

Retraction

RETRACTION: Design of an Optimized GMV Controller based on Data-Driven ApproachLiyong Shi^{1,*}, Zhe Guan², Toru Yamamoto³¹Graduate School of Engineering, Hiroshima University, 1-4-1 Kagamiyama, HigashiHiroshima 739-8527, Japan²KOBELCO Construction Machinery Dream-Driven Co-Creation Research Center, Hiroshima University, 1-4-1 Kagamiyama, HigashiHiroshima 739-8527, Japan³Graduate School of Advanced Science and Engineering, 1-4-1 Kagamiyama, HigashiHiroshima, Hiroshima 739-8527, Japan

The Editor-in-Chief - Dr. Masanori Sugisaka - has retracted this article (<https://doi.org/10.2991/jrnal.k.211108.001>), because it has already been published in a previous issue of Journal of Robotics, Networking and Artificial Life [1]. This was not noticed during the proofing stage, resulting in a duplicate publication. We apologize to the authors and readers for the inconvenience.

All authors agree to the retraction.

[1] Shi, L., Guan, Z. and Yamamoto, T., 2021. Design of an Optimized GMV Controller based on Data-Driven Approach. // Journal of Robotics, Networking and Artificial Life, 8(3), 180-185. <https://doi.org/10.2991/jrnal.k.210922.006>

All parties would like to apologize for any inconvenience this may cause.

The full Atlantis Press Policy on Article Retraction can be found at: <https://www.atlantis-press.com/policies/article-retraction-and-withdrawal>.