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New Integrable and Linearizable Nonlinear Difference Equations

R. Sahadevan and G. Nagavigneshwari

Ramanujan Institute for Advanced Study in Mathematics, University of Madras, Chennai-600 005, Tamil Nadu, India ramajayamsaha@yahoo.co.in, grgnaga@gmail.com

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A systematic investigation to derive nonlinear lattice equations governed by partial difference equations $(P\Delta\Delta E)$ admitting specific Lax representation is presented. Further it is shown that for a specific value of the parameter the derived nonlinear $P\Delta\Delta E$'s can be transformed into a linear $P\Delta\Delta E$'s under a global transformation. Also it is demonstrated how to derive higher order ordinary difference equations $(O\Delta E)$ or mappings in general and linearizable ones in particular from the obtained nonlinear $P\Delta\Delta E$'s through periodic reduction. The question of measure preserving property of the obtained $O\Delta E$'s and the construction of more than one integrals (or invariants) of them is examined wherever possible.

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1. Introduction

The study of discrete systems governed by nonlinear $P\Delta\Delta Es$ and $O\Delta Es$ has attracted researchers in nonlinear phenomena in recent years. One of the reasons for the interest to study discrete systems is that they are more fundamental than the continuous ones. Also it is of interest to understand whether or not the discrete systems derived from continuous nonlinear systems governed by ordinary or partial differential equation especially integrable ones preserve their integrability characteristics [1, 2, 5, 11, 20-26]. In the last few decades, considerable progress has been accomplished and several integrable nonlinear ordinary and partial differential equations were discretized leading to differential-difference, ordinary difference equations or mappings preserving integrability characteristics of their counterpart [7, 12, 14, 27–29, 33, 34]. Several analytical methods have also been devised to derive both mathematical and physical aspects from integrability to chaos of discrete nonlinear systems. To the best of our knowledge only a few nonlinear partial difference equations or lattice equations with two independent variables have been derived whose continuum limit can be related with known integrable partial differential equations with two independent variables including soliton possessing systems. It is appropriate to mention that the study of integrable nonlinear $P\Delta\Delta E$'s enables one to derive integrable higher dimensional nonlinear $O\Delta E$'s or integrable mappings, for example through periodic reductions [3, 8, 16, 18, 19, 21] and hence the search for integrable lattice equations involving two or more independent variables is interesting.

It is known that the concept of integrability of nonlinear difference equations is not well defined like for nonlinear differential equations however there exists some working definitions in the literature. A nonlinear $P\Delta\Delta E$ with two independent variables is said to be integrable

- (i) if it arises from the compatibility condition of a system of linear partial difference equations [1,2,18] and the underlying method is referred to as Lax pair method;
- (ii) if it possesses multi-soliton solutions [11, 13, 19];
- (iii) if it passes the ultra-local singularity confinement criterion [10, 11] and has zero algebraic entropy [6, 15];
- (iv) if it has the Consistency Around the Cube (CAC) property [4];
- (v) if it can be transformed into a linear partial difference equation through a global transformation;

We would like to mention that in definition (v), the transformation of a nonlinear differential equation means that the solutions can be expressed in terms of known functions. Hence in the discrete case also one would expect the discrete analogues of the known functions to play a crucial role. In this article a scalar nonlinear $P\Delta\Delta E$ with two independent variables having the form

$$v_{m+1}^{l+1} = F(v_m^l, v_m^{l+1}, v_{m+1}^l), v_m^l = v(l,m)$$

is considered and derived equations admitting specific Lax representation. The identified nonlinear $P\Delta\Delta E$'s can be classified into two distinct forms namely

(i)
$$v_{m+1}^{l+1} = \frac{h_{11}(v_m^l)^3 + h_{12}(v_m^l)^2 + h_{13}v_m^l + h_{14}}{h_{15}(v_m^l)^3 + h_{16}(v_m^l)^2 + h_{17}v_m^l + h_{18}}$$
 (1.1)

and

(ii)
$$v_{m+1}^{l+1} = \frac{F_{11}(v_m^{l+1}, v_{m+1}^l) + v_m^l F_{12}(v_m^{l+1}, v_{m+1}^l)}{F_{12}(v_m^{l+1}, v_{m+1}^l) - v_m^l F_{11}(v_m^{l+1}, v_{m+1}^l)}$$
 (1.2)

where h_{1i} 's are polynomials in (v_m^{l+1}, v_{m+1}^l) and F_{11} and F_{12} are polynomials of degree (2|r|-1)and 2|r| respectively, $r \in \mathbb{Z} \setminus \{0\}$. It is shown that the latter nonlinear $P\Delta\Delta E$ with specific forms of F_{1i} i = 1, 2 can be transformed into linear $P\Delta\Delta E$ through a global transformation.

The plan of the article is as follows. Given a set of Lax pairs with rational entries having the form, $\frac{P}{Q}$ where both *P* and *Q* are polynomials in v_m^l, v_m^{l+1} and v_{m+1}^l , how to derive the associated nonlinear $P\Delta\Delta E$'s with two independent variables is presented in section 2 which results to the above equations (1.1) and (1.2). It is shown that equation (1.2) is linearizable under a global transformation ensuring its integrability. In section 3 it is demonstrated how to derive higher order $O\Delta E$'s in general and linearizable ones in particular from the obtained nonlinear $P\Delta\Delta E$'s through periodic reductions. The question of measure preserving property of the obtained $O\Delta E$'s and construction of more than one integrals of them is examined wherever possible. In section 4 a brief summary of the obtained results and concluding remarks are presented.

2. Integrable and Linearizable Nonlinear Partial Difference Equations

Consider a system of linear difference equations with two independent variables *l* and *m* given by

$$\begin{pmatrix} v_1_m^{l+1} \\ v_2_m^{l+1} \end{pmatrix} = L(l,m,k) \begin{pmatrix} v_1_m^l \\ v_2_m^l \end{pmatrix},$$
(2.1)

New Integrable and Linearizable Nonlinear Difference Equations

$$\begin{pmatrix} v_1_{m+1}^l \\ v_2_{m+1}^l \end{pmatrix} = M(l,m,k) \begin{pmatrix} v_1_m^l \\ v_2_m^l \end{pmatrix},$$
(2.2)

where L(l,m,k) and M(l,m,k) denoted by L_m^l and M_m^l are (2×2) matrices. Here v_{1m}^l and v_{2m}^l are wave functions defined at the sites of a two-dimensional lattice as functions of the spectral parameter k. Then the compatibility condition of (2.1) and (2.2) gives

$$M_m^{l+1} L_m^l = L_{m+1}^l M_m^l$$
(2.3)

which is usually referred to as Lax equation. Let us assume that the matrices L_m^l and M_m^l depend only on the potential (v_m^l, v_m^{l+1}) and (v_m^l, v_{m+1}^l) respectively. Then the Lax equation (2.3) is equivalent to a condition of the type

$$v_{m+1}^{l+1} = F(v_m^l, v_m^{l+1}, v_{m+1}^l).$$
(2.4)

Recently we considered Lax matrices with rational entries, having the form $\frac{P}{Q}$ where both *P* and *Q* are linear in v_m^l, v_m^{l+1} and v_{m+1}^l and reported several new nonlinear $P\Delta\Delta E$'s satisfying (2.3) and hence they are integrable in the sense of Lax [30]. In this article we wish to consider Lax matrices again with rational entries in which *P* and *Q* are algebraic polynomials of degree greater than one and show that there exists a class of nonlinear $P\Delta\Delta E$'s satisfying the compatibility condition (2.3).

We now consider specific Lax matrices L_m^l and M_m^l having the form

$$L_{m}^{l}(k) = \begin{pmatrix} 0 & \frac{f_{11}(v_{m}^{l}, v_{m}^{l+1})}{kf_{12}(v_{m}^{l}, v_{m}^{l+1})} \\ \frac{kf_{13}(v_{m}^{l}, v_{m}^{l+1})}{f_{14}(v_{m}^{l}, v_{m}^{l+1})} & 0 \end{pmatrix},$$
(2.5)
$$M_{m}^{l}(k) = \begin{pmatrix} 0 & \frac{g_{11}(v_{m}^{l}, v_{m+1}^{l})}{kg_{12}(v_{m}^{l}, v_{m+1}^{l})} \\ \frac{kg_{13}(v_{m}^{l}, v_{m+1}^{l})}{g_{14}(v_{m}^{l}, v_{m+1}^{l})} & 0 \end{pmatrix},$$
(2.6)

where k is the spectral parameter and f_{1i} 's and g_{1i} 's, i = 1, 2, 3 and 4 are arbitrary unknown functions. It is easy to verify that the components (1,1) and (2,2) of the compatibility condition (2.3) vanish while the components of (1,2) and (2,1) result the following respectively:

$$\frac{f_{11}(v_{m+1}^l, v_{m+1}^{l+1})f_{14}(v_m^l, v_m^{l+1})}{f_{12}(v_{m+1}^l, v_{m+1}^{l+1})f_{13}(v_m^l, v_m^{l+1})} = \frac{g_{11}(v_m^{l+1}, v_{m+1}^{l+1})g_{14}(v_m^l, v_{m+1}^l)}{g_{12}(v_m^{l+1}, v_{m+1}^{l+1})g_{13}(v_m^l, v_{m+1}^l)},$$
(2.7)

$$\frac{f_{13}(v_{m+1}^l, v_{m+1}^{l+1})f_{12}(v_m^l, v_m^{l+1})}{f_{14}(v_{m+1}^l, v_{m+1}^{l+1})f_{11}(v_m^l, v_m^{l+1})} = \frac{g_{13}(v_m^{l+1}, v_{m+1}^{l+1})g_{12}(v_m^l, v_{m+1}^l)}{g_{14}(v_m^{l+1}, v_{m+1}^{l+1})g_{11}(v_m^l, v_{m+1}^l)}.$$
(2.8)

From equations (2.7) and (2.8) it is clear that they reduce into a single equation

$$\frac{f_{11}(v_{m+1}^l, v_{m+1}^{l+1})f_{12}(v_m^l, v_m^{l+1})}{f_{12}(v_{m+1}^l, v_{m+1}^{l+1})f_{11}(v_m^l, v_m^{l+1})} = \frac{g_{11}(v_m^{l+1}, v_{m+1}^{l+1})g_{12}(v_m^l, v_{m+1}^{l})}{g_{12}(v_m^{l+1}, v_{m+1}^{l+1})g_{11}(v_m^l, v_{m+1}^{l})},$$
(2.9)

provided

 $\begin{array}{l} f_{13}(v_m^l,v_m^{l+1}) &= f_{11}(v_m^l,v_m^{l+1}), \ f_{14}(v_m^l,v_m^{l+1}) &= f_{12}(v_m^l,v_m^{l+1}), \\ g_{13}(v_m^l,v_{m+1}^l) &= g_{11}(v_m^l,v_{m+1}^l), \ g_{14}(v_m^l,v_{m+1}^l) &= g_{12}(v_m^l,v_{m+1}^l). \end{array}$

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Equation (2.9) is a functional equation and therefore cannot be solved for v_{m+1}^{l+1} explicitly. To solve equation (2.9) for v_{m+1}^{l+1} we first consider f_{1i} 's and g_{1i} 's, i = 1, 2, are linear which leads to not so interesting cases. Next we consider both f_{1i} 's and g_{1i} 's are quadratic in $(v_m^l, v_m^{l+1}, v_{m+1}^l)$. A detailed calculation show that equation (2.9) can be solved for v_{m+1}^{l+1} , for the following forms:

 $\begin{aligned} f_{11}(v_m^l, v_m^{l+1}) &= (\alpha + v_m^l)^2, \qquad f_{12}(v_m^l, v_m^{l+1}) = (\alpha v_m^l + 1)^2 \\ g_{11}(v_m^l, v_{m+1}^l) &= (-\alpha v_m^l + 1)(\alpha - v_{m+1}^l), \\ g_{12}(v_m^l, v_{m+1}^l) &= (\alpha - v_m^l)(\alpha + v_{m+1}^l), \\ \text{where } \alpha \text{ is an arbitrary parameter and so we obtain a nonlinear } P\Delta\Delta E \text{ which can be written as a ratio of polynomials of degree three in } v_m^l \end{aligned}$

$$v_{m+1}^{l+1} = \frac{h_{11}(v_m^l)^3 + h_{12}(v_m^l)^2 + h_{13}v_m^l + h_{14}}{h_{15}(v_m^l)^3 + h_{16}(v_m^l)^2 + h_{17}v_m^l + h_{18}}$$
(2.10)

where h_{1i} 's, i = 1, ..., 8 are also polynomials in (v_m^{l+1}, v_{m+1}^l) ,

$$\begin{split} h_{11} &= \alpha [1 - \alpha^{6} + \alpha (\alpha^{4} - 1) v_{m}^{l+1} + 2\alpha v_{m+1}^{l} - 2\alpha^{2} \\ &v_{m}^{l+1} v_{m+1}^{l} + \alpha^{2} (\alpha^{2} + 1) (v_{m+1}^{l})^{2} - 2\alpha^{3} v_{m}^{l+1} (v_{m+1}^{l})^{2}], \\ h_{12} &= \alpha^{2} [(1 - \alpha^{4}) + \alpha (\alpha^{2} - 1) v_{m}^{l+1} + 2\alpha v_{m+1}^{l} - 2\alpha^{2} v_{m}^{l+1} v_{m+1}^{l} \\ &+ 2\alpha^{2} (v_{m+1}^{l})^{2} - \alpha (\alpha^{2} + 1) v_{m}^{l+1} (v_{m+1}^{l})^{2}], \\ h_{13} &= \alpha^{2} [\alpha (\alpha^{2} - 1) - 2\alpha^{2} v_{m+1}^{l} + 2\alpha^{3} v_{m}^{l+1} v_{m+1}^{l} \\ &- \alpha (\alpha^{2} + 1) (v_{m+1}^{l})^{2} + (\alpha^{4} + 1) v_{m}^{l+1} (v_{m+1}^{l})^{2}], \\ h_{14} &= \alpha [\alpha^{2} (\alpha^{2} - 1) v_{m}^{l+1} - 2\alpha^{4} v_{m+1}^{l} + 2\alpha^{5} v_{m}^{l+1} v_{m+1}^{l} \\ &- \alpha (\alpha^{4} + 1) (v_{m+1}^{l})^{2} + (\alpha^{6} + 1) v_{m}^{l+1} (v_{m+1}^{l})^{2}], \\ h_{15} &= (\alpha^{6} + 1) - \alpha (\alpha^{4} + 1) v_{m}^{l+1} + 2\alpha v_{m+1}^{l} - 2\alpha^{2} v_{m}^{l+1} v_{m+1}^{l} \\ &- \alpha^{2} (\alpha^{2} - 1) (v_{m+1}^{l})^{2}, \\ h_{16} &= \alpha [(\alpha^{4} + 1) - \alpha (\alpha^{2} + 1) v_{m}^{l+1} + 2\alpha v_{m+1}^{l} - 2\alpha^{2} v_{m}^{l+1} v_{m+1}^{l} \\ &- \alpha (\alpha^{2} - 1) (v_{m+1}^{l})^{2} + (\alpha^{4} - 1) v_{m}^{l+1} (v_{m+1}^{l})^{2}], \\ h_{17} &= \alpha [-\alpha (\alpha^{2} + 1) + 2\alpha^{2} (v_{m}^{l+1} - v_{m+1}^{l}) + 2\alpha^{3} v_{m}^{l+1} v_{m+1}^{l} \\ &- \alpha (\alpha^{2} - 1) (v_{m+1}^{l})^{2} + (\alpha^{4} - 1) v_{m}^{l+1} (v_{m+1}^{l})^{2}], \\ h_{18} &= -2\alpha^{3} + \alpha^{2} (\alpha^{2} + 1) v_{m}^{l+1} - 2\alpha^{4} v_{m+1}^{l} + 2\alpha^{5} v_{m}^{l+1} v_{m+1}^{l} \\ &- \alpha (\alpha^{4} - 1) (v_{m+1}^{l})^{2} + (\alpha^{6} - 1) v_{m}^{l+1} (v_{m+1}^{l})^{2}. \end{split} \right\}$$

Thus the equation (2.10) is integrable in the sense of Lax. It is not clear, at the moment, whether this equation possesses other characteristics of integrability such as CAC (Consistency Around the Cube) property, ultra-singularity confinement criteria, conservation laws, etc. However we wish to report that when $\alpha^2 = -1$, equation (2.10) becomes

$$v_{m+1}^{l+1} = \frac{2(i - v_{m+1}^l)((v_m^l)^2 + 1)[v_m^{l+1} - v_{m+1}^l + v_m^l(1 + v_m^{l+1}v_{m+1}^l)]}{2(i - v_{m+1}^l)((v_m^l)^2 + 1)[(1 + v_m^{l+1}v_{m+1}^l) - v_m^l(v_m^{l+1} - v_{m+1}^l)]}$$
(2.12)

which can be transformed into a linear $P\Delta\Delta E$

$$\boldsymbol{\theta}_{m+1}^{l+1} - \boldsymbol{\theta}_m^{l+1} + \boldsymbol{\theta}_{m+1}^l - \boldsymbol{\theta}_m^l = p\pi, \ \boldsymbol{\theta}_m^l = tan^{-1}(\boldsymbol{v}_m^l), \ p \in \mathbb{Z}$$
(2.13)

and thus equation (2.12) is both integrable and linearizable. Next we consider f_{1i} 's and g_{1i} 's are polynomials of degree three in their respective arguments. A detailed calculation show that equation (2.9) is solvable for v_{m+1}^{l+1} when the degree of g_{1i} is lesser by 2 than that of f_{1i} . In other words, for the following forms

$$\begin{aligned} f_{11}(v_m^l, v_m^{l+1}) &= (\alpha + v_m^l)^2 (\alpha + v_m^{l+1}), \ f_{12}(v_m^l, v_m^{l+1}) &= (\alpha v_m^l + 1)^2 (\alpha v_m^{l+1} + 1), \\ g_{11}(v_m^l, v_{m+1}^l) &= (-\alpha v_m^l + 1), \qquad g_{12}(v_m^l, v_{m+1}^l) = (\alpha - v_m^l) \end{aligned}$$

where α is an arbitrary parameter, equation (2.9) yields a nonlinear $P\Delta\Delta E$ which can be written as ratio of polynomials of degree three in v_m^l

$$v_{m+1}^{l+1} = \frac{\tilde{h}_{11}(v_m^l)^3 + \tilde{h}_{12}(v_m^l)^2 + \tilde{h}_{13}v_m^l + \tilde{h}_{14}}{\tilde{h}_{15}(v_m^l)^3 + \tilde{h}_{16}(v_m^l)^2 + \tilde{h}_{17}v_m^l + \tilde{h}_{18}}$$
(2.14)

where \tilde{h}_{1i} 's, i = 1,...8 are also polynomials in (v_m^{l+1}, v_{m+1}^l) . Since each \tilde{h}_{1i} 's involve a lengthy expression we refrain from presenting its explicit form. Thus the equation (2.14) is integrable in the sense of Lax. Here again for $\alpha^2 = -1$, equation (2.14), after eliminating common factors appeared in both numerator and the denominator, becomes a QRT type equation,

$$v_{m+1}^{l+1} = \frac{F_{11}(v_m^{l+1}, v_{m+1}^l) + v_m^l F_{12}(v_m^{l+1}, v_{m+1}^l)}{F_{12}(v_m^{l+1}, v_{m+1}^l) - v_m^l F_{11}(v_m^{l+1}, v_{m+1}^l)},$$
(2.15)

where

where $F_{11} = 2(v_m^{l+1} - v_{m+1}^l)(1 + v_m^{l+1}v_{m+1}^l),$ $F_{12} = (1 + v_m^{l+1} - v_{m+1}^l + v_m^{l+1}v_{m+1}^l)(1 - v_m^{l+1} + v_{m+1}^l + v_m^{l+1}v_{m+1}^l).$ which can also be transformed into a linear $P\Delta\Delta E$

$$\theta_{m+1}^{l+1} - 2(\theta_m^{l+1} - \theta_{m+1}^{l}) - \theta_m^{l} = p\pi, \ \theta_m^{l} = tan^{-1}(v_m^{l}), \ p \in \mathbb{Z}$$
(2.16)

and hence integrable and linearizable as well.

Next we consider f_{1i} 's and g_{1i} 's are polynomials of degree four in their respective arguments and find that the solution of (2.9), that is for v_{m+1}^{l+1} involve irrational functions and hence not pursued further. The situation remains the same when f_{1i} 's and g_{1i} 's are polynomials of degree > 4. However for the following forms of f_{1i} 's and g_{1i} 's

$$\begin{cases} f_{11}(v_m^l, v_m^{l+1}) &= (\alpha + v_m^l)^2 (\alpha + v_m^{l+1})^{r-1}, \\ f_{12}(v_m^l, v_m^{l+1}) &= (\alpha v_m^l + 1)^2 (\alpha v_m^{l+1} + 1)^{r-1}, \\ g_{11}(v_m^l, v_{m+1}^l) &= (-\alpha v_m^l + 1) (\alpha + v_{m+1}^l)^{r-2}, \\ g_{12}(v_m^l, v_{m+1}^l) &= (\alpha - v_m^l) (\alpha - v_{m+1}^l)^{r-2} \end{cases}$$

$$(2.17)$$

with $\alpha^2 = -1$, equation (2.9) leads to QRT type nonlinear $P\Delta\Delta E$ of the form

$$v_{m+1}^{l+1} = \frac{F_{11}(v_m^{l+1}, v_{m+1}^l) + v_m^l F_{12}(v_m^{l+1}, v_{m+1}^l)}{F_{12}(v_m^{l+1}, v_{m+1}^l) - v_m^l F_{11}(v_m^{l+1}, v_{m+1}^l)},$$
(2.18)

where F_{11} and F_{12} are specific polynomials of degree (2|r|-1) and 2|r| respectively and their explicit expression for different values of *r* are given in Table 1 and Table 2. Here again equation (2.18) can be transformed into a linear $P\Delta\Delta E$

$$\boldsymbol{\theta}_{m+1}^{l+1} - r(\boldsymbol{\theta}_m^{l+1} - \boldsymbol{\theta}_{m+1}^{l}) - \boldsymbol{\theta}_m^{l} = p\pi, \ \boldsymbol{\theta}_m^{l} = tan^{-1}(\boldsymbol{v}_m^{l}), \ p \in \mathbb{Z}, \ r \in \mathbb{Z} \setminus \{0\}.$$
(2.19)

Hence equation (2.18) is integrable in the sense of Lax as well as being linearizable under a global transformation.

r	Explicit expressions of F_{11} and F_{12} in equation (2.18)
r = 1	$F_{11} = (v_m^{l+1} - v_{m+1}^l),$ $F_{12} = (1 + v_m^{l+1} v_{m+1}^l)$
r = 2	$F_{11} = 2(v_m^{l+1} - v_{m+1}^l)(1 + v_m^{l+1}v_{m+1}^l)$ $F_{12} = (1 + v_m^{l+1} - v_{m+1}^l + v_m^{l+1}v_{m+1}^l)(1 - v_m^{l+1} + v_{m+1}^l + v_m^{l+1}v_{m+1}^l)$
r = 3	$F_{11} = (v_m^{l+1} - v_{m+1}^l)[3 - (v_m^{l+1})^2 - (v_{m+1}^l)^2 + 8v_m^{l+1}v_{m+1}^l + 3(v_m^{l+1})^2(v_{m+1}^l)^2]$ $F_{12} = (1 + v_m^{l+1}v_{m+1}^l)[1 - 3(v_m^{l+1})^2 - 3(v_{m+1}^l)^2 + 8v_m^{l+1}v_{m+1}^l + (v_m^{l+1})^2(v_{m+1}^l)^2]$
<i>r</i> = 4	$\begin{split} F_{11} &= 2(v_m^{l+1} - v_{m+1}^l)(1 + v_m^{l+1}v_{m+1}^l)(1 + v_m^{l+1} - v_{m+1}^l + v_m^{l+1}v_{m+1}^l) \\ & (1 - v_m^{l+1} + v_{m+1}^l + v_m^{l+1}v_{m+1}^l) \\ F_{12} &= [1 + 2(v_m^{l+1} - v_{m+1}^l) - (v_m^{l+1})^2 - (v_{m+1}^l)^2 + 4v_m^{l+1}v_{m+1}^l \\ & + 2v_m^{l+1}v_{m+1}^l(v_m^{l+1} - v_{m+1}^l) + (v_m^{l+1})^2(v_{m+1}^l)^2][1 - 2(v_m^{l+1} - v_{m+1}^l) \\ & - (v_m^{l+1})^2 - (v_{m+1}^l)^2 + 4v_m^{l+1}v_{m+1}^l - 2v_m^{l+1}v_{m+1}^l(v_m^{l+1} - v_{m+1}^l) \\ & + (v_m^{l+1})^2(v_{m+1}^l)^2] \end{split}$
<i>r</i> = 5	$\begin{split} F_{11} &= (v_m^{l+1} - v_{m+1}^l) [5 - 2((v_m^{l+1})^2 + (v_{m+1}^l)^2) (5 + 12v_m^{l+1}v_{m+1}^l \\ &+ 5(v_m^{l+1})^2 (v_{m+1}^l)^2) + v_m^{l+1}v_{m+1}^l (40 + 76v_m^{l+1}v_{m+1}^l + 40(v_m^{l+1})^2 (v_{m+1}^l)^2 \\ &+ 5(v_m^{l+1})^3 (v_{m+1}^l)^3) + (v_m^{l+1})^4 + (v_{m+1}^l)^4] \\ F_{12} &= (1 + v_m^{l+1}v_{m+1}^l) [1 - 10((v_m^{l+1})^2 + (v_{m+1}^l)^2) (1 + 4v_m^{l+1}v_{m+1}^l + (v_m^{l+1})^2 (v_{m+1}^l)^2) \\ &+ v_m^{l+1}v_{m+1}^l (24 + 76v_m^{l+1}v_{m+1}^l + 24(v_m^{l+1})^2 (v_{m+1}^l)^2 + (v_m^{l+1})^3 (v_{m+1}^l)^3) \\ &+ 5(v_m^{l+1})^4 + 5(v_{m+1}^l)^4] \end{split}$
<i>r</i> = 6	$\begin{split} F_{11} &= 2(v_m^{l+1} - v_{m+1}^l)(1 + v_m^{l+1}v_{m+1}^l)[3 - (v_m^{l+1})^2 - (v_{m+1}^l)^2 + 8v_m^{l+1}v_{m+1}^l \\ & + 3(v_m^{l+1})^2(v_{m+1}^l)^2][1 - 3(v_m^{l+1})^2 - 3(v_{m+1}^l)^2 + 8v_m^{l+1}v_{m+1}^l + (v_m^{l+1})^2(v_{m+1}^l)^2] \\ F_{12} &= (1 + v_m^{l+1} - v_{m+1}^l + v_m^{l+1}v_{m+1}^l)(1 - v_m^{l+1} + v_{m+1}^l + v_m^{l+1}v_{m+1}^l) \\ & [1 + 4(v_m^{l+1} - v_{m+1}^l) + (v_m^{l+1})^2 + (v_{m+1}^l)^2 + 4v_m^{l+1}v_{m+1}^l(v_m^{l+1} - v_{m+1}^l) + (v_m^{l+1})^2 \\ & (v_{m+1}^l)^2][1 - 4(v_m^{l+1} - v_{m+1}^l) + (v_m^{l+1})^2 + (v_{m+1}^l)^2 - 4v_m^{l+1}v_{m+1}^l(v_m^{l+1} - v_{m+1}^l) \\ & + (v_m^{l+1})^2(v_{m+1}^l)^2] \end{split}$
etc.,	etc.,

Table 1: Explicit expressions of F_{11} and F_{12} in equation (2.18) with $r \in \mathbb{Z}^+$

r	Explicit expressions of F_{11} and F_{12} in equation (2.18)
r-odd	$F_{11} = \sum_{i=1}^{ r } (-1)^{\frac{i-1}{2}} { r \choose i} \left(\operatorname{sgn}(r) (v_m^{l+1} - v_{m+1}^l) \right)^i (1 + v_m^{l+1} v_{m+1}^l)^{ r -i}$
	$F_{12} = \sum_{\substack{i=0\\i=\text{ven}}}^{l-\text{odd}} (-1)^{\left\lceil \frac{i-1}{2} \right\rceil} {\binom{ r }{i}} \left(\text{sgn}(r)(v_m^{l+1} - v_{m+1}^l) \right)^i (1 + v_m^{l+1}v_{m+1}^l)^{ r -i}$
<i>r</i> -even	$F_{11} = \sum_{\substack{i=1\\i=d4}}^{ r-1 } (-1)^{\frac{i-1}{2}} { r \choose i} \left(\operatorname{sgn}(r) (v_m^{l+1} - v_{m+1}^l) \right)^i (1 + v_m^{l+1} v_{m+1}^l)^{ r -i}$
	$F_{12} = \sum_{\substack{i=0\\i=ven}}^{ r } (-1)^{\lceil \frac{i-1}{2} \rceil} { r \choose i} \left(\operatorname{sgn}(r)(v_m^{l+1} - v_{m+1}^l) \right)^i (1 + v_m^{l+1}v_{m+1}^l)^{ r -i}$

Table 2: Explicit expressions of F_{11} and F_{12} in equation (2.18) with $r \in \mathbb{Z} \setminus \{0\}$.

where $\lceil \frac{i-1}{2} \rceil$ is the smallest integer greater than or equal to $\frac{i-1}{2}$ and

$$\operatorname{sgn}(r) = \begin{cases} 1, \text{ if } r > 0\\ 0, \text{ if } r = 0\\ -1, \text{ if } r < 0. \end{cases}$$
(2.20)

It is appropriate to mention that Levi and Scimiterna [9] have derived a set of necessary conditions for a nonlinear $P\Delta\Delta E$ (2.4) to be linearizable [9] and we checked that equation (2.18) satisfies those conditions [9].

3. Reductions to ordinary difference equations

In this section we would like to show that how periodic reduction of the obtained nonlinear $P\Delta\Delta E$'s result to higher order autonomous $O\Delta E$'s. With this, we consider a solution v_m^l of the nonlinear $P\Delta\Delta E$ (2.4) satisfying the periodicity property

$$v_{m+z_1}^{l-z_2} = v_{l,m} = v_n, \tag{3.1}$$

where $gcd(z_1, z_2) = 1, z_1, z_2 \in \mathbb{Z}$. Here $n = mz_1 + lz_2$ and so

$$v_{m+1}^{l} = v_{n+z_1}, \ v_m^{l+1} = v_{n+z_2}, \ v_{m+1}^{l+1} = v_{n+z_1+z_2}$$

. As a consequence equation (2.4) becomes an $O\Delta E$ of order $(z_1 + z_2)$, that is

$$v_{n+z_1+z_2} = F(v_n, v_{n+z_1}, v_{n+z_2}).$$

We wish to report that the periodic reduction of each of the obtained $P\Delta\Delta E$'s in section 2 namely (2.10), (2.12), (2.14) and (2.18) results to higher order $O\Delta E$'s. We explain how to derive them below. To begin with we consider equation (2.10) which reduces into an $O\Delta E$ of order $(z_1 + z_2)$

$$v_{n+z+1} = \frac{h_{11}v_n^3 + h_{12}v_n^2 + h_{13}v_n + h_{14}}{h_{15}v_n^3 + h_{16}v_n^2 + h_{17}v_n + h_{18}},$$
(3.2)

where $h'_{1i}s$, i = 1, ..., 8 are polynomials in (v_{n+z_2}, v_{n+z_1}) given by,

$$\begin{split} h_{11} &= \alpha [1 - \alpha^{6} + \alpha (\alpha^{4} - 1)v_{n+z_{2}} + 2\alpha v_{n+z_{1}} - 2\alpha^{2} \\ &v_{n+z_{2}}v_{n+z_{1}} + \alpha^{2} (\alpha^{2} + 1)v_{n+z_{1}}^{2} - 2\alpha^{3} v_{n+z_{2}}v_{n+z_{1}}^{2}], \\ h_{12} &= \alpha^{2} [(1 - \alpha^{4}) + \alpha (\alpha^{2} - 1)v_{n+z_{2}} + 2\alpha v_{n+z_{1}} - 2\alpha^{2} v_{n+z_{2}}v_{n+z_{1}} \\ &+ 2\alpha^{2} v_{n+z_{1}}^{2} - \alpha (\alpha^{2} + 1)v_{n+z_{2}}v_{n+z_{1}}^{2}], \\ h_{13} &= \alpha^{2} [\alpha (\alpha^{2} - 1) - 2\alpha^{2} v_{n+z_{1}} + 2\alpha^{3} v_{n+z_{2}}v_{n+z_{1}} \\ &- \alpha (\alpha^{2} + 1)v_{n+z_{1}}^{2} + (\alpha^{4} + 1)v_{n+z_{2}}v_{n+z_{1}}^{2}], \\ h_{14} &= \alpha [\alpha^{2} (\alpha^{2} - 1)v_{n+z_{2}} - 2\alpha^{4} v_{n+z_{1}} + 2\alpha^{5} v_{n+z_{2}}v_{n+z_{1}} \\ &- \alpha (\alpha^{4} + 1)v_{n+z_{1}}^{2} + (\alpha^{6} + 1)v_{n+z_{2}}v_{n+z_{1}}^{2}], \\ h_{15} &= (\alpha^{6} + 1) - \alpha (\alpha^{4} + 1)v_{n+z_{2}} + 2\alpha v_{n+z_{1}} - 2\alpha^{2} v_{n+z_{2}}v_{n+z_{1}} \\ &- \alpha^{2} (\alpha^{2} - 1)v_{n+z_{1}}^{2}, \\ h_{16} &= \alpha [(\alpha^{4} + 1) - \alpha (\alpha^{2} + 1)v_{n+z_{2}} - 2\alpha^{4} v_{n+z_{1}} - 2\alpha^{2} v_{n+z_{2}}v_{n+z_{1}} \\ &- \alpha (\alpha^{2} - 1)v_{n+z_{2}}^{2}v_{n+z_{1}}^{2}], \\ h_{17} &= \alpha [-\alpha (\alpha^{2} + 1) + 2\alpha^{2} (v_{n+z_{2}} - v_{n+z_{1}}) + 2\alpha^{3} v_{n+z_{2}}v_{n+z_{1}} \\ &- \alpha (\alpha^{2} - 1)v_{n+z_{1}}^{2} + (\alpha^{4} - 1)v_{n+z_{2}}v_{n+z_{1}}^{2}], \\ h_{18} &= -2\alpha^{3} + \alpha^{2} (\alpha^{2} + 1)v_{n+z_{2}} - 2\alpha^{4} v_{n+z_{1}} + 2\alpha^{5} v_{n+z_{2}}v_{n+z_{1}} \\ &- \alpha (\alpha^{4} - 1)v_{n+z_{1}}^{2} + (\alpha^{6} - 1)v_{n+z_{2}}v_{n+z_{1}}^{2}. \end{split} \right\}$$

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By assigning distinct values for z_1 and z_2 one can derive higher order $O\Delta E$'s and its integrability is an open question. However equation (3.2) with $\alpha^2 = -1$ or equation (2.12) becomes

$$v_{n+z_1+z_2} = \frac{v_{n+z_2} - v_{n+z_1} + v_n(1 + v_{n+z_1}v_{n+z_2})}{(1 + v_{n+z_1}v_{n+z_2}) - v_n(v_{n+z_2} - v_{n+z_1})}$$
(3.4)

which can be transformed into a linear $O\Delta E$

$$\theta_{n+z_1+z_2} - (\theta_{n+z_2} - \theta_{n+z_1}) - \theta_n = p\pi, \ \theta_n = tan^{-1}(v_n), p \in \mathbb{Z}$$

$$(3.5)$$

and hence the reduced $O\Delta E$ of order $(z_1 + z_2)$ is linearizable and so integrable. Similar conclusion can be arrived at for the reduced equation, obtained from equation (2.14), given by

$$v_{n+z+1} = \frac{\tilde{h}_{11}v_n^3 + \tilde{h}_{12}v_n^2 + \tilde{h}_{13}v_n + \tilde{h}_{14}}{\tilde{h}_{15}v_n^3 + \tilde{h}_{16}v_n^2 + \tilde{h}_{17}v_n + \tilde{h}_{18}}$$
(3.6)

where \tilde{h}_{1i} 's, i = 1, ..., 8 are polynomials in (v_{n+z_2}, v_{n+z_1}) and its integrability is an open question. As before equation (3.6) with $\alpha^2 = -1$ can be transformed into linear $O\Delta E$. Next, the $O\Delta E$ arising from equation (2.18) reads

$$v_{n+z_1+z_2} = \frac{F_{11}(v_{n+z_2}, v_{n+z_1}) + v_n F_{12}(v_{n+z_2}, v_{n+z_1})}{F_{12}(v_{n+z_2}, v_{n+z_1}) - v_n F_{11}(v_{n+z_2}, v_{n+z_1})},$$
(3.7)

where F_{11} and F_{12} are specific polynomials of degree (2|r|-1) and 2|r| respectively and their explicit expression for different values of r are given in Table 3 and Table 4.

Equation (3.7) can be transformed into a linear $O\Delta E$ of order $(z_1 + z_2)$ with constant coefficients

$$\theta_{n+z_1+z_2} - r(\theta_{n+z_2} - \theta_{n+z_1}) - \theta_n = p\pi, \ \theta_n = tan^{-1}(v_n), \ p \in \mathbb{Z}, \ r \in \mathbb{Z} \setminus \{0\}$$
(3.8)

and so integrable.

We wish to add that the linearizable equation (3.7) also possesses more than one integrals for lower order with specific values of r. Some of them are as follows:

Case I: $r = 1, z_1 = 1, z_2 = 2$ Equation (3.4) becomes a third order $O\Delta E$

$$v_{n+3} = \frac{v_{n+2} - v_{n+1} + (1 + v_{n+1}v_{n+2})v_n}{(1 + v_{n+1}v_{n+2}) - (v_{n+2} - v_{n+1})v_n}$$
(3.9)

which admits two integrals $J_1(n)$ and $J_2(n)$

$$J_1(n) = \frac{1 - v_n v_{n+2}}{1 - v_n v_{n+2} + v_n + v_{n+2}},$$

$$J_2(n) = \frac{P_1(n)}{P_2(n)},$$

where

where

$$P_{1}(n) = (v_{n+1}^{2}v_{n+2} - v_{n+2}^{2} + v_{n+1}v_{n+2} + v_{n+1})v_{n}^{2} + v_{n+1}v_{n+2}^{2} - v_{n+1}^{2} + (1 + v_{n+1})v_{n+2} + (1 + v_{n+1})(1 + v_{n+2})(1 + v_{n+1}v_{n+2})v_{n},$$

$$P_{2}(n) = [v_{n+1}v_{n+2}(v_{n+1}v_{n+2} + v_{n+1} + 1) + v_{n+1}^{2} + v_{n+1} + 1]v_{n}^{2} + v_{n+1}^{2}v_{n+2}^{2} + 1 + (1 + v_{n+1})(1 + v_{n+2})(1 + v_{n+1}v_{n+2})v_{n} + (1 + v_{n+1})(v_{n+2} + v_{n+2}^{2}).$$

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New Integrable and Linearizable Nonlinear Difference Equations

r	Explicit expressions of F_{11} and F_{12} in equation (3.7)
r = 1	$F_{11} = (v_{n+z_2} - v_{n+z_1}),$
	$F_{12} = (1 + v_{n+z_2}v_{n+z_1})$
<i>r</i> = 2	$F_{11} = 2(v_{n+z_2} - v_{n+z_1})(1 + v_{n+z_2}v_{n+z_1})$
	$F_{12} = (1 + v_{n+z_2} - v_{n+z_1} + v_{n+z_2} v_{n+z_1})(1 - v_{n+z_2} + v_{n+z_1} + v_{n+z_2} v_{n+z_1})$
r = 3	$F_{11} = (v_{n+z_2} - v_{n+z_1})[3 - (v_{n+z_2})^2 - (v_{n+z_1})^2 + 8v_{n+z_2}v_{n+z_1} + 3(v_{n+z_2})^2(v_{n+z_1})^2]$
	$F_{12} = (1 + v_{n+z_2}v_{n+z_1})[1 - 3(v_{n+z_2})^2 - 3(v_{n+z_1})^2 + 8v_{n+z_2}v_{n+z_1} + (v_{n+z_2})^2(v_{n+z_1})^2]$
	$F_{11} = 2(v_{n+z_2} - v_{n+z_1})(1 + v_{n+z_2}v_{n+z_1})(1 + v_{n+z_2} - v_{n+z_1} + v_{n+z_2}v_{n+z_1})$
	$(1 - v_{n+z_2} + v_{n+z_1} + v_{n+z_2}v_{n+z_1})$
r = 1	$F_{12} = [1 + 2(v_{n+z_2} - v_{n+z_1}) - (v_{n+z_2})^2 - (v_{n+z_1})^2 + 4v_{n+z_2}v_{n+z_1}]$
/ _ 4	$+2v_{n+z_2}v_{n+z_1}(v_{n+z_2}-v_{n+z_1})+(v_{n+z_2})^2(v_{n+z_1})^2][1-2(v_{n+z_2}-v_{n+z_1})$
	$-(v_{n+z_2})^2 - (v_{n+z_1})^2 + 4v_{n+z_2}v_{n+z_1} - 2v_{n+z_2}v_{n+z_1}(v_{n+z_2} - v_{n+z_1})$
	$+(v_{n+z_2})^2(v_{n+z_1})^2]$
	$F_{11} = (v_{n+z_2} - v_{n+z_1}) \left[5 - 2\left((v_{n+z_2})^2 + (v_{n+z_1})^2 \right) \left(5 + 12v_{n+z_2}v_{n+z_1} \right) \right]$
	$+5(v_{n+z_2})^2(v_{n+z_1})^2)+v_{n+z_2}v_{n+z_1}(40+76v_{n+z_2}v_{n+z_1}+40(v_{n+z_2})^2(v_{n+z_1})^2)$
r — 5	$+5(v_{n+z_2})^3(v_{n+z_1})^3) + (v_{n+z_2})^4 + (v_{n+z_1})^4]$
r = 3	$F_{12} = (1 + v_{n+z_2}v_{n+z_1})[1 - 10((v_{n+z_2})^2 + (v_{n+z_1})^2)(1 + 4v_{n+z_2}v_{n+z_1})]$
	$+(v_{n+z_2})^2(v_{n+z_1})^2)+v_{n+z_2}v_{n+z_1}(24+76v_{n+z_2}v_{n+z_1}+24(v_{n+z_2})^2(v_{n+z_1})^2)$
	$+(v_{n+z_2})^3(v_{n+z_1})^3)+5(v_{n+z_2})^4+5(v_{n+z_1})^4]$
<i>r</i> = 6	$F_{11} = 2(v_{n+z_2} - v_{n+z_1})(1 + v_{n+z_2}v_{n+z_1})[3 - (v_{n+z_2})^2 - (v_{n+z_1})^2 + 8v_{n+z_2}v_{n+z_1}]$
	$+3(v_{n+z_2})^2(v_{n+z_1})^2][1-3(v_{n+z_2})^2-3(v_{n+z_1})^2+8v_{n+z_2}v_{n+z_1})^2]$
	$+(v_{n+z_2})^2(v_{n+z_1})^2$
	$F_{12} = (1 + v_{n+z_2} - v_{n+z_1} + v_{n+z_2} v_{n+z_1})(1 - v_{n+z_2} + v_{n+z_1} + v_{n+z_2} v_{n+z_1})$
	$[1 + 4(v_{n+z_2} - v_{n+z_1}) + (v_{n+z_2})^2 + (v_{n+z_1})^2 + 4v_{n+z_2}v_{n+z_1}(v_{n+z_2} - v_{n+z_1})$
	$+(v_{n+z_2})^2(v_{n+z_1})^2[(1-4(v_{n+z_2}-v_{n+z_1})+(v_{n+z_2})^2+(v_{n+z_1})^2-4v_{n+z_2}v_{n+z_1})$
	$(v_{n+z_2} - v_{n+z_1}) + (v_{n+z_2})^2 (v_{n+z_1})^2]$
etc.,	etc.,

Table 3: Explicit expressions of F_{11} and F_{12} in equation (3.7) with $r \in \mathbb{Z}^+$

It is easy to check that equation (3.9) is measure preserving with measure $\frac{1}{P_2(n)}$ [31].

Case II: r = 1, $z_1 = 1$, $z_2 = 3$ Here equation (3.4) becomes a fourth order $O\Delta E$

$$v_{n+4} = \frac{v_{n+3} - v_{n+1} + (1 + v_{n+1}v_{n+3})v_n}{(1 + v_{n+1}v_{n+3}) - (v_{n+3} - v_{n+1})v_n}$$
(3.10)

which admits two integrals $J_1(n)$ and $J_2(n)$

$$J_1(n) = \frac{1 - v_n v_{n+3}}{1 - v_n v_{n+3} + v_n + v_{n+3}},$$

$$J_2(n) = \frac{Q_1(n) + Q_2(n)}{-Q_1(n) + Q_2(n)},$$

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$$\begin{array}{|c|c|c|c|c|c|}\hline r & \text{Explicit expressions of } F_{11} \text{ and } F_{12} \text{ in equation } (3.7) \\ \hline r \text{-odd} & F_{11} = \sum_{i=0}^{|r|} (-1)^{\frac{i-1}{2}} {|r| \choose i} \left(\text{sgn}(r) (v_{n+z_2} - v_{n+z_1}) \right)^i (1 + v_{n+z_2} v_{n+z_1})^{|r|-i} \\ \hline r \text{-odd} & F_{12} = \sum_{i=0}^{|r-1|} (-1)^{\left\lceil \frac{i-1}{2} \rceil} {|r| \choose i} \left(\text{sgn}(r) (v_{n+z_2} - v_{n+z_1}) \right)^i (1 + v_{n+z_2} v_{n+z_1})^{|r|-i} \\ \hline r \text{-even} & F_{11} = \sum_{i=0}^{|r-1|} (-1)^{\frac{i-1}{2}} {|r| \choose i} \left(\text{sgn}(r) (v_{n+z_2} - v_{n+z_1}) \right)^i (1 + v_{n+z_2} v_{n+z_1})^{|r|-i} \\ \hline F_{12} = \sum_{i=0 \atop i-\text{oud}} |r| (-1)^{\left\lceil \frac{i-1}{2} \rceil} {|r| \choose i} \left(\text{sgn}(r) (v_{n+z_2} - v_{n+z_1}) \right)^i (1 + v_{n+z_2} v_{n+z_1})^{|r|-i} \\ \hline \end{array}$$

Table 4: Explicit expressions of
$$F_{11}$$
 and F_{12} in equation (3.7) with $r \in \mathbb{Z} \setminus \{0\}$.

where $Q_1(n) = (v_n + v_{n+3})(v_{n+2}v_{n+3} + 1)(v_{n+1}v_n + 1)(v_{n+2}v_{n+1} + 1),$ $Q_2(n) = (1 + v_n^2)(1 + v_{n+1}^2)(1 + v_{n+2}^2)(1 + v_{n+3}^2).$ We have verified that equation (3.10) is a measure preserving one with measure $\frac{1}{[-O_1(n)+O_2(n)]}$ [32].

Case III: $r = 2, z_1 = 1, z_2 = 2$ Equation (3.7) becomes a third order $O\Delta E$

$$v_{n+3} = \frac{F_{11}(v_{n+2}, v_{n+1}) + v_n F_{12}(v_{n+2}, v_{n+1})}{F_{12}(v_{n+2}, v_{n+1}) - v_n F_{11}(v_{n+2}, v_{n+1})}$$
(3.11)

where

 $F_{11} = 2(v_{n+2} - v_{n+1})(1 + v_{n+1}v_{n+2}),$ $F_{12} = (1 + v_{n+2} - v_{n+1} + v_{n+1}v_{n+2})(1 - v_{n+2} + v_{n+1} + v_{n+1}v_{n+2}).$ which admits two integrals $J_1(n)$ and $J_2(n)$ given by

$$J_1(n) = \frac{2[(v_{n+1}-1)(v_n+v_{n+2})-(v_{n+1}+1)(v_nv_{n+2}-1)]}{v_{n+1}(v_n+v_{n+2})-(v_nv_{n+2}-1)}$$

$$J_2(n) = \frac{R_1(n)}{R_2(n)},$$

where

where $\begin{aligned} R_1(n) &= [\gamma_3(n)v_{n+2}^2 - \gamma_2(n)v_{n+2} + \gamma_1(n)]v_n^2 + [-\gamma_2(n)(v_{n+2}^2 - 1) - 4v_{n+1}v_{n+2}]v_n \\ &+ [\gamma_1(n)v_{n+2}^2 + \gamma_2(n)v_{n+2} + \gamma_3(n)], \\ R_2(n) &= -[\gamma_1(n)v_{n+2}^2 + \gamma_2(n)v_{n+2} + \gamma_3(n)]v_n^2 + [-\gamma_2(n)(v_{n+2}^2 - 1) - 4v_{n+1}v_{n+2}]v_n \\ &- [\gamma_3(n)v_{n+2}^2 - \gamma_2(n)v_{n+2} + \gamma_1(n)], \\ \gamma_1(n) &= -(v_{n+1}^2 + v_{n+1} + 1), \ \gamma_2(n) &= (v_{n+1}^2 - 1), \\ \gamma_3(n) &= (-v_{n+1}^2 + v_{n+1} - 1). \end{aligned}$ We have verified that equation (3.10) is measure preserving with measure $\frac{1}{10}$ [3.10]

We have verified that equation (3.10) is measure preserving with measure $\frac{1}{R_2(n)}$ [31].

Similarly higher order $O\Delta E$'s can be obtained by taking different values for z_1 and z_2 in equation (3.7) which may admit more than one integral.

4. Summary and Concluding Remarks

In this article, a systematic investigation has been made to derive autonomous nonlinear $P\Delta\Delta E$'s admitting specific Lax representation. In Section 2, we have derived two nonlinear $P\Delta\Delta E$'s equations (2.10) and (2.14) possessing Lax pair but not belonging to QRT type. Also we have derived another nonlinear $P\Delta\Delta E$ (2.18) which is a QRT type and shown that it is linearizable with $r \in \mathbb{Z} \setminus \{0\}$. We would like to mention that nonlinear $P\Delta\Delta E$'s (2.10) and (2.14) fall into equation (2.18) when r = 1 and r = 2 respectively, for a particular parametric restriction. Equation (2.12) gives a particular case of equation (2.18) when r = 1.

In Section 3, we have shown how $O\Delta E$'s of order $(z_1 + z_2)$ namely equations (3.2), (3.6) and (3.7) can be derived from each of the identified nonlinear $P\Delta\Delta E$'s (2.10), (2.14) and (2.18) respectively. Among them, the reduced equations (3.2) and (3.6) obtained from equations (2.10) and (2.14) respectively are nonintegrable in general and their integrability nature is under investigation. The reduced equation of order $(z_1 + z_2)$ obtained from equation (2.18), given in equation (3.7) can be transformed into a linear $O\Delta E$ (3.8) ensuring its integrability. Further we have discussed the integrability of lower orders of equation (3.7) in three different cases giving different values for z_1 and z_2 . We obtain one third order $O\Delta E$ each in Case I and III, from equation (3.7), namely equation (3.9) and equation (3.11) respectively, admitting two integrals. Next in Case II, from equation (3.7) we get a fourth order $O\Delta E$ (3.10) admitting two integrals.

Equations (3.9), (3.10) and (3.11) are measure preserving and the corresponding measures are given in each case. We would like to caution the reader that the analysis carried out in this article is not an exhaustive one. It is also interesting to find the most general form of Lax integrable and linearizable nonlinear $P\Delta\Delta E$'s with the above mentioned global transformation which is under investigation. In addition examining the corresponding $O\Delta E$'s, obtained through periodic reductions of the $P\Delta\Delta E$'s, for integrability is also under investigation.

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