \partial-P_{1}\right) \cdots\left(\mathrm{I}_{n} \partial-P_{m}\right), \quad \partial=\frac{\partial}{\partial x}, \quad P_{j}, \quad U_{j} \in \operatorname{gl}(n, \mathbb{C}),
\end{aligned}
\]
where \(\mathrm{I}_{n}\) is the \(n^{\text {th }}\)-order identity matrix. Upon reducing to \(U_{1}=0\), the non-commutativity of matrices implies the presence of non-local terms in the \(\mathrm{V}_{n, m}\)-algebra. A Miura transformation relates these Poisson brackets of the \(U_{j}\) to much simpler ones of a set of \(P_{i} \in g l(n, \mathbb{C})\), i.e., the KupershmidtWilson (KW briefly) type theorem. Contrary to the scalar case, generally \(P_{i}\) are not free fields. It is difficult to give such a free-field realization because of the non-local terms except some special cases [3,4].

Recently motivated by the work in [ \(6,13,16,25\) ], Strachan and Zuo began to study the Frobenius algebra-valued integrable systems [21,22,24,26]. In [21] they introduced an \(\mathfrak{F}\)-valued KP hierarchy associated with an \(\mathfrak{F}\)-valued pseudo-differential operator ( \(\Psi D O\) in brief)
\[
L=\mathbf{1}_{\mathfrak{F}} \partial+U_{1} \partial^{-1}+U_{2} \partial^{-2}+\cdots
\]
and constructed infinite series of bi-Hamiltonian structures, where \(\mathbf{1}_{\mathfrak{F}}\) is the unit of the Frobenius algebra \(\mathfrak{F}\). Via the properties of the second Hamiltonian structures, they have obtained a local matrix generalization of \(W\)-type algebras. Because the Frobenius algebra is commutative, upon reducing to the \(U_{1}=0\), the second Hamiltonian structure is still local, which gives a chance to construct free-field realizations.

The aim of this paper is to construct free-field realizations of the \(\mathrm{W}_{\mathscr{\mathscr { A } _ { n } , N}}\) algebra associated to a concrete \(\mathscr{A}_{n}\)-valued differential operator
\[
\mathscr{L}=\mathrm{I}_{n} \partial^{N}+U_{N-1} \partial^{N-1}+U_{N-2} \partial^{N-2}+\cdots U_{0}
\]
and organized as follows. Firstly, we recall the definition of \(\mathrm{W}_{\mathfrak{F}_{n}, N}\)-algebra and then show a KWtype theorem. Afterwards, with the help of the KW-type theorem we will construct the free-field realizations of the \(\mathrm{W}_{\mathscr{A}_{n}, N}\) algebra. Finally we give two examples to illustrate our method.

\section*{2. The \(\mathbf{W}_{\mathfrak{F}_{n}, N \text {-algebra }}\) and the \(K W\)-type theorem}

\subsection*{2.1. Local matrix generalizations of the classical W algebras}

To be self-contained, below we recall some known facts, see [21,22] for details. Let us begin with some basic definitions.

Definition 2.1. The Frobenius algebra \(\mathfrak{F}:=\left\{\mathfrak{F}, \operatorname{tr}_{\mathfrak{F}}, \mathbf{1}_{\mathfrak{F}}, \circ\right\}\) over \(\mathbb{K}\) is a free \(\mathbb{K}\)-module \(\mathfrak{F}\) of finite rank \(n\), equipped with a commutative and associative multiplication \(\circ\) and the unit \(\mathbf{1}_{\mathfrak{F}}\), and a \(\mathbb{K}\) linear form \(\operatorname{tr}_{\mathfrak{F}}: \mathfrak{F} \rightarrow \mathbb{K}\) whose kernel contains no nontrivial ideas, where \(\mathbb{K}\) is \(\mathbb{C}\) or \(\mathbb{R}\).

Let
\[
\begin{equation*}
\mathscr{L}=\mathbf{1}_{\mathfrak{F}} \partial^{N}+U_{N-1} \partial^{N-1}+U_{N-2} \partial^{N-2}+\cdots U_{0} \tag{2.1}
\end{equation*}
\]
be an \(\mathfrak{F}\)-valued differential operator of order \(N\). The \(\mathfrak{F}\)-valued Gefland-Dickey (GD in brief) hierarchy is defined as
\[
\begin{equation*}
\frac{\partial \mathscr{L}}{\partial t_{r}}=B_{r} \circ \mathscr{L}-\mathscr{L} \circ B_{r}, \quad r=1,2, \ldots \tag{2.2}
\end{equation*}
\]
where \(B_{r}=\mathscr{L}_{+}^{\frac{r}{N}}\) is the pure differential part of the operator \(L^{\frac{r}{N}}\). As discussed in [21], the \(\mathfrak{F}\)-valued GD hierarchy has bi-hamiltonian structures with the second Poisson bracket as
\[
\begin{equation*}
\{\tilde{f}, \tilde{g}\}^{(N)}=\operatorname{tr}_{\tilde{F}} \int \operatorname{res}\left(\left(\mathscr{L} \circ \frac{\delta f}{\delta \mathscr{L}}\right)_{+} \circ \mathscr{L}-\mathscr{L} \circ\left(\frac{\delta f}{\delta \mathscr{L}} \circ \mathscr{L}\right)_{+}\right) \circ \frac{\delta g}{\delta \mathscr{L}} d x \tag{2.3}
\end{equation*}
\]
where the variational derivative \({ }^{\mathrm{a}} \frac{\delta f}{\delta \mathscr{L}}\) is defined by the formula \(\frac{\delta f}{\delta \mathscr{L}}=\sum_{i=0}^{N-1} \partial^{-i-1} \frac{\delta f}{\delta U_{i}}\). Upon reducing to the \(U_{N-1}=0\), the Poisson bracket \(\{,\}^{(N)}\) is reducible if and only if
\[
\begin{equation*}
\operatorname{res}\left[\mathscr{L}, \frac{\delta f}{\delta \mathscr{L}}\right]=0 \tag{2.4}
\end{equation*}
\]

We denote the reduced bracket by \(\{,\}_{D}^{(N)}\), which provides a local matrix generalization of the classical \(W_{N}\)-algebra ([21]). We would like to call the \(\mathrm{W}_{\mathfrak{F}_{n}, N}\)-algebra. Especially when one takes \(\varphi(x)=\operatorname{tr}_{\mathfrak{F}} U_{N-2}\), with the use of (2.3) and (2.4) the reduced Poisson bracket is given by
\[
\{\varphi(x), \varphi(y)\}_{D}^{(N)}=-\left(\frac{N^{3}-N}{12} \partial^{3}+\varphi \partial+\partial \varphi\right) \delta(x-y)
\]

This means that the \(\mathrm{W}_{\mathfrak{F}_{n}, N}\)-algebra contains the Virasoro algebra as its subalgebra.
\({ }^{\text {a }}\) The variational derivative with respect to an algebra-valued field has been discussed in [20]. In the present context, let \(\tilde{f}=\int \operatorname{tr}_{\mathfrak{F}} F(V) d x\) for \(V=\sum_{q=1}^{n} v_{q} e_{q} \in \mathfrak{F}\), the variational derivative \(\frac{\delta F}{\delta V}\) is defined by
\[
\tilde{f}(v+\delta v)-\tilde{f}(v)=\int \operatorname{tr}_{\tilde{F}}\left(\frac{\delta F}{\delta V} \circ \delta V+o(\delta V)\right) d x=\int \sum_{q=1}^{n}\left(\frac{\delta f}{\delta v_{q}} \delta v_{q}+o(\delta v)\right) d x
\]
where \(f(v)=\operatorname{tr}_{\mathfrak{F}} F(V), \delta V=\sum_{q=1}^{n} \delta v_{q} e_{q} \in \mathfrak{F}, \frac{\delta f}{\delta v_{q}}=\sum_{j=0}^{\infty}(-\partial)^{j} \frac{\partial f}{\partial v_{q}^{(j)}}\) and \(\delta v\) is a small parameter. Without confusion, we use the notation \(\frac{\delta f}{\delta V}\) instead of \(\frac{\delta F}{\delta V}\).

\subsection*{2.2. Modifying the second Hamiltonian structure}

In order to construct free-field realizations of the \(\mathrm{W}_{\mathfrak{F}_{n}, N}\)-algebra, we want to study the transformation of the second Hamiltonian structure \(\{\),\(\} by the factorization\)
\[
\begin{equation*}
\mathscr{L}=\mathscr{L}_{r} \circ \mathscr{L}_{r-1} \circ \cdots \circ \mathscr{L}_{1}, \tag{2.5}
\end{equation*}
\]
where \(\mathscr{L}_{j}=\mathbf{1}_{\mathfrak{F}} \partial^{N_{j}}+V_{j, N_{j}-1} \partial^{N_{j}-1}+\cdots\) are \(\mathfrak{F}\)-valued \(\Psi\) DOs and \(\sum_{j=1}^{r} N_{r}=N\).
Theorem 2.1. Assume that the factorization (2.5) exists, then the second Poisson bracket for \(L\) is \(a\) direct sum of those for \(\mathscr{L}_{1}, \ldots, \mathscr{L}_{r}\), that is to say,
\[
\begin{equation*}
\{\tilde{f}, \tilde{g}\}^{(N)}=\sum_{j=1}^{r}\{\tilde{f}, \tilde{g}\}^{\left(N_{j}\right)} \tag{2.6}
\end{equation*}
\]

Moreover, the constraint condition \(U_{N-1}=0\) is equivalent to
\[
\begin{equation*}
\operatorname{res}\left[\mathscr{L}, \frac{\delta f}{\delta \mathscr{L}}\right]=\sum_{j=1}^{r} \operatorname{res}\left[\mathscr{L}_{j}, \frac{\delta f}{\delta \mathscr{L}_{j}}\right]=0 \tag{2.7}
\end{equation*}
\]

When \(\mathfrak{F}=\mathbb{R}\), this result is the so-called \(K W\) theorem in [15].

Proof. Observe that
\[
\begin{aligned}
\delta \tilde{f} & =\operatorname{tr}_{\tilde{F}} \int \operatorname{res} \frac{\delta f}{\delta \mathscr{L}} \circ \delta \mathscr{L} d x=\sum_{j=1}^{r} \operatorname{tr}_{\tilde{F}} \int \operatorname{res} \frac{\delta f}{\delta \mathscr{L}_{j}} \circ \delta \mathscr{L}_{j} d x \\
& =\sum_{j=1}^{r} \operatorname{tr}_{\mathfrak{F}} \int \operatorname{res} \frac{\delta f}{\delta \mathscr{L}} \circ \mathscr{L}_{r} \circ \cdots \circ \mathscr{L}_{j+1} \circ \delta \mathscr{L}_{j} \circ \mathscr{L}_{j-1} \circ \cdots \circ \mathscr{L}_{1} d x \\
& =\sum_{j=1}^{r} \operatorname{tr}_{\mathfrak{F}} \int \operatorname{res} \mathscr{L}_{j-1} \circ \cdots \circ \mathscr{L}_{1} \circ \frac{\delta f}{\delta \mathscr{L}} \circ \mathscr{L}_{r} \circ \cdots \circ \mathscr{L}_{j+1} \circ \delta \mathscr{L}_{j} d x .
\end{aligned}
\]

This expression implies
\[
\begin{equation*}
\frac{\delta f}{\delta \mathscr{L}_{j}}=\mathscr{L}_{j-1} \circ \cdots \circ \mathscr{L}_{1} \circ \frac{\delta f}{\delta \mathscr{L}} \circ \mathscr{L}_{r} \circ \cdots \circ \mathscr{L}_{j+1} \quad \bmod \quad R\left(-\infty,-m_{j}-1\right) \tag{2.8}
\end{equation*}
\]

Here \(R(-\infty,-k)\) contains all of the \(\mathfrak{F}\)-valued operators of the form \(\sum_{j=-\infty}^{-k} A_{j} \partial^{j}\). With the use of (2.8), we get
\[
\begin{equation*}
\mathscr{L}_{j} \circ \frac{\delta f}{\delta \mathscr{L}_{j}}=\frac{\delta f}{\delta \mathscr{L}_{j+1}} \circ \mathscr{L}_{j+1}=\mathscr{L}_{j} \circ \cdots \circ \mathscr{L}_{1} \circ \frac{\delta f}{\delta \mathscr{L}} \circ \mathscr{L}_{r} \circ \cdots \circ \mathscr{L}_{j+1} \quad \bmod \quad R(-\infty,-1) \tag{2.9}
\end{equation*}
\]
and
\[
\begin{equation*}
\sum_{j=1}^{r} \operatorname{res}\left[\mathscr{L}_{j}, \frac{\delta f}{\delta \mathscr{L}_{j}}\right]=\operatorname{res}\left(\mathscr{L}_{r} \circ \frac{\delta f}{\delta \mathscr{L}_{r}}-\frac{\delta f}{\delta \mathscr{L}_{1}} \circ \mathscr{L}_{1}\right)=\operatorname{res}\left[\mathscr{L}, \frac{\delta f}{\delta \mathscr{L}^{\prime}}\right] \tag{2.10}
\end{equation*}
\]

Obviously, (2.7) follows from (2.4) and (2.10). With the help of (2.9), the right side of (2.6) is
\[
\begin{aligned}
& \sum_{j=1}^{r}\{\tilde{f}, \tilde{g}\}^{\left(N_{j}\right)} \\
& =\sum_{j=1}^{r} \operatorname{tr}_{\mathfrak{F}} \int \operatorname{res}\left(\left(\mathscr{L}_{j} \circ \frac{\delta f}{\delta \mathscr{L}_{j}}\right)_{+} \circ \mathscr{L}_{j}-\mathscr{L}_{j} \circ\left(\frac{\delta f}{\delta \mathscr{L}_{j}} \circ \mathscr{L}_{j}\right)_{+}\right) \circ \frac{\delta g}{\delta \mathscr{L}_{j}} d x \\
& =\sum_{j=1}^{r} \operatorname{tr}_{\tilde{F}} \int \operatorname{res}\left(\mathscr{L}_{j} \circ\left(\frac{\delta f}{\delta \mathscr{L}_{j}} \circ \mathscr{L}_{j}\right)_{-}-\left(\mathscr{L}_{j} \circ \frac{\delta f}{\delta \mathscr{L}_{j}}\right)_{-} \circ \mathscr{L}_{j}\right) \circ \frac{\delta g}{\delta \mathscr{L}_{j}} d x \\
& =\sum_{j=1}^{r} \operatorname{tr}_{\tilde{F}} \int \operatorname{res}\left(\frac{\delta f}{\delta \mathscr{L}_{j}} \circ \mathscr{L}_{j}\right)_{-} \circ\left(\frac{\delta g}{\delta \mathscr{L}_{j}} \circ \mathscr{L}_{j}\right)_{+} d x \\
& -\sum_{j=1}^{r} \operatorname{tr}_{\mathfrak{F}} \int \operatorname{res}\left(\mathscr{L}_{j} \circ \frac{\delta f}{\delta \mathscr{L}_{j}}\right)_{-} \circ\left(\mathscr{L}_{j} \circ \frac{\delta g}{\delta \mathscr{L}_{j}}\right)_{+} d x \\
& =\sum_{j=1}^{r} \operatorname{tr}_{\mathfrak{F}} \int \operatorname{res}\left(\frac{\delta f}{\delta \mathscr{L}_{j}} \circ \mathscr{L}_{j}\right)_{-} \circ\left(\frac{\delta g}{\delta \mathscr{L}_{j}} \circ \mathscr{L}_{j}\right)_{+} d x \\
& -\sum_{j=1}^{r-1} \operatorname{tr}_{\mathfrak{F}} \int \operatorname{res}\left(\frac{\delta f}{\delta \mathscr{L}_{j+1}} \circ \mathscr{L}_{j+1}\right)_{-} \circ\left(\frac{\delta g}{\delta \mathscr{L}_{j+1}} \circ \mathscr{L}_{j+1}\right)_{+} d x \\
& -\operatorname{tr}_{\tilde{F}} \int \operatorname{res}\left(\mathscr{L}_{r} \circ \frac{\delta f}{\delta \mathscr{L}_{r}}\right)_{-} \circ\left(\mathscr{L}_{r} \circ \frac{\delta g}{\delta \mathscr{L}_{r}}\right)_{+} d x \\
& =\operatorname{tr}_{\tilde{F}} \int \operatorname{res}\left[\left(\frac{\delta f}{\delta \mathscr{L}_{1}} \circ \mathscr{L}_{1}\right)_{-} \circ\left(\frac{\delta g}{\delta \mathscr{L}_{1}} \circ \mathscr{L}_{1}\right)_{+}-\left(\mathscr{L}_{r} \circ \frac{\delta f}{\delta \mathscr{L}_{r}}\right)_{-} \circ\left(\mathscr{L}_{r} \circ \frac{\delta g}{\delta \mathscr{L}_{r}}\right)_{+}\right] d x \\
& =\{\tilde{f}, \tilde{g}\}
\end{aligned}
\]

We thus complete the proof of this theorem.
The above theorem implies that it is possible to simplify the construction of the free-field realization for the \(\mathrm{W}_{\mathfrak{V}_{n}, N \text {-algebra }}\) to the construction of the free-field realization for each copy of the \(\mathrm{W}_{\mathfrak{V}_{n}, 1}\)-algebra. Many examples suggest the existence of free-filed realizations of the above W-type algebras, but up to now we have no a unified proof for the general \(\mathrm{W}_{\tilde{Y}_{n}, N}\)-algebra. In the next section we illustrate our construction by taking a concrete algebra \(\mathscr{A}_{n}\).

\section*{3. Free-field realizations of the \(\mathbf{W}_{\mathscr{A}_{n}, N}\)-algebra}

Let us denote
\[
\mathscr{Z}_{n}=\left\{a=\sum_{k=1}^{n} a_{k} \Lambda^{k-1} \mid a_{k} \in \mathbb{C}, k=1, \ldots, n\right\},
\]
where \(\Lambda=\left(\Lambda_{i j}\right) \in g l(n, \mathbb{C})\) with the elements
\[
\Lambda_{i j}=\delta_{i, j+1}=\left\{\begin{array}{l}
1, i=j+1 \\
0, \text { other cases }
\end{array}\right.
\]
and \(\Lambda^{0}=\mathrm{I}_{n}\) is the \(n^{\text {th }}\)-order identity matrix. Observe that \(\Lambda^{n}=0\), then \(\mathscr{Z}_{n}\) is a maximal commutative subalgebra of \(g l(n, \mathbb{C})\). In [21,26], they have shown that the algebra \(\mathscr{Z}_{n}\) has at least \(n\)-"basic"
different ways to be realized as the Frobenius algebra \(\mathscr{A}_{k}:=\left\{\mathscr{Z}_{n}, \mathbf{I}_{n}, \mathrm{tr}_{\mathscr{A}_{k}}\right\}\) with the trace form defined by
\[
\begin{equation*}
\operatorname{tr}_{\mathscr{O}_{k}}(a)=a_{k}+a_{n}\left(1-\delta_{n, k}\right) \quad \text { for any } \quad a=\sum_{k=1}^{n} a_{k} \Lambda^{k-1} \in \mathscr{Z}_{n} . \tag{3.1}
\end{equation*}
\]

Without loss of generality, in this section we will take the Frobenius algebra \(\mathfrak{F}\) as \(\mathscr{A}_{n}\) and construct a free-field realization of \(\mathrm{W}_{\mathscr{A}_{n}, N}\)-algebra.

Suppose that the \(\mathscr{A}_{n}\)-valued differential operator
\[
\mathscr{L}=\mathrm{I}_{n} \partial^{N}+U_{N-1} \partial^{N-1}+U_{N-2} \partial^{N-2}+\cdots U_{0}
\]
could be represented as a product of
\[
\mathscr{L}=\mathscr{L}_{N} \circ \mathscr{L}_{N-1} \circ \cdots \circ \mathscr{L}_{1}
\]
of \(\mathscr{A}_{n}\)-valued differential operators \(\mathscr{L}_{j}=\mathrm{I}_{n} \partial+V_{j}, j=1, \ldots, N\). With the use of Theorem 2.1, we get
\[
\begin{align*}
\{\tilde{f}, \tilde{g}\}^{(N)} & =\sum_{j=1}^{N}\{\tilde{f}, \tilde{g}\}_{\mathscr{L}_{j}}^{(1)} \\
& =\sum_{j=1}^{N} \operatorname{tr}_{\tilde{F}} \int \operatorname{res}\left(\left(\mathscr{L}_{j} \circ \frac{\delta f}{\delta \mathscr{L}_{j}}\right)_{+} \circ \mathscr{L}_{j}-\mathscr{L}_{j} \circ\left(\frac{\delta f}{\delta \mathscr{L}_{j}} \circ \mathscr{L}_{j}\right)_{+}\right) \circ \frac{\delta g}{\delta \mathscr{L}_{j}} d x \\
& =\sum_{j=1}^{N} \operatorname{tr}_{\tilde{F}} \int \frac{\delta f}{\delta V_{j}} \circ \frac{\partial}{\partial x} \frac{\delta g}{\delta V_{j}} d x . \quad \text { Here using } \frac{\delta f}{\delta \mathscr{L}_{j}}=\partial^{-1} \frac{\delta f}{\delta V_{j}} . \tag{3.2}
\end{align*}
\]

More precisely,
\[
\left\{\operatorname{tr}_{\mathscr{A}_{n}} \int F V_{i} d x, \operatorname{tr}_{\mathscr{A}_{n}} \int G V_{j} d x\right\}^{(N)}=\delta_{i j} \operatorname{tr}_{\mathscr{A}_{n}} \int F \frac{\partial}{\partial x} G d x,
\]
where \(F\) and \(G\) are two \(\mathscr{\mathscr { A }}_{n}\)-valued test functions.
Next, we want to study the reduced bracket under reduction to the submanifold \(U_{N-1}=0\).
Lemma 3.1. The Poisson bracket \(\{,\}^{(N)}\) with the constraint \(U_{N-1}=0\) is reduced to
\[
\begin{equation*}
\left\{\operatorname{tr}_{\mathscr{\mathscr { A } _ { n }}} \int F V_{i} d x, \operatorname{tr}_{\mathscr{A}_{n}} \int G V_{j} d x\right\}_{D}^{(N)}=\left(\delta_{i j}-\frac{1}{N}\right) \operatorname{tr}_{\mathscr{A}_{n}} \int F \frac{\partial}{\partial x} G d x, \tag{3.3}
\end{equation*}
\]
where \(F\) and \(G\) are two \(\mathscr{A}_{n}\)-valued test functions. In particular,
\[
\begin{equation*}
\left\{V_{i, q}(x), V_{j, r}(y)\right\}_{D}^{(N)}=\left(\delta_{i j}-\frac{1}{N}\right) \delta_{q+r, n+1} \delta^{\prime}(x-y), \tag{3.4}
\end{equation*}
\]
where \(V_{i}=\sum_{q=1}^{n} V_{i, q} \Lambda^{q-1}\).
\[
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\]

Proof. Taking an overcomplete set of vectors \({ }^{\text {b }}\)
\[
\begin{equation*}
\overrightarrow{\mathbf{h}}_{j}=\left(h_{j}^{1}, \ldots, h_{j}^{N-1}\right), \quad j=1, \ldots, N \tag{3.5}
\end{equation*}
\]
in an \((N-1)\)-dimensional Euclidean space with
\[
\begin{equation*}
\sum_{j=1}^{N} \overrightarrow{\mathbf{h}}_{j}=0, \quad \sum_{j=1}^{N} h_{j}^{a} h_{j}^{b}=\delta_{a b}, \quad \sum_{a=1}^{N-1} h_{i}^{a} h_{j}^{a}=\delta_{i j}-\frac{1}{N} . \tag{3.6}
\end{equation*}
\]

Observe that \(U_{N-1}=\sum_{j=1}^{N} V_{j}\) and denoting \(\mathscr{V}_{a}=\sum_{j=1}^{N} h_{j}^{a} V_{j}, \quad a=1, \ldots, N-1\). With the help of (3.6), we have
\[
V_{j}=\frac{1}{N} U_{N-1}+\sum_{a=1}^{N-1} h_{j}^{a} \mathscr{V}_{a}, \quad j=1, \ldots, N
\]
and
\[
\begin{equation*}
\frac{\delta f}{\delta V_{j}}=\frac{\delta f}{\delta U_{N-1}}+\sum_{a=1}^{N-1} h_{j}^{a} \frac{\delta f}{\delta V_{a}}, \quad j=1, \ldots, N . \tag{3.7}
\end{equation*}
\]

So using (3.6) and (3.7), the Poisson bracket \(\{,\}^{(N)}\) in (3.2) can be rewritten as
\[
\begin{aligned}
\{\tilde{f}, \tilde{g}\}^{(N)} & =\sum_{j=1}^{N} \operatorname{tr}_{\tilde{\mathscr{F}}} \int \frac{\delta f}{\delta V_{j}} \circ \frac{\partial}{\partial x} \frac{\delta g}{\delta V_{j}} d x \\
& =N \operatorname{tr}_{\tilde{F}} \int \frac{\delta f}{\delta U_{N-1}} \circ \frac{\partial}{\partial x} \frac{\delta g}{\delta U_{N-1}} d x+\sum_{a=1}^{N-1} \operatorname{tr}_{\tilde{F}} \int \frac{\delta f}{\delta \mathscr{V}_{a}} \circ \frac{\partial}{\partial x} \frac{\delta g}{\delta V_{a}} d x .
\end{aligned}
\]

When we consider the reduction \(U_{N-1}=0\), from (2.7) we should take into account the following condition
\[
\begin{equation*}
\sum_{j=1}^{N}\left(\frac{\delta f}{\delta V_{j}}\right)_{x}=0 \tag{3.8}
\end{equation*}
\]

That is to say,
\[
0=\sum_{j=1}^{N}\left(\frac{\delta f}{\delta V_{j}}\right)_{x}=N \frac{\delta f}{\delta U_{N-1}}+\sum_{j=1}^{N} \sum_{a=1}^{N-1} h_{j}^{a} \frac{\delta f}{\delta V_{a}}=N \frac{\delta f}{\delta U_{N-1}} .
\]

Thus the reduced Poisson bracket \(\{,\}_{D}^{(N)}\) is given by
\[
\{\tilde{f}, \tilde{g}\}_{D}^{(N)}=\sum_{a=1}^{N-1} \operatorname{tr}_{\tilde{\mathcal{F}}} \int \frac{\delta f}{\delta \mathscr{V}_{a}} \circ \frac{\partial}{\partial x} \frac{\delta g}{\delta \mathscr{V}_{a}} d x
\]

\footnotetext{
\({ }^{\mathrm{b}}\) e.g., such vectors have been explicitly written in [8].
}
and for two \(\mathscr{A}_{n}\)-valued test functions \(F\) and \(G\),
\[
\begin{aligned}
\left\{\operatorname{tr}_{\mathscr{A}_{n}} \int F V_{i} d x, \operatorname{tr}_{\mathscr{A}_{n}} \int G V_{j} d x\right\}_{D}^{(N)} & =\sum_{a=1}^{N-1} h_{i}^{a} h_{j}^{a} \operatorname{tr}_{\mathscr{O}_{n}} \int F \frac{\partial}{\partial x} G d x \\
& =\left(\delta_{i j}-\frac{1}{N}\right) \operatorname{tr}_{\mathscr{A}_{n}} \int F \frac{\partial}{\partial x} G d x .
\end{aligned}
\]

The identity (3.4) follows from the formula (3.3) and the definition \(\operatorname{tr}_{\mathfrak{F}}\) in (3.1).
Let \(K=\left(K_{q r}\right)\) be an \(n \times n\) matrix with the elements \(K_{q r}=\delta_{q+r, n+1}\). Obvious the matrix \(K\) is a real symmetric matrix, thus there exists an orthogonal matrix \(Q\) such that \(K=Q \operatorname{diag}\left(\lambda_{1}, \ldots, \lambda_{n}\right) Q^{t}\), where \(\lambda_{j}\) are eigenvalues of \(K\) and \(Q^{t}\) is the transpose of \(Q\). Assume
\[
\begin{equation*}
S=\left(S_{q r}\right)=Q \operatorname{diag}\left(\sqrt{\lambda_{1}}, \ldots, \sqrt{\lambda_{n}}\right) \in g l(n, \mathbb{C}), \tag{3.9}
\end{equation*}
\]
then \(K=S S^{t}\).
Taking \((N-1) n\) free fields \(\varphi_{j, q}(x)\) with the currents \(\mathbf{j}_{i, q}(x)=\varphi_{i, q}^{\prime}(x)\) together with the Poisson bracket
\[
\begin{equation*}
\left\{\mathbf{j}_{i, q}(x), \mathbf{j}_{j, r}(y)\right\}_{D}^{(N)}=\delta_{i j} \delta_{q r} \delta^{\prime}(x-y) \tag{3.10}
\end{equation*}
\]
where \(i, j=1, \ldots, N-1\) and \(q, r=1, \ldots, n\).

Theorem 3.1. Setting
\[
\begin{equation*}
\overrightarrow{\mathbf{J}}_{k}=\left(\mathbf{J}_{1, k}, \ldots, \mathbf{J}_{N-1, k}\right), \quad \mathbf{J}_{a, k}=\sum_{\alpha=1}^{n} S_{k, \alpha} \mathbf{j}_{a, \alpha}(x), \tag{3.11}
\end{equation*}
\]
then the identification \(\mathscr{L}=\mathscr{L}_{N} \circ \mathscr{L}_{N-1} \circ \cdots \circ \mathscr{L}_{1}\) with the element
\[
\begin{equation*}
\mathscr{L}_{j}=\mathrm{I}_{n} \partial+V_{j}=\mathrm{I}_{n} \partial+\sum_{k=1}^{n}\left(\overrightarrow{\mathbf{h}}_{j} \cdot \overrightarrow{\mathbf{J}}_{k}\right) \Lambda^{k-1}, \quad j=1, \ldots, N \tag{3.12}
\end{equation*}
\]
provides a free-field realization of the \(W_{\mathscr{A}_{n}, N}\)-algebra, where \(\overrightarrow{\mathbf{h}}_{j} \cdot \overrightarrow{\mathbf{J}}_{k}:=\sum_{a=1}^{N-1} h_{j}^{a} \mathbf{J}_{a, k}\).

Proof. The constrained condition \(U_{N-1}=0\) follows from
\[
\sum_{j=1}^{N} V_{j}=\sum_{j=1}^{N} \sum_{k=1}^{n}\left(\overrightarrow{\mathbf{h}}_{j} \cdot \overrightarrow{\mathbf{J}}_{k}\right) \Lambda^{k-1}=\sum_{k=1}^{n}\left(\sum_{j=1}^{N} \overrightarrow{\mathbf{h}}_{j} \cdot \overrightarrow{\mathbf{J}}_{k}\right) \Lambda^{k-1}=0 .
\]
\[
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\]

Denoting \(V_{j}=\sum_{k=1}^{n} V_{j, k}(x) \Lambda^{k-1}\), then \(V_{j, k}(x)=\overrightarrow{\mathbf{h}}_{j} \cdot \overrightarrow{\mathbf{J}}_{k}=\sum_{a=1}^{N-1} h_{j}^{a} \mathbf{J}_{a, k}\). Now, with the help of (3.6), (3.9) and (3.10), we have
\[
\begin{aligned}
\left\{V_{i, q}(x), V_{j, r}(y)\right\}_{D}^{(N)} & =\left\{\overrightarrow{\mathbf{h}}_{i} \cdot \overrightarrow{\mathbf{J}}_{q}, \overrightarrow{\mathbf{h}}_{j} \cdot \overrightarrow{\mathbf{J}}_{r}\right\}_{D}^{(m)} \\
& =\sum_{a, b=1}^{N-1}\left\{h_{i}^{a} \mathbf{J}_{a, q}(x), h_{j}^{a} \mathbf{J}_{b, r}(x)\right\}_{D}^{(m)} \\
& =\sum_{a, b=1}^{N-1} h_{i}^{a} h_{j}^{b} \sum_{\alpha, \beta=1}^{n}\left\{S_{q, \alpha} \mathbf{j}_{a, \alpha}(x), S_{r, \beta} \mathbf{j}_{b, \beta}(x)\right\}_{D}^{(m)} \\
& =\sum_{a, b=1}^{N-1} h_{i}^{a} h_{j}^{b} \sum_{\alpha, \beta=1}^{n} S_{q, \alpha} S_{r, \beta} \delta_{a b} \delta_{\alpha \beta} \delta^{\prime}(x-y) \\
& =\sum_{a=1}^{N-1} h_{i}^{a} h_{j}^{a} \delta_{q+r, n-1} \delta^{\prime}(x-y) \\
& =\overrightarrow{\mathbf{h}}_{i} \cdot \overrightarrow{\mathbf{h}}_{j} \delta_{q+r, n-1} \delta^{\prime}(x-y) \\
& =\left(\delta_{i j}-\frac{1}{N}\right) \delta_{q+r, n-1} \delta^{\prime}(x-y),
\end{aligned}
\]
which is exactly the reduced Poisson bracket (3.4). We thereby obtain the free-field realization of the \(\mathrm{W}_{\mathscr{A}_{n}, N}\)-algebra.

\section*{4. Conclusion}

In summary, with the help of the KW-type theorem, we have constructed free-field realizations of the \(\mathrm{W}_{\mathscr{A}_{n}, N}\) algebra associated with the \(\mathscr{A}_{n}\)-valued differential operator
\[
\mathscr{L}=\mathrm{I}_{n} \partial^{N}+U_{N-1} \partial^{N-1}+U_{N-2} \partial^{N-2}+\cdots U_{0} .
\]

By analogy with the above, a minor modification will give the free-field realizations of the \(\mathrm{W}_{\mathscr{A}_{k}, N}\) algebra for \(k=1, \ldots, n-1\). But for general \(\mathrm{W}_{\mathfrak{F}, N}\) algebra, it is still open because of the uncertainty of the \(\mathbb{K}\)-linear form \(\operatorname{tr}_{\mathfrak{F}}\).

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