

Novel Sensor Position on Vehicle Wheels

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Abstract. Nowadays, thieves aim for a vehicle's wheel rims because it has the least security among all parts of the vehicle. It can cost up to a thousand ringgit for sports rims especially. Products are available in the market with lug-nut structured key which may help to secure wheel rims. However, they are not that much helpful.

Our wireless electronic wheel security prototype can provide more flexibility and protection that can assists the vehicle owner in unexpected situations.

Another product related to our project would be the TPMS which is in the market now. This product has electronic sensors in the tire valve to detect tire pressure and tread integrity warning but they are difficult to replace or service. In future TPMS could be equipped with predicative road condition system that could assist autonomous vehicle and navigation service provider with warning system. This is not tested due to lack of space and power source of the TPMS system.

We have found a novel solution for the above problem. The novel new placement suggested on a rotation wheel mass of the vehicle will provide ample space, power source and plug and play capability. Our device can perform all four functions - rim security, tire pressure, tire tread and road condition warning system. The accuracy is sufficient for pre-warnings to drivers.

Keywords: Vehicle electronic lug nut · bolt wheel · rim security · anti-theft · TPMS · Tyre · Tire Tread Integrity Monitoring System · Autonomous driver predicative road condition

1 Introduction

A rotating part such as the wheel is the most difficult part to position electronic sensors. For many years now Mechanical Wheel Security (MWS) mode 1 in Table 1 is the preferred choice for car enthusiasts. This anti-theft lug nuts is capable of securing expensive wheel rim from thieves. Many attempts to design an Electronic Wheel Security (EWS) system [1] and [2] resulted in failure of implementation due to un-strategic sensors placement and limited power source availability.

One of the success story of sensor placement on vehicle wheels is the Tire Pressure Monitoring System (TPMS). TPMS is now fitted in the new vehicles produced or even can be installed as after sales kit [5]. But there is a big challenge to the TPMS. As newer applications associated to TPMS are emerging in the market now, example the EWS [2], tire tread integrity monitoring system [9] and autonomous driver predicative road

warnings.

Title, Reference Functionality Method, Image Advantages Drawbacks MWS Structural design of Takes more effort A simple modified lug-nut key lock. and time for theft of tool with a hard wheel with preknock to the lug-nut planed tools needed can open the lug-nut for a success theft. Mode 1 MWS and Structural design of Electronic The electronic EWS monitor [1]. lug-nut key lock. combination system expose to Placement of structural lock with the outside of the battery, wireless high security wheel making them device, PIR distance features and early easy to be tempered. sensor on the hub anti-theft alert The sport rim system. design needs to cap. confine with the wheel cap enclosure limiting the rim beauty. Mode 2 The sensor closes to It is not PnP module EWS monitor [2], Placement of TPMS monitor [3] battery, wireless the subject need to difficult to do monitor making the [4] [5] [6], Tread device, air pressure maintenance. The monitor [7] [8], and sensor and accuracy good. device size is small Road condition accelerometer resulting the battery monitor [9] [10]. inside of the tire. size is small. Not able to do all the function at once. Mode 3 EWS monitor [2], Placement of PnP module and the Placement of TPMS monitor [3] battery, wireless system have large sensors a bit far [4] [5] [6], Tread device, force sensor, space for battery from the subject monitor [7] [8], fly fish sensor and reduce maintenance. needed to be Road condition accelerometer All the function can monitored. But the monitor [9] [10], between break hub be done once in this accuracy good Disk lug nut and wheel rim. location. enough for early

Table 1. Methodology showing how our novel EWMS performance compared to existing devices.

condition [10] all of which incorporate the TPMS. As before TPMS only needs small energy source as most of the time it goes into sleep mode but with this new application it needs bigger energy source and space for components. The TPMS could not install all this due to limited space inside the tire. Any attempt to increase the size would result to tire performance failure.

protector [11] and

our novel EWMS

design.

Mode 4

TPMS success story lead us to design our own novel sensor positioning system - the Electronic Wheel Monitor System (EWMS) that has the similar Plug and Play (PnP)

capability as the TPMS but with much large space for additional features, sensors and energy storage.

2 Research Method

Our first prototype shown in Fig. 1 which is the imitation of mode 2 features a combination. This prototype has flying fish sensor and PIR distance sensor with GSM module. The flying fish sensor could detect if the bolt is turning as bar code strip painted on the bolt. The PIR distant sensor could detect any person or object close to the vehicle tires. This is a 2 stage EWS alert system via wireless GSM to vehicle driver. The prototype developed in Fig. 1 enhanced with replacing the PIR sensor with axial accelerometer and with additional force sensor. Figure 2 show how this new 3 stage EWS wireless GSM alert system works when the car is parked. The accelerometer tested is very sensitive as it could even detect road the vibration of the road due to a heavy vehicle passing. The accelerometer is also used during car drive mode. During this mode it could detect tire pressure, tire tread and tire wobbling alert on dashboard LCD.

Our second design is the novel mode 4 prototype where, now we have transition from a hub cab design of mode 2 and 3 to a unique structural disk design as shown in Fig. 3. This design is more hidden inside, between break hub and wheel rim. Even though it is hidden, it is designed with PnP in mind. Battery maintenance is convenient as it could be done at a interval of 10,000 km mileage where at this time normally a wheel crossing is performed. Furthermore, this design gives ample space for electronic devices compared to a TPMS mode 3 design. TPMS mode 3 design could only perform tire pressure, where else tread monitor and road condition monitor are proposed only to be incorporated in the module. They are not in the market currently due to lack of space for battery. But in our project, we have incorporated them all as shown in Fig. 4. Our system could be fitted

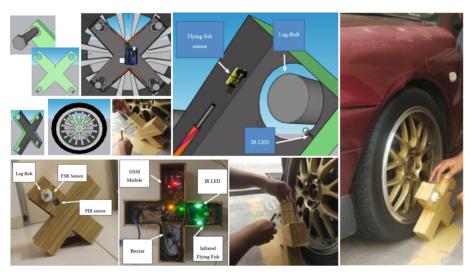


Fig. 1. Hardware construction of our first prototype.

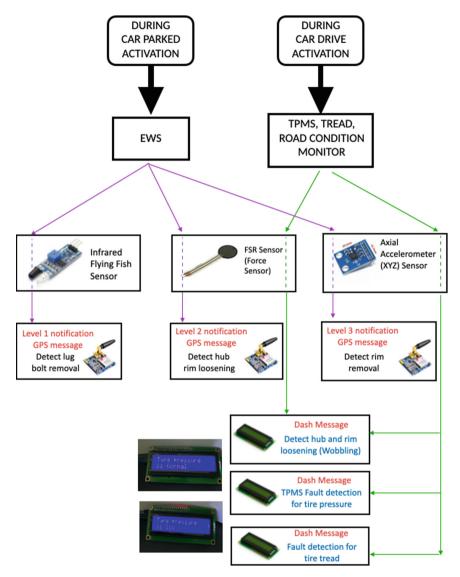


Fig. 2. Flow chart of our EWS system.

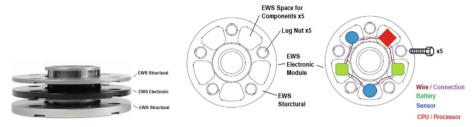


Fig. 3. Shows our second prototype of EWMS disk design.



Fig. 4. Shows hardware our second prototype of EWMS.

in all types of vehicles. The structural disk aluminium alloy cut by the Computerised Numerical Control (CNC) machine, can withstand ambient temperatures of 150 degrees that is produced from the break disks for a short bust. Our EWMS package comes with wireless dash display, EWS disk and a longer anti-theft lug nuts (mode 1). This anti-theft lug nuts gives double security with MWS and EWS incorporated.

3 Results and Analysis

This section shows the results of our novel EWMS. Figure 5 show the average time is taken for a low priority level 1 message is 12 s, medium priority level 2 message is 8 s and highest priority level 3 message is 9 s wireless GSM response. The accelerometer is placed in 45 degrees angle for better data security. Figure 6 shows the accelerometer data when the car is parked still and when wheel rim theft is in progress. Figure 7 show difference between car tire pressure data of the accelerometer.

Number of trials Attempts	Time taken to receive Level 1 Security message (s)	Time taken to receive Level 2 Security message (s)	Time taken to receive Level 3 Security message (s)	± 1610 S € B — EWS SECURITY Today 16.09 Intruder detected level 1	Edit ···			
1	11	7	8	Today 16-10 Intruder detected level 1				
2	12	7	9	Today 16 10 Intruder detected level 1	≤ 1612 S • B − ← EWS SECU			
3	10	8	7	Today 16 10 Intruder detected level 1	Intruder detect	Today 16:11 ed level 2		
4	13	9	10	Intruder detected level 1	Intruder detecti			
5	12	7	10					
6	12	8	9			≤ 16·12 S • □ ··· ← EWS SECURITY	Edit ···	
7	11	8	10			Today 16-12 Intruder detected Level 3 Theft		
8	14	9	10			Confirm!		
9	13	7	9			Intruder detected Level 3 Theft Confirm!		
10	14	8	10					

Fig. 5. Analysis on respond time to receive a text message.

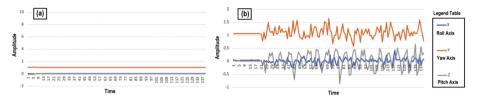


Fig. 6. (a) With movement of rim during parked (b) without movement of rim during theft.

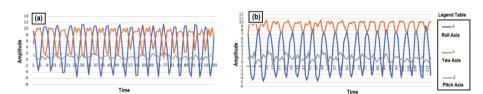


Fig. 7. (a) Normal tire pressure (b) low tire pressure

4 Conclusion

This project is a success as it is able to overcome all hindrances previously experienced by the automotive industry which primarily involves working in a mechanical rotating device (wheel/rim). Our project has the best of both worlds of MWS and EWS incorporated together. There are many applications other than EWS on this rotation area for example TPMS, tire tread integrity monitoring system and autonomous driver predicative road condition. For this project, TPMS is implemented and other ideas could not be fully implemented because the TPMS power system is too small. We have solved all of these hindrances with a simple PnP system that would be the next generation EWMS. Our system is sensitive enough to give early warnings to drivers. Future work suggestion would be to implement the design for heavy vehicles for example trucks and buses.

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