

The Existence of the Moore-Penrose Inverse in Symmetrized Max-Plus Algebraic Matrix

Suroto Suroto^{1,*} Najmah Istikaanah¹, Renny Renny¹

¹*Departement of Mathematics, Universitas Jenderal Soedirman, Purwokerto, Central Java, Indonesia*

^{*}*Corresponding author. Email: suroto@unsoed.ac.id*

ABSTRACT

In this paper we discuss Moore-Penrose inverse in symmetrized max-plus algebraic matrix. The existence of Moore-Penrose inverse is shown using a link among symmetrized max-plus algebra and conventional algebra. The result is a Moore-Penrose inverse in symmetrized max-plus algebraic matrix exists. Furthermore, the balanced inverse and the max-plus inverse are also the Moore-Penrose inverse in symmetrized max-plus algebraic matrix.

Keywords: *Existence, Moore-Penrose inverse, Symmetrized max-plus algebra, Conventional algebra.*

1. INTRODUCTION

Max-plus algebra is the set of $\mathbb{R} \cup \{-\infty\}$ equipped with maximum (simply written "max") as addition and usual addition (simply written "plus") as multiplication, where \mathbb{R} is the set of all real numbers. Henceforth, the max-plus algebra is denoted by \mathbb{R}_{\max} . It is different from conventional algebra, since there is no inverse element under addition for every element in max-plus algebra, except for zero element [1][2][3]. The symmetrization process can be done to solve the additive inverse problem. This process is carried out using a balance relation (denoted by ∇) in order to obtain the minus and balance of all elements in \mathbb{R}_{\max} . The result of this symmetrization is called symmetrized max-plus algebra and denoted by \mathbb{S} [4][5].

In conventional algebra, it is known that A^{-1} denotes the inverse of an invertible square matrix $A_{n \times n}$ [6]. It is known that there is an inverse for an $m \times n$ matrix called the Moore-Penrose inverse and usually denoted by A^+ [7]. The concept of the inverse of an $n \times n$ matrix can be used as an alternative way to find a solution to a system of linear equations in the form $Ax = b$. If A is an invertible matrix, then the solution of the system of linear equations can be solved using the formula $x = A^{-1}b$. If the matrix A of the system has a size of $m \times n$, the solution of the system cannot be found using these rules. The discussion about application of the Moore-Penrose inverse in linear equation systems was discussed in [8].

The discussion about the Moore-Penrose inverse on arbitrary ring and integral domain were discussed in [9] and [10], respectively. In this paper, we discuss the Moore-Penrose inverse of matrix over \mathbb{S} . We use a link

between \mathbb{S} and conventional algebra in [11] to show the existence of Moore-Penrose inverse in \mathbb{S} . We adopt the Moore-Penrose inverse in conventional algebra [12] to define the Moore-Penrose inverse in \mathbb{S} , by changing equal relation in the conventional Moore-Penrose inverse into balance relation in symmetrized max-plus algebra. The results in this paper can potentially be used as an alternative tool to solve the solution of the systems of linear balance in \mathbb{S} .

2. BASIC TERMINOLOGY

This section discusses basic terminologies in symmetrized max-plus algebra. Let \mathbb{R} be the set of all real numbers, $\mathcal{E} \stackrel{\text{def}}{=} -\infty$ and $\mathbb{R}_{\mathcal{E}} \stackrel{\text{def}}{=} \mathbb{R} \cup \{-\infty\}$. The basic operations in $\mathbb{R}_{\mathcal{E}}$ are defined by

$$a \oplus b = \max\{a, b\} \quad (1)$$

$$a \otimes b = a + b \quad (2)$$

where $\max\{a, -\infty\} = a$ and $a + (-\infty) = -\infty$, for all $a, b \in \mathbb{R}_{\mathcal{E}}$. The mathematical system $\mathbb{R}_{\max} = (\mathbb{R}_{\mathcal{E}}, \oplus, \otimes)$ is called the max-plus algebra, with the zero element is \mathcal{E} , the unity element is e and the zero element \mathcal{E} is absorbing for \otimes . Furthermore, \mathbb{R}_{\max} is an idempotent commutative semiring. There is no inverse element under addition for all a in \mathbb{R}_{\max} except for $a = \mathcal{E}$.

Let $P_{\mathcal{E}} \stackrel{\text{def}}{=} \mathbb{R}_{\mathcal{E}} \times \mathbb{R}_{\mathcal{E}}$. The basic operations in $P_{\mathcal{E}}$ are defined by

$$(a, b) \oplus (c, d) = (a \oplus c, b \oplus d) \quad (3)$$

$$(a, b) \otimes (c, d) = (a \otimes c \oplus b \otimes d, a \otimes d \oplus b \otimes c) \quad (4)$$

for all $(a, b), (c, d) \in P_{\mathcal{E}}$. The zero element is $(\mathcal{E}, \mathcal{E})$, the unity element is $(0, \mathcal{E})$ and $(\mathcal{E}, \mathcal{E})$ is absorbing for multiplication. The mathematical system $P_{\max} = (P_{\mathcal{E}}, \oplus$

(\otimes) is a commutative idempotent semiring and called the algebra of pairs. Some terminologies in algebra of pairs refers to [4]. If $u = (a, b) \in P_{\max}$, then the absolute value of u is defined as $|u|_{\oplus} = a \oplus b$, the minus of u is $\ominus u = (b, a)$ and the balance of u is $u^* = u \oplus (\ominus u) = (|u|_{\oplus}, |u|_{\oplus})$. Furthermore, for all $u, v \in P_{\max}$, the following statements are satisfied: $u^* = (\ominus u)^* = (u^*)^*$, $u \otimes v^* = u^* \otimes v = (u \otimes v)^*$, $\ominus(\ominus u) = u$, $\ominus(u \oplus v) = (\ominus u) \oplus (\ominus v)$ and $\ominus(u \otimes v) = (\ominus u) \otimes v$.

In the conventional algebra, for all $x \in \mathbb{R}$, $x - x = 0$, but for all $u \in P_{\max}$, $u \ominus u = u^* \neq (\mathcal{E}, \mathcal{E})$, except $u = (\mathcal{E}, \mathcal{E})$. It is important to introduce "balance" relation for substituting "equal" relation in conventional algebra. If $u = (a, b), v = (c, d) \in P_{\max}$, balance relation (denoted by ∇) in P_{\max} is defined as follows :

$$u \nabla v \text{ if } a \oplus d = b \oplus c. \tag{5}$$

The balance relation reflexive, symmetric but it is not transitive, so that it is impossible to define the quotient set of $P_{\mathcal{E}}$ by ∇ . For example, $(5,4) \nabla (5,5)$ and $(5,5) \nabla (4,5)$ but $(5,4) \not\nabla (4,5)$. The new relation will be introduced in order to solve "transitive problem" in balance relation. Let $u = (a, b), v = (c, d) \in P_{\max}$, relation \mathcal{B} in P_{\max} is defined as follows :

$$u \mathcal{B} v \text{ if } \begin{cases} (a, b) \nabla (c, d), & \text{if } a \neq b \text{ and } c \neq d \\ (a, b) = (c, d), & \text{if } a = b \text{ or } c = d \end{cases} \tag{6}$$

For all $u \in P_{\max}$, $u \ominus u \mathcal{B} (\mathcal{E}, \mathcal{E})$ except for $u = (\mathcal{E}, \mathcal{E})$ and \mathcal{B} is an equivalence relation. So, it is possible to obtain a quotient set of P_{\max} by \mathcal{B} . The equivalence classes generated by \mathcal{B} are

1. $\overline{(w, -\infty)} = \{(w, x) \in P_{\max} | x < w\}$ is called max-positive,
2. $\overline{(-\infty, w)} = \{(x, w) \in P_{\max} | x < w\}$ is called max-negative, and
3. $\overline{(w, w)} = \{(w, w) \in P_{\max}\}$ is called balanced.

The quotient set of P_{\max} by \mathcal{B} is denoted $P_{\max}/\mathcal{B} \stackrel{\text{def}}{=} \mathbb{S}$. Note that $(5,4)$ balance with $(5,5)$ and $(5,5)$ also balance with $(4,5)$, but $(5,4)$ is not \mathcal{B} relation to $(5,5)$, neither are $(5,5)$ and $(4,5)$.

The mathematical system $\mathbb{S}_{\max} = (\mathbb{S}, \oplus, \otimes)$ is called the symmetrized max-plus algebra. The zero element is the class $\bar{\mathcal{E}} = \overline{(\mathcal{E}, \mathcal{E})}$ class, the unity element is the class $\bar{e} = \overline{(0, \mathcal{E})}$ and the zero element $\overline{(\mathcal{E}, \mathcal{E})}$ is absorbing for \otimes . Furthermore, $\overline{(w, -\infty)}$, $\overline{(-\infty, w)}$ and $\overline{(w, w)}$ are sufficiently written by w , $\ominus w$ and w^* , respectively. The set of all max-positive class or zero class, max-negative class or zero class and balanced class are denoted by \mathbb{S}^{\oplus} , \mathbb{S}^{\ominus} and \mathbb{S}^* , respectively. The set $\mathbb{S}^{\vee} = \mathbb{S}^{\oplus} \cup \mathbb{S}^{\ominus}$ is called the set of all signed element. Note that $\mathbb{S}^{\oplus} \cup \mathbb{S}^{\ominus} \cup \mathbb{S}^* = \mathbb{S}$ and $\mathbb{S}^{\oplus} \cap \mathbb{S}^{\ominus} \cap \mathbb{S}^* = \{\overline{(\mathcal{E}, \mathcal{E})}\}$.

The basic operation of matrix over \mathbb{S} can be done in the usual way as that in conventional algebra. The zero matrix in $\mathbb{S}^{m \times n}$ is $[\mathcal{E}]$ with $\mathcal{E}_{ij} = \mathcal{E}$ for all $i = 1, 2, \dots, m$

and $j = 1, 2, \dots, n$. The identity matrix is $I = [a] \in \mathbb{S}^{n \times n}$ with $a_{ij} = e$ if $i = j$ and $a_{ij} = \mathcal{E}$ if $i \neq j$, for $i, j = 1, 2, \dots, n$. For all $A, B \in \mathbb{S}^{m \times n}$, $A \nabla B$ if $a_{ij} \nabla b_{ij}$ for $i = 1, 2, \dots, m$ and $j = 1, 2, \dots, n$. If $A = \begin{bmatrix} 1 & \ominus 2 \\ \mathcal{E} & 3^* \end{bmatrix}$ and $B = \begin{bmatrix} 2^* & \ominus 2 \\ 4^* & 3 \end{bmatrix}$, then $A \nabla B$ since $a_{ij} \nabla b_{ij}$ for $i = 1, 2$ and $j = 1, 2$. Note that the corresponding entries of A and B are not always equal.

3. A LINK BETWEEN CONVENTIONAL ALGEBRA AND SYMMETRIZED MAX-PLUS ALGEBRA

This section discusses a link between \mathbb{S} and conventional algebra. It is used to solve the Moore-Penrose inverse in \mathbb{S} via conventional algebra approach. In this paper, this link is used to show the existence of axioms of the Moore-Penrose inverse in \mathbb{S} sense. The link is referred from [11].

Definition 1

A mapping \mathcal{F} with domain of definition $\mathbb{S} \times \mathbb{R}_0 \times \mathbb{R}_0^+$ is defined as

$$\mathcal{F}(a, \mu, s) = \begin{cases} |\mu|e^{as}, & \text{if } a \in \mathbb{S}^{\oplus} \\ -|\mu|e^{|\mu| \oplus s}, & \text{if } a \in \mathbb{S}^{\ominus} \\ \mu e^{|\mu| \oplus s}, & \text{if } a \in \mathbb{S}^* \end{cases} \tag{7}$$

where $a \in \mathbb{S}, \mu \in \mathbb{R}_0, s \in \mathbb{R}_0^+$.

Definition 2

Let $f(s) \sim v e^{|\mu| \oplus s}$ be in the neighbourhood of ∞ , here is the function \mathcal{R} is defined as

$$\mathcal{R}(f) = \begin{cases} |a|_{\oplus}, & \text{if } v \text{ positive} \\ \ominus |a|_{\oplus}, & \text{if } v \text{ negative} \end{cases} \tag{8}$$

The function in (7) and (8) are used to correspond elements in symmetrized max-plus algebra into conventional algebra and otherwise, respectively. If $\mu = 1$ then $\mathcal{F}(5, 1, s) = e^{5s}$, $\mathcal{F}(\ominus 5, 1, s) = e^{-5s}$ and $\mathcal{F}(5^*, 1, s) = e^{5s}$. Note that $\mathcal{R}(\mathcal{F}(5, 1, s)) = \mathcal{R}(e^{5s}) = 5$ and $\mathcal{R}(\mathcal{F}(\ominus 5, 1, s)) = \mathcal{R}(e^{-5s}) = \ominus 5$. Range of \mathcal{R} is $\mathbb{S}^{\vee} = \mathbb{S}^{\oplus} \cup \mathbb{S}^{\ominus}$ i.e the set of all signed element.

The following theorem explain the correspondence between addition and multiplication in symmetrized max-plus algebra into conventional algebra.

Theorem 3

Let $a, b, c \in \mathbb{S}$.

1. If $a \oplus b = c$ then there are $\mu_a, \mu_b, \mu_c \in \mathbb{R}_0$ such that $\mathcal{F}(a, \mu_a, s) + \mathcal{F}(b, \mu_b, s) \sim \mathcal{F}(c, \mu_c, s)$, $s \rightarrow \infty$.
2. If there are $\mu_a, \mu_b, \mu_c \in \mathbb{R}_0$ such that $\mathcal{F}(a, \mu_a, s) + \mathcal{F}(b, \mu_b, s) \sim \mathcal{F}(c, \mu_c, s)$, for $s \rightarrow \infty$ then $a \oplus b \nabla c$.
3. If $a \otimes b = c$ then there are $\mu_a, \mu_b, \mu_c \in \mathbb{R}_0$ such that $\mathcal{F}(a, \mu_a, s) \times \mathcal{F}(b, \mu_b, s) = \mathcal{F}(c, \mu_c, s)$, $s \in \mathbb{R}_0^+$.
4. If there are $\mu_a, \mu_b, \mu_c \in \mathbb{R}_0$ such that

$$\mathcal{F}(a, \mu_a, s) \times \mathcal{F}(b, \mu_b, s) = \mathcal{F}(c, \mu_c, s), \text{ for } s \in \mathbb{R}_0^+ \text{ then } a \otimes b \nabla c.$$

We can expand Theorem 3 into matrix over \mathbb{S} . If $A = [a_{ij}] \in \mathbb{S}^{m \times n}$ and $M_A = [(m_A)_{ij}] \in \mathbb{R}_0^{m \times n}$ then $\tilde{A} = [\tilde{a}_{ij}] = \mathcal{F}(A, M_A, \cdot)$ is the $m \times n$ real matrix-valued function of A with $\tilde{a}_{ij}(s) = \mathcal{F}(a_{ij}, (m_A)_{ij}, s)$.

Theorem 4

Let A, B, C are matrices whose entries are in \mathbb{S} .

1. If $A \oplus B = C$ then there are matrices M_A, M_B, M_C whose entries are in \mathbb{R}_0 such that $\mathcal{F}(A, M_A, s) + \mathcal{F}(B, M_B, s) \sim \mathcal{F}(C, M_C, s), s \rightarrow \infty$.
2. If there are matrices M_A, M_B, M_C whose entries are in \mathbb{R}_0 such that $\mathcal{F}(A, M_A, s) + \mathcal{F}(B, M_B, s) \sim \mathcal{F}(C, M_C, s), s \rightarrow \infty$ then $A \oplus B \nabla C$.
3. If $A \otimes B = C$ then there are matrices M_A, M_B, M_C whose entries are in \mathbb{R}_0 such that $\mathcal{F}(A, M_A, s) \times \mathcal{F}(B, M_B, s) \sim \mathcal{F}(C, M_C, s), s \rightarrow \infty$.
4. If there are matrices M_A, M_B, M_C whose entries are in \mathbb{R}_0 such that $\mathcal{F}(A, M_A, s) \times \mathcal{F}(B, M_B, s) \sim \mathcal{F}(C, M_C, s), s \rightarrow \infty$ then $A \otimes B \nabla C$.

The entries of the matrix in \mathbb{S} will be considered as sums or series of exponentials. So we give the definition such functions and their properties.

Definition 5

Let S_e be the set of real functions which are analytic and can be written as a sum of exponentials in a neighborhood of ∞ , i.e

$$S_e = \{f: A \rightarrow \mathbb{R} | A \subseteq \mathbb{R}, \exists K \in \mathbb{R}_0^+ \text{ such that } [K, \infty) \subseteq A \text{ and } f \text{ is analytic in } [K, \infty) \text{ and either } \forall x \geq K, f(x) = \sum_{i=0}^n \alpha_i e^{b_i x}, n \in \mathbb{N}, \alpha_i \in \mathbb{R}_0, b_i \in \mathbb{R}_\varepsilon \text{ for all } i \text{ and } b_0 > b_1 > \dots > b_n \text{ or } \forall x \geq K, f(x) = \sum_{i=0}^\infty \alpha_i e^{b_i x}, \alpha_i \in \mathbb{R}_0, b_i \in \mathbb{R}, b_i > b_{i+1}, \lim_{i \rightarrow \infty} b_i = \varepsilon \text{ and the series are absolutely convergent for each } x \geq K\}.$$

Theorem 6

If $f \in S_e$ then $f(x) \sim \alpha_0 e^{b_0 x}$ for $x \rightarrow \infty$.

Theorem 7

1. If f and g belong to S_e then $pf, f + g, fg, f^l$ and $|f|$ are also in S_e for all $p \in \mathbb{R}$ and $l \in \mathbb{N}$.
2. If there exists $K \in \mathbb{R}$ such that $f(x) \neq 0$ for each $x \geq K$ then $\frac{1}{f}$ and $\frac{g}{f}$ restricted to $[K, \infty)$ are also in S_e .
3. If there exist $Q \in \mathbb{R}$ such that $f(x) > 0$ for every $x \geq Q$ then \sqrt{f} restricted to $[Q, \infty)$ are also in S_e .

4. THE MOORE-PENROSE INVERSE IN SYMMETRIZED MAX-PLUS ALGEBRAIC MATRIX

This section discusses the existence of the Moore-Penrose inverse in \mathbb{S} sense. The link between \mathbb{S} and conventional algebra is used to derive several properties in determining the existence of the Moore-Penrose inverse on matrix over \mathbb{S} .

The following theorems explain the existence of the balance of matrix over \mathbb{S} , which is similiar to the first and second axioms of the Moore-Penrose in conventional algebra.

Theorem 8

Let A and X be matrices over \mathbb{S} . If there are matrices N_A, N_X whose entries are in \mathbb{R}_0 such that $\mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s) \sim \mathcal{F}(A, N_A, s),$ for $s \rightarrow \infty$, then $A \otimes X \otimes A \nabla A$.

Proof. Let a and x be entries of A and X , respectively. By using Definition 1, the exponential form of all entries in A and X as in conventional algebra are obtained. All entries in exponential form are in S_e . Therefore, according to Theorem 6 and Theorem 7, all of algebraic operation of those exponential are in S_e . Let $\mathcal{F}(A, N_A, s)$ and $\mathcal{F}(X, N_X, s)$ be real matrix-valued function for A and X , with N_A and N_X are matrices whose entries are in \mathbb{R}_0 . Suppose there are matrices N_A, N_X whose entries are in \mathbb{R}_0 such that $\mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s) \sim \mathcal{F}(A, N_A, s),$ for $s \rightarrow \infty$. If the asymptotic equivalent form in part 4 of Theorem 4 is replaced by $\mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s) \sim \mathcal{F}(A, N_A, s),$ for $s \rightarrow \infty$ then it is obtained that $A \otimes X \otimes A \nabla A$. ■

Theorem 9

Let A and X be matrices over \mathbb{S} . If there are matrices N_A, N_X whose entries are in \mathbb{R}_0 such that $(X, N_X, s) \cdot \mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s) \sim \mathcal{F}(X, N_X, s),$ for $s \rightarrow \infty$ then $X \otimes A \otimes X \nabla X$.

Proof. Let $\mathcal{F}(A, N_A, s)$ and $\mathcal{F}(X, N_X, s)$ be real matrix-valued function for A and X , with N_A and N_X are matrices whose entries are in \mathbb{R}_0 . Suppose there are matrices N_X, N_A whose entries are in \mathbb{R}_0 such that $\mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s) \sim \mathcal{F}(X, N_X, s),$ for $s \rightarrow \infty$. If the asymptotic equivalent form in part 4 of Theorem 4 is replaced by $\mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s) \sim \mathcal{F}(X, N_X, s)$ for $s \rightarrow \infty$ then it is obtained that $X \otimes A \otimes X \nabla X$. ■

The following theorems explain the existence of the balance of matrix over \mathbb{S} , which is similiar to the third and fourth axioms of the Moore-Penrose in conventional algebra.

Theorem 10

Let A and X be matrices over \mathbb{S} . If there are N_A, N_X whose entries are in \mathbb{R}_0 such that $(\mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s))^T \sim \mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s)$ for $s \rightarrow \infty$ then $(A \otimes X)^T \nabla A \otimes X$

Proof. Let $\mathcal{F}(A, N_A, s)$ and $\mathcal{F}(X, N_X, s)$ be real matrix-valued function for A and X , with N_A and N_X are matrices whose entries are in \mathbb{R}_0 . Suppose there are matrices N_A, N_X whose entries are in \mathbb{R}_0 such that

$(\mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s))^T \sim \mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s)$,
for $s \rightarrow \infty$. If the asymptotic equivalent form in part 4 of Theorem 4 is replaced by

$(\mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s))^T \sim \mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s)$
for $s \rightarrow \infty$ then we have $(A \otimes X)^T \nabla A \otimes X$. ■

Theorem 11

Let A and X be matrices over \mathbb{S} . If there are N_A, N_X whose entries are in \mathbb{R}_0 such that

$(\mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s))^T \sim \mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s)$
for $s \rightarrow \infty$, then $(X \otimes A)^T \nabla X \otimes A$

Proof. Let $\mathcal{F}(X, N_X, s)$ and $\mathcal{F}(A, N_A, s)$ be real matrix-valued function for X and A , with N_X and N_A are matrices whose entries are in \mathbb{R}_0 . Suppose there are matrices N_X, N_A whose entries are in \mathbb{R}_0 such that

$(\mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s))^T \sim \mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s)$,
for $s \rightarrow \infty$. If the asymptotic equivalent form in part 4 of Theorem 4 is replaced by

$(\mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s))^T \sim \mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s)$
for $s \rightarrow \infty$ then we have $(X \otimes A)^T \nabla X \otimes A$. ■

The following example illustrates the existence of the matrix balance form in Theorem 8 until Theorem 11.

Example 12

Let A and X be matrices over \mathbb{S} , respectively where $A =$

$$\begin{bmatrix} 1 & 2 & \ominus 1 \\ \ominus 2 & \ominus 3 & 2 \end{bmatrix} \text{ and } X = \begin{bmatrix} -5 & \ominus(-4) \\ -4 & \ominus(-3) \\ \ominus(-5) & -4 \end{bmatrix}.$$

If $N_A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ and $N_X = \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{bmatrix}$ then

$$\mathcal{F}(A, N_A, s) = \begin{bmatrix} e^s & e^{2s} & -e^s \\ -e^{2s} & -e^{3s} & e^{2s} \end{bmatrix} \text{ and } \mathcal{F}(X, N_X, s) = \begin{bmatrix} e^{-5s} & -e^{-4s} \\ e^{-4s} & -e^{-3s} \\ -e^{-5s} & e^{-4s} \end{bmatrix}.$$

Therefore, there are $N_A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$

and $N_X = \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{bmatrix}$ such that

a. $\mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s)$
 $\sim \begin{bmatrix} e^s & e^{2s} & -e^s \\ -e^{2s} & -e^{3s} & e^{2s} \end{bmatrix} = \mathcal{F}(A, N_A, s), s \rightarrow \infty.$

b. $\mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s)$
 $\sim \begin{bmatrix} e^{-5s} & -e^{-4s} \\ e^{-4s} & -e^{-3s} \\ -e^{-5s} & e^{-4s} \end{bmatrix} = \mathcal{F}(X, N_X, s), s \rightarrow \infty.$

c. $(\mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s))^T$
 $\sim \begin{bmatrix} 2e^{-4s} + e^{-2s} & -e^{1s} - 2e^{-3s} \\ -e^{-s} - 2e^{-3s} & 1 + 2e^{-2s} \end{bmatrix}$
 $= (\mathcal{F}(A, N_A, s) \cdot \mathcal{F}(X, N_X, s)), s \rightarrow \infty.$

d. $(\mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s))^T$
 $\sim \begin{bmatrix} e^{-4s} + e^{-2s} & e^{-3s} + e^{-s} & -e^{-4s} - e^{-2s} \\ e^{-3s} + e^{-s} & e^{-2s} + 1 & -e^{-3s} - e^{-s} \\ -e^{-4s} - e^{-2s} & -e^{-3s} - e^{-s} & e^{-4s} + e^{-2s} \end{bmatrix}$
 $= \mathcal{F}(X, N_X, s) \cdot \mathcal{F}(A, N_A, s), s \rightarrow \infty.$

Since A and X satisfy a, b, c and d, then it is obtained that

1. $A \otimes X \otimes A \nabla A$

2. $X \otimes A \otimes X \nabla X$
3. $(A \otimes X)^T \nabla A \otimes X$
4. $(X \otimes A)^T \nabla X \otimes A$. ■

The discussion in Theorem 8 until Theorem 11 were used to show the existence of the matrix balances in order to define the Moore-Penrose inverse in \mathbb{S} .

The following definition explains the Moore-Penrose inverse in the matrix over \mathbb{S} . This definition is defined by modifying the definition of the Moore-Penrose inverse in a conventional matrix, i.e by changing “equals” relation in conventional algebra to “balance” relation in \mathbb{S} .

Definition 13

Let $M \in \mathbb{S}^{m \times n}$. The Moore-Penrose inverse of M is an $n \times m$ matrix M^+ which satisfies

1. $M \otimes M^+ \otimes M \nabla M$
2. $M^+ \otimes M \otimes M^+ \nabla M^+$
3. $(M \otimes M^+)^T \nabla M \otimes M^+$
4. $(M^+ \otimes M)^T \nabla M^+ \otimes M$

Since $X = \begin{bmatrix} -5 & \ominus(-4) \\ -4 & \ominus(-3) \\ \ominus(-5) & -4 \end{bmatrix}$ in Example 12 fulfills the axioms in Definition 13, then X is the Moore-Penrose inverse of $A = \begin{bmatrix} 1 & 2 & \ominus 1 \\ \ominus 2 & \ominus 3 & 2 \end{bmatrix}$.

The discussion of symmetrization of \mathbb{R}_{\max} shows that \mathbb{R}_{\max} is the positive part or zero of \mathbb{S} . Therefore, \mathbb{R}_{\max} is a special case of the symmetrized max-plus algebra, i.e \mathbb{R}_{\max} is a special case of \mathbb{S} . According to Theorem 8 until Theorem 11, the existence of the Moore-Penrose inverse in max-plus algebraic matrix is guaranteed.

Based on the properties of the weak balances, the weak transitive and the reduction of balance in symmetrized max-plus algebra, Definition 13 can be changed into the following definition.

Definition 14

Let $M \in (\mathbb{S}^V)^{m \times n}$. The Moore-Penrose inverse of M is an $n \times m$ matrix $M^+ \in (\mathbb{S}^V)^{n \times m}$ which satisfies

1. $M \otimes M^+ \otimes M = M$
2. $M^+ \otimes M \otimes M^+ = M^+$
3. $(M \otimes M^+)^T = M \otimes M^+$
4. $(M^+ \otimes M)^T = M^+ \otimes M$

According to Definition 14, we can define the Moore-Penrose in max-plus algebra sense.

Definition 15

Let $A \in (\mathbb{R}_{\max})^{m \times n}$. The Moore-Penrose inverse of M is an $n \times m$ matrix $A^+ \in (\mathbb{R}_{\max})^{n \times m}$ which satisfies

1. $A \otimes A^+ \otimes A = A$
2. $A^+ \otimes A \otimes A^+ = A^+$
3. $(A \otimes A^+)^T = A \otimes A^+$
4. $(A^+ \otimes A)^T = A^+ \otimes A$

The balanced inverse of a square symmetrized max-plus algebraic matrix plays a similiar role as an inverse in conventional matrix.

Definition 16 (Balanced Inverse)

Let $A \in \mathbb{S}^{n \times n}$. If there is $B \in \mathbb{S}^{n \times n}$ such that $A \otimes B \nabla I_n$ and $B \otimes A \nabla I_n$ then A is said to be balanced invertible and B is a balanced inverse of A . Furthermore, the balanced inverse of A is denoted by A_{∇}^{-1} .

The balanced inverse of a square matrix in \mathbb{S} can be solved using Definition 1, Definition 2 and the properties of the link between \mathbb{S} with conventional algebra. The following example explains the balanced inverse of square matrix over \mathbb{S} .

Example 17

Let $A = \begin{bmatrix} 1 & 1^* \\ 2^* & 4 \end{bmatrix}$ where $\det(A) = 5 \nabla \varepsilon$. The real matrix-valued function which corresponds to A by the function in (7) is $\tilde{A}(s) = \begin{bmatrix} e^s & e^s \\ e^{2s} & e^{4s} \end{bmatrix}$. Therefore $\det(\tilde{A}(s)) = e^{5s} - e^{3s}$ and $\text{cof}(\tilde{A}(s))^T = \begin{bmatrix} e^{4s} & -e^s \\ -e^{2s} & e^s \end{bmatrix}$

for $s \in \mathbb{R}_0^+$. Since $\frac{\text{cof}(\tilde{A}(s))^T}{\det(\tilde{A}(s))} = \begin{bmatrix} \frac{e^{4s}}{e^{5s}-e^{3s}} & \frac{-e^s}{e^{5s}-e^{3s}} \\ \frac{-e^{2s}}{e^{5s}-e^{3s}} & \frac{e^s}{e^{5s}-e^{3s}} \end{bmatrix}$ then

$$\tilde{A}(s) \frac{\text{cof}(\tilde{A}(s))^T}{\det(\tilde{A}(s))} = \begin{bmatrix} \frac{e^{5s}-e^{3s}}{e^{5s}-e^{3s}} & \frac{-e^{2s}+e^{2s}}{e^{5s}-e^{3s}} \\ \frac{e^{6s}-e^{6s}}{e^{5s}-e^{3s}} & \frac{-e^{3s}+e^{5s}}{e^{5s}-e^{3s}} \end{bmatrix} \sim \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \tilde{I}_2 \text{ and}$$

$$\frac{\text{cof}(\tilde{A}(s))^T}{\det(\tilde{A}(s))} \tilde{A}(s) = \begin{bmatrix} \frac{e^{5s}-e^{3s}}{e^{5s}-e^{3s}} & \frac{e^{5s}-e^{5s}}{e^{5s}-e^{3s}} \\ \frac{e^{5s}-e^{3s}}{e^{5s}-e^{3s}} & \frac{e^{5s}-e^{3s}}{e^{5s}-e^{3s}} \end{bmatrix} \sim \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \tilde{I}_2 \text{ for}$$

$s \rightarrow \infty$.

Consequently, $\begin{bmatrix} 1 & 1 \\ 2 & 4 \end{bmatrix} \otimes \begin{bmatrix} -1 & \ominus(-4) \\ \ominus(-3) & -4 \end{bmatrix} \nabla \begin{bmatrix} 0 & \varepsilon \\ \varepsilon & 0 \end{bmatrix}$ and $\begin{bmatrix} -1 & \ominus(-4) \\ \ominus(-3) & -4 \end{bmatrix} \otimes \begin{bmatrix} 1 & 1 \\ 2 & 4 \end{bmatrix} \nabla \begin{bmatrix} 0 & \varepsilon \\ \varepsilon & 0 \end{bmatrix}$ are

obtained. Since $\begin{bmatrix} 1 & 1 \\ 2 & 4 \end{bmatrix} \nabla \begin{bmatrix} 1 & 1^* \\ 2^* & 4 \end{bmatrix}$ where $\begin{bmatrix} 1 & 1 \\ 2 & 4 \end{bmatrix}$ is a signed matrix in symmetrized max-plus algebra, then $\begin{bmatrix} 1 & 1^* \\ 2^* & 4 \end{bmatrix} \otimes \begin{bmatrix} -1 & \ominus(-4) \\ \ominus(-3) & -4 \end{bmatrix} \nabla \begin{bmatrix} 0 & \varepsilon \\ \varepsilon & 0 \end{bmatrix}$ and $\begin{bmatrix} -1 & \ominus(-4) \\ \ominus(-3) & -4 \end{bmatrix} \otimes \begin{bmatrix} 1 & 1^* \\ 2^* & 4 \end{bmatrix} \nabla \begin{bmatrix} 0 & \varepsilon \\ \varepsilon & 0 \end{bmatrix}$. Therefore, a balanced inverse $A_{\nabla}^{-1} = \begin{bmatrix} -1 & \ominus(-4) \\ \ominus(-3) & -4 \end{bmatrix}$ such that $A \otimes A_{\nabla}^{-1} \nabla I_2$ and $A_{\nabla}^{-1} \otimes A \nabla I_2$ is obtained ■

The following theorem explains that the balanced inverse of A is also the Moore-Penrose inverse of A .

Theorem 18

A balanced inverse of $A \in \mathbb{S}^{n \times n}$ is the Moore-Penrose of A .

Proof. Let A_{∇}^{-1} be a balanced inverse of A . According to Definition 16, it satisfies

$$A \otimes A_{\nabla}^{-1} \nabla I_n \text{ and } A_{\nabla}^{-1} \otimes A \nabla I_n.$$

Consequently, it also satisfies

1. $A \otimes A_{\nabla}^{-1} \otimes A \nabla I_n \otimes A = A$
2. $A_{\nabla}^{-1} \otimes A \otimes A_{\nabla}^{-1} \nabla I_n \otimes A_{\nabla}^{-1} = A_{\nabla}^{-1}$
3. $(A \otimes A_{\nabla}^{-1})^T \nabla (I_n)^T = I_n \nabla A \otimes A_{\nabla}^{-1}$
4. $(A_{\nabla}^{-1} \otimes A)^T \nabla (I_n)^T = I_n \nabla A_{\nabla}^{-1} \otimes A$.

Therefore, A_{∇}^{-1} is the Moore-Penrose inverse of A . ■

According to Example 17, the balanced inverse matrix $A_{\nabla}^{-1} = \begin{bmatrix} -1 & \ominus(-4) \\ \ominus(-3) & -4 \end{bmatrix}$ is the Moore-Penrose inverse of $A = \begin{bmatrix} 1 & 1^* \\ 2^* & 4 \end{bmatrix}$.

Corollary 19

An inverse matrix of $A \in (\mathbb{R}_{\max})^{n \times n}$ is the Moore-Penrose of A .

Proof. Let $A^{\otimes -1}$ be an inverse of A in max-plus algebra sense. It satisfies

$$A \otimes A^{\otimes -1} = I_n \text{ and } A^{\otimes -1} \otimes A = I_n.$$

Consequently, it also satisfies

1. $A \otimes A^{\otimes -1} \otimes A = I_n \otimes A = A$
2. $A^{\otimes -1} \otimes A \otimes A^{\otimes -1} \nabla I_n \otimes A^{\otimes -1} = A^{\otimes -1}$
3. $(A \otimes A^{\otimes -1})^T \nabla (I_n)^T = I_n \nabla A \otimes A^{\otimes -1}$
4. $(A^{\otimes -1} \otimes A)^T \nabla (I_n)^T = I_n \nabla A^{\otimes -1} \otimes A$.

Therefore, $A^{\otimes -1}$ is the Moore-Penrose inverse of A . ■

5. CONCLUSION

The existence of the Moore-Penrose inverse in symmetrized max-plus algebra can be determined using a link between symmetrized max-plus algebra and conventional algebra. The Moore-Penrose inverse in symmetrized max-plus algebra can be defined as that in conventional algebra by replacing “equal” relation by “balance” relation. The balanced inverse is the Moore-Penrose inverse in symmetrized max-plus algebra.

The future research potentially can be done in construction Moore-Penrose inverse using matrix decomposition in symmetrized max-plus algebra.

AUTHORS’ CONTRIBUTIONS

S is a researcher whose research object is symmetrized max-plus algebra and the main researcher in this study. NI and R contributed to drafting and editing the manuscript.

ACKNOWLEDGMENTS

The authors would like to thank all parties related to this research, especially the LPPM-Universitas Jenderal Soedirman which provided research funds under contract No. T/458/UN23.18/PT.01.03/2021.

REFERENCES

- [1] H. Goto, Introduction to max-plus algebra, in: Proceeding of the 39th International Symposium on Symbolic and Algebraic Computation (ISSAC) ’14, Kobe, Japan, 2014, pp. 21-22. DOI: 10.1145/2608628.2627496
- [2] L. Hogben, R. Brualdi, A. Greenbaum, R. Mathias, Hand Book of Linear Algebra, Chapman and Hall, 2007.

- [3] S. Gaubert, Two Lecture on Max-Plus Algebra, Doamine de Voluceau, 1998
- [4] F. Baccelli, G. Cohen, G.J. Olsder, J.P. Quadrat, Synchronozation and Linearity: An Algebra for Discrete Event Systems, Wiley, 2001.
- [5] M. Akian, G. Cohen, S. Gaubert, R. Nikoukhah, J.P. Quadrat, Linear system in $(\max,+)$ algebra, in: 29th IEEE Conference on Decision and Control, Honolulu, USA, 1990, pp. 151-156. DOI: 10.1109/CDC.1990.203566
- [6] S. Boyd, L. Vandenberghe, Introduction to Applied Linear Algebra: Vectors, Matrices and Least Squares, 1st edition. Cambridge University Press, 2018. DOI: 10.1017/9781108583664
- [7] K.M. Prasad, R.B. Bapat, The Generalized Moore-Penrose Inverse, Linear Algebra and Its Application, vol. 165, 1992, pp. 59-69. DOI: 10.1016/0024-3795(92)90229-4
- [8] A. Ben-Israel, T. N. E. Greville, Generalized Inverses: Theory and Applications, 2nd edition. Springer, 2003.
- [9] F.O. Farid, I.A. Khan, Q.W. Wang, On Matrices over an Arbitrary Semiring and Their Generalized Inverses, Linear Algebra and its Applications, vol. 439, no. 7, 2013, pp. 2085–2105. DOI: 10.1016/j.laa.2013.06.002
- [10] R. B. Bapat, K. P. S. Bhaskara-Rao, K. M. Prasad, Generalized Inverses over Integral Domains, Linear Algebra and its Applications, 140 (1990) 181–196. DOI: 10.1016/0024-3795(90)90229-6
- [11] B. De Schutter, B. De Moor, The QR Decomposition and the Singular Value Decomposition in the Symmetrized Max-Plus Algebra Revisited, SIAM Journal on Matrix Analysis and Application, vol. 44, no. 3, 2002, pp. 417-454. DOI: 10.1137/S00361445024039
- [12] R. A. Beezer, A First Course in Linear Algebra, Congruent Press, 2015.