



Racing Car Aerodynamics: Optimising Vehicle Drag Reduction and Downforce Control

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Abstract. This paper presents a comprehensive review of aerodynamic optimisation strategies for modern racing vehicles, with a focus on drag reduction and downforce control. Racing cars operate under extreme performance conditions where aerodynamic forces critically influence stability, acceleration, fuel efficiency, and cornering performance. The paper begins by outlining fundamental aerodynamic principles, such as the roles of drag and downforce, the formation of vortices, and ground-effect phenomena. Advanced simulation methods, particularly Computational Fluid Dynamics (CFD), and experimental techniques such as wind tunnel testing and Particle Image Velocimetry (PIV), are analysed for their effectiveness in evaluating and improving aerodynamic behaviour. The study highlights hybrid development strategies that combine CFD with physical testing to accelerate and validate design iterations. Recent developments in artificial intelligence and machine learning are also explored, demonstrating how surrogate models and data-driven optimisation can enhance simulation efficiency. Case studies from Formula 1, Formula E, and high-performance road vehicles illustrate the implementation of both active and passive aerodynamic control systems. The paper concludes by identifying future directions, including adaptive systems and AI-integrated workflows, as key to unlocking the next generation of race car aerodynamic performance.

Keywords: Racing Car Aerodynamics, Drag Reduction, Downforce Optimisation, Computational Fluid Dynamics, Active Aero Systems

1 Introduction

Aerodynamics plays a foundational role in modern racing car design, where the competing demands of speed, stability, and efficiency must be balanced under extreme conditions [1]. As a vehicle moves through the atmosphere, it is subjected to aerodynamic forces—primarily drag and lift. In racing, drag reduces top speed and energy efficiency, while lift, if not controlled, can reduce tire grip and compromise stability. To address this, engineers have developed aerodynamic strategies that actively reduce drag while generating downforce—negative lift—to enhance vehicle performance [2].

One of the core challenges in racing car aerodynamics lies in the trade-off between downforce and drag. Increasing downforce improves tire grip and enhances braking, acceleration, and cornering capabilities, but also tends to increase drag. Conversely, minimising drag enhances straight-line speed but can reduce cornering performance due to a loss of grip. Engineers must therefore optimise the vehicle's aerodynamic setup according to the demands of each circuit.

The evolution of aerodynamic design in motorsport reflects decades of progress. From the early use of simple airfoils, development has advanced toward complex, multi-element wings, ground-effect tunnels, active flaps, and intelligent control systems [3]. Today, high-performance race cars integrate both passive design elements and active devices to optimise airflow across all regions of the vehicle. Computational Fluid Dynamics (CFD) and wind tunnel testing are used in tandem to evaluate and refine aerodynamic performance across design cycles [4,5].

This paper aims to provide a systematic analysis of modern race car aerodynamic optimisation techniques [6]. The discussion begins with fundamental principles governing drag and downforce, followed by key numerical and experimental methods used in aerodynamic development, including CFD, wind tunnel testing, and hybrid validation workflows [7]. The paper also explores recent advances in artificial intelligence and machine learning that enhance simulation efficiency and predictive capability. Finally, case studies from Formula 1, Formula E, and high-performance road cars are analysed to demonstrate the practical implementation of aerodynamic principles. By unifying these perspectives, this study provides both theoretical insight and engineering guidance for achieving optimal aerodynamic balance in racing vehicle design.

2 Fundamental Aerodynamic Principles in Race Cars

Race car aerodynamic performance is fundamentally governed by two key nondimensional coefficients: the drag coefficient (CD) and the lift coefficient (CL), the latter typically representing downforce in motorsport applications. The drag coefficient quantifies aerodynamic resistance acting opposite to the direction of motion, while the lift (or downforce) coefficient measures the pressure differential that either lifts the vehicle from the surface or presses it downward [8]. In racing applications, negative lift—downforce is intentionally generated using inverted aerofoil profiles, venturi tunnels, and body shaping strategies. Aerodynamic elements such as front and rear wings accelerate airflow over and under their surfaces, creating a pressure differential that results in a net downward force. Diffusers and underbody tunnels further enhance downforce by exploiting the Venturi effect, whereby accelerated airflow beneath the car generates a low-pressure zone that effectively pulls the vehicle toward the track surface.

Increasing downforce improves lateral and longitudinal acceleration capabilities by enhancing tire grip through elevated normal force. This, in turn, leads to better cornering, braking, and acceleration performance—factors widely recognised as critical to lap time reduction in circuit racing. While increased downforce offers performance advantages in corners, it is accompanied by a rise in induced drag, which scales with the square of downforce. Consequently, a fundamental trade-off emerges, maximising downforce improves cornering but penalises top-end speed due to greater drag, whereas reducing

downforce enhances straight-line speed at the cost of cornering stability [9]. Optimal aerodynamic configuration thus depends on circuit characteristics, with high-downforce setups preferred on technical tracks, and low-drag configurations favoured on high-speed circuits.

Aerodynamic drag in race cars originates from both skin friction and pressure drag, the latter arising due to flow separation. The total drag coefficient is defined as $C_D = 2F_d / (\rho v^2 A)$, where F_d is the drag force, ρ is air density, v is velocity, and A is frontal area [10,11]. To minimise drag, race cars utilise streamlined bodywork and flow control devices such as winglets and fairings to reduce separation and manage wake turbulence. At typical racing speeds, turbulent flow dominates. Although turbulence increases skin friction, it can delay flow separation compared to laminar flow, potentially reducing pressure drag. Three-dimensional vortical structures—such as wingtip vortices and corner vortices—commonly form and require precise management using vortex generators, fences, and other flow-guiding features.

A critical aerodynamic innovation in motorsport is the use of ground effect. This technique leverages underbody venturi tunnels to create a low-pressure region beneath the vehicle, substantially increasing downforce with a relatively minor drag penalty. Ground-effect aerodynamics are among the most efficient downforce-generating mechanisms in open-wheel racing cars. However, these systems are highly sensitive to ride height and ground clearance, necessitating meticulous design and suspension integration to maintain consistent performance across varying track conditions.

3 Aerodynamic Optimisation Methods

3.1 Computational Fluid Dynamics (CFD) Techniques

Modern race car aerodynamic development relies extensively on Computational Fluid Dynamics (CFD) to simulate airflow behaviour and guide geometric optimisation. Among the various CFD techniques, Reynolds-Averaged Navier–Stokes (RANS) methods are most employed in industrial and motorsport applications. RANS models compute the time-averaged flow field using turbulence closure models, enabling relatively fast prediction of mean aerodynamic forces such as drag and downforce. This makes RANS particularly suitable for iterative design processes under time constraints [12].

More advanced turbulence modelling approaches, such as Large-Eddy Simulation (LES), resolve large turbulent structures explicitly while modelling the smaller subgrid-scale motions. LES provides rich information on unsteady flow phenomena and vortex dynamics, but incurs significantly higher computational costs, often an order of magnitude greater than RANS. Direct Numerical Simulation (DNS), which resolves all turbulence scales without approximation, remains impractical for full-vehicle simulations due to its prohibitive computational demands at realistic Reynolds numbers. As a compromise, hybrid models such as Scale-Adaptive Simulation (SAS) and Detached-Eddy Simulation (DES) have been developed to balance accuracy and computational efficiency, offering improved resolution of transient vortical structures while maintaining acceptable simulation time.

In practical motorsport engineering, RANS models—especially the SST $k-\omega$ and Spalart–Allmaras formulations—remain the primary tools for simulating aerodynamic forces. These models are widely used to evaluate aerodynamic loads and pressure distributions, particularly in conjunction with rolling-road boundary conditions and rotating wheel models, which are essential for accurately replicating on-track conditions and capturing ground-effect behaviours. Without these considerations, predictions of underbody airflow and diffuser performance would be severely compromised.

CFD enables detailed analysis of surface pressure, flow separation, wake structures, and vortex interactions. It allows engineers to evaluate the aerodynamic impact of modifications to wing camber, endplate geometry, underbody contours, and diffuser angles. High-fidelity simulations help visualise complex flow phenomena such as reattachment and corner vortices, guiding decisions on vortex generator placement and airflow conditioning. However, CFD remains a predictive tool that must be validated through experimental methods. Wind tunnel testing and on-track data collection are essential to ensure model accuracy, particularly when operating in the complex flow regimes associated with ground-effect aerodynamics. Therefore, CFD is best viewed as a complementary tool that augments, rather than replaces, physical testing in competitive race car development.

3.2 Wind Tunnel Testing and PIV

Wind tunnel testing continues to serve as a cornerstone in race car aerodynamic development. In such experiments, either scale models or full-scale vehicles are mounted within a controlled testing environment to directly measure aerodynamic forces. These forces, including drag and downforce (negative lift), are recorded using multi-axis force balances under carefully regulated flow speeds. Modern wind tunnel facilities are often equipped with rolling-road belts and rotating wheel rigs to closely replicate on-track boundary conditions, including relative ground movement and tire-induced flow.

Advanced flow visualisation and measurement technologies are frequently integrated into wind tunnel setups. Among them, Particle Image Velocimetry (PIV) is particularly valuable for capturing high-resolution flow velocity fields. This technique involves seeding the flow with tracer particles and illuminating them with laser sheets to record instantaneous two-dimensional or three-dimensional velocity distributions. Additional techniques, such as pressure-sensitive paint, enable mapping of surface pressure distributions across aerodynamic surfaces [13]. These diagnostic tools allow engineers to analyse wake behaviour, flow separation, vortex structures, and underbody aerodynamics in detail.

One of the key advantages of wind tunnel testing is its ability to isolate specific flow conditions, such as varying yaw angles or simulated crosswind disturbances. This capability is essential for evaluating aerodynamic stability under real-world cornering and side-wind scenarios. Wind tunnel experiments are also instrumental in optimising aerodynamic devices such as gurney flaps, vortex generators, wheel covers, and underbody diffusers. Furthermore, wind tunnel data provide critical validation for

Computational Fluid Dynamics (CFD) simulations, helping to calibrate turbulence models and confirm flow phenomena, such as three-dimensional separation or shock-induced effects, that may not be fully captured in numerical predictions.

In contemporary aerodynamic development workflows, a hybrid approach is typically adopted. CFD simulations are employed to rapidly explore a wide array of design configurations due to their flexibility and lower cost, while wind tunnel tests are used to validate and fine-tune the most promising configurations. Despite the growing capabilities of CFD, wind tunnel testing remains the definitive method for verifying full-vehicle aerodynamic behaviour, particularly in complex ground-effect flow regimes and multi-component interactions. Its continued role is indispensable in the iterative design and validation process within high-performance motorsport engineering.

3.3 Hybrid CFD–Wind Tunnel Approaches

Given that no single aerodynamic analysis method offers complete accuracy and efficiency, a hybrid development strategy is commonly adopted in modern race car design. Typically, the process begins with initial geometry exploration using rapid RANS-based CFD simulations or inverse design methods, which allow quick iteration across a wide design space. Once promising configurations are identified, high-fidelity simulations, such as Large-Eddy Simulation (LES), are applied to critical components, such as the front wing, underfloor diffuser, or rear wing assembly, to resolve complex unsteady flow structures and refine local aerodynamic features.

Following computational refinement, physical validation is conducted through wind tunnel testing. These experimental measurements not only verify the performance of the final design under controlled conditions but also provide reference data to calibrate turbulence models used in CFD simulations [14]. In some cases, feedback from wind tunnel experiments is used to adjust numerical parameters, improving the predictive accuracy of subsequent simulations.

Beyond traditional hybrid workflows, data-driven integration strategies are gaining traction. Some engineering teams now employ regression-based machine learning models trained on wind tunnel force measurements to correct or compensate for systematic errors in CFD predictions. Additionally, in-situ aerodynamic data from embedded pressure sensors during on-track testing can be correlated with CFD output to identify discrepancies and improve model fidelity.

The overarching objective of these hybrid approaches is to combine the computational efficiency and geometric flexibility of CFD with the empirical accuracy of wind tunnel and on-track testing. By leveraging the strengths of both numerical and physical methods, engineers can ensure that aerodynamic optimisations not only perform well in simulation but also translate effectively to real-world vehicle conditions. This integrative method breaks down the reliability and performance of aerodynamic designs in competitive motorsport environments.

4 AI-Enhanced Aerodynamic Optimisation

In recent years, artificial intelligence (AI) and machine learning (ML) have been increasingly integrated into the aerodynamic optimisation workflow. These techniques enable the development of surrogate models—data-driven approximations that predict aerodynamic performance based on prior simulation or experimental data. Once trained, surrogate models, such as neural networks, Kriging models, or polynomial regressions, can estimate key performance indicators like drag and downforce for new geometric configurations with minimal computational cost. This capability facilitates rapid design space exploration and accelerates optimisation processes by reducing reliance on large-scale CFD simulations [15].

Deep learning approaches, including convolutional neural networks and autoencoders, have been successfully applied to predict surface pressure distributions and aerodynamic forces based on vehicle geometry inputs. These models implicitly learn the underlying fluid dynamic relationships from previously generated CFD data, allowing for near-instantaneous evaluation of new shape variants. Such predictive capacity enables more efficient implementation of optimisation algorithms, including genetic algorithms and gradient-based methods.

Furthermore, hybrid approaches have emerged that combine data-driven models with traditional physical principles. Examples include the use of physics-informed neural networks to augment RANS turbulence models and reinforcement learning strategies that adapt aerodynamic devices, such as wings or flaps, in real time based on performance feedback. In the context of ground vehicle aerodynamics, surrogate models have been developed to interpolate airflow behaviour under varying yaw angles, allowing for rapid assessment of crosswind effects [16].

These AI-driven tools represent a transformative shift toward data-enhanced fluid mechanics. By integrating machine learning with physics-based simulations and experimental data, engineers can achieve faster design iterations and uncover novel aerodynamic solutions that may not emerge through traditional methods. Nonetheless, data-driven models must still undergo rigorous validation against physical principles and empirical results. As such, AI serves as a powerful augmentation tool—enhancing, rather than replacing, conventional CFD and wind tunnel techniques within the aerodynamic design process.

5 Case Studies

5.1 Formula 1

Formula 1 (F1) vehicles represent the forefront of aerodynamic innovation, driven by strict regulatory frameworks and the demands of high-speed competition. Among the most notable aerodynamic devices employed in modern F1 is the Drag Reduction System (DRS). This system consists of a driver-activated flap within the rear wing that opens under specified conditions, typically on straights and within a defined proximity to a leading car. When activated, DRS significantly reduces aerodynamic drag, enabling

increased straight-line speed. Once the car approaches a braking or cornering zone, the flap automatically closes to restore maximum downforce and stability. The introduction of DRS was intended to mitigate the inherent trade-off between minimising drag and maintaining high downforce, allowing engineers to optimise both aspects depending on real-time driving conditions.

In addition to active aerodynamic devices, recent Formula 1 regulations have renewed emphasis on ground-effect aerodynamics. Since 2022, F1 cars have reintroduced venturi tunnels along the vehicle's floor to generate the majority of downforce. These tunnels accelerate airflow under the car, creating low-pressure zones that effectively "suction" the car toward the track surface. This strategy shifts downforce production from the wings, traditionally responsible for turbulent wake generation, to the underbody, which offers higher aerodynamic efficiency and reduces sensitivity to disturbed airflow when trailing another vehicle. As a result, cars experience improved stability and reduced wake interference, enhancing overtaking opportunities and race dynamics.

Modern F1 cars also incorporate highly refined aerodynamic components, including multi-element front and rear wings, complex diffusers, and vortex-generating structures such as the Y250 vortex at the junction of the front wing and nose. These components are continuously tuned and optimised using an integrated development process that includes extensive Computational Fluid Dynamics (CFD) simulations and wind tunnel testing. Teams conduct hundreds of simulations and millions of wind tunnel measurements throughout a single season to incrementally refine their aerodynamic packages.

The combination of active systems like DRS and passive devices such as ground-effect floors exemplifies the holistic approach F1 engineers take in managing the drag–downforce trade-off. By strategically leveraging both body geometry and controllable aerodynamic features, modern Formula 1 achieves high-performance outcomes under the constraints of increasingly complex regulatory and physical environments [17].

5.2 Formula E

In contrast to Formula 1, Formula E—an electric single-seater racing series—prioritises aerodynamic efficiency over maximum downforce, driven by the critical need to maximise energy efficiency and battery range. The aerodynamic design philosophy of Formula E reflects its unique performance constraints and energy management strategies. In both Generation 2 (Gen2) and Generation 3 (Gen3) vehicles, designers have deliberately minimised aerodynamic drag by reducing the size and complexity of external aerodynamic components. This is evident in the simplified rear wing structures, often referred to as "split rear wings," or in some cases, the complete omission of rear wings. Instead, aerodynamic performance is concentrated on the underbody, where diffusers and venturi-style floors are optimised to produce sufficient downforce with minimal drag penalty.

Underbody aerodynamic elements, particularly the rear diffuser, play a central role in enhancing airflow beneath the vehicle. These components generate low-pressure regions that contribute to effective downforce while also smoothing wake flow to

reduce overall drag. This configuration not only maintains vehicle stability but also directly supports energy efficiency. Lower drag reduces the propulsion energy required at race speeds, thereby extending battery range—a critical parameter in electric racing.

Energy recovery through regenerative braking further reinforces the importance of drag reduction. Formula E vehicles can regenerate up to 600 kw of energy, representing approximately 40–50% of the energy consumed during a race. Drivers strategically utilise aerodynamic slipstreaming, or drafting, to reduce air resistance while following another vehicle. This allows them to decelerate earlier, coast for longer distances, and maximise regenerative braking effectiveness, all of which contribute to overall race energy efficiency.

Unlike Formula 1, Formula E does not employ drag reduction systems (DRS), as overtaking is facilitated by track layout, energy management strategies, and traction control systems. Most Formula E circuits are temporary urban layouts characterised by tight corners and short straights, which further diminishes the need for high downforce configurations. As such, aerodynamic development in Formula E focuses heavily on reducing drag within a typical operating speed range of 180–240 km/h, accepting lower downforce levels as a trade-off for enhanced range and thermal efficiency.

In summary, the aerodynamic design of Formula E vehicles centres on drag minimisation, efficient underfloor airflow management, and integration with energy recovery systems. The resulting designs feature smaller aerodynamic appendages, flatter bodywork, and highly optimised diffusers to support the series' emphasis on efficiency-driven performance [18].

5.3 High-Performance Road Cars

Many modern supercars and hypercars incorporate advanced active aerodynamic systems inspired by motorsport applications. These systems dynamically adjust aerodynamic surfaces in real time to optimise the balance between drag and downforce based on vehicle speed, braking condition, and driving input. Typically, active aero systems increase downforce at low speeds or during cornering to enhance grip and stability, while reducing drag at high speeds to improve acceleration and top-end velocity. This functional adaptability allows road cars to achieve race-level performance in varying driving scenarios.

Examples of such implementations include the McLaren P1 and Ferrari SF90, both of which utilise hydraulically actuated rear wings. During heavy braking or low-speed manoeuvres, the rear wing elements deploy to high angles, generating increased downforce for enhanced stability. At higher speeds, these elements retract or flatten, acting as drag-reduction devices. More recent models, such as the Ferrari SF90 XX and McLaren P1 GTR, integrate road-legal Drag Reduction System (DRS)-like functionality, enabling low-drag aerodynamic modes during straight-line driving. In addition to wing-based systems, adaptive ride height technologies are commonly employed, wherein the vehicle body or front splitter lowers at high speeds to amplify ground-effect downforce. A notable example is the Bugatti Chiron, which uses "speed hydraulics" to automatically adjust ride height for aerodynamic benefit.

Historically, the development of active aerodynamics traces back to early motorsport experimentation. Notably, the 1968 Porsche 908 featured mechanically linked flaps that responded to suspension movement, adjusting downforce in real time. However, early

implementations in Formula 1 proved structurally unreliable and led to safety concerns. Movable wing systems were subsequently banned after a series of structural failures, including notable high-speed crashes attributed to aerodynamic component malfunction. Today, active systems in production vehicles are electronically controlled, incorporating driver inputs and electronic control unit (ECU) logic into the actuation loop to ensure safe and precise operation.

In conclusion, the adoption of active aerodynamic systems in high-performance road vehicles allows for decoupling the traditional trade-off between drag and downforce. Drivers benefit from high cornering grip and enhanced braking performance at low speeds, alongside reduced aerodynamic resistance during high-speed driving. This technology, when integrated with rigid chassis structures and high-output powertrains, enables performance capabilities that were once exclusive to top-tier racing machines, further blurring the line between road and track engineering [19].

6 Conclusion

Race car aerodynamics continues to evolve at the intersection of fluid dynamics, computational modelling, and adaptive control. Across various platforms—Formula 1, Formula E, and high-performance road vehicles—engineers aim to optimise the trade-off between drag and downforce to maximise overall performance. This study has reviewed the core aerodynamic principles that govern vehicle behaviour, including the drag coefficient, pressure distribution, flow separation, and the impact of ground effect.

A wide range of optimisation methods has been discussed. Traditional tools such as RANS-based CFD and wind tunnel testing provide essential frameworks for evaluating aerodynamic performance. Meanwhile, higher-fidelity simulations like LES offer insight into unsteady flow structures at the cost of greater computational demand. Hybrid CFD-CFD-CFD-experimental workflows are now standard, allowing fast iteration and validation. Furthermore, the integration of machine learning tools—including surrogate models and reinforcement learning—has added a new dimension to aerodynamic design, enabling rapid exploration of complex design spaces and real-time aerodynamic adjustment.

The application of these strategies was demonstrated through case studies in Formula 1, where devices such as Drag Reduction Systems and ground-effect tunnels balance performance across varying track conditions. In Formula E, aerodynamic design emphasises low drag and energy recovery to enhance battery range and efficiency. High-performance road cars integrate active aero systems inspired by motorsport to deliver adaptable performance for both high-speed and cornering scenarios.

Despite this progress, challenges remain. Designing aerodynamic components that function optimally under real-world conditions requires balancing performance, structural integrity, cost, and safety. The sensitivity of ground-effect systems to ride height, the validation of AI-driven predictions, and the integration of adaptive aero with vehicle dynamics all require further investigation.

Looking forward, the future of race car aerodynamics will likely involve greater reliance on AI-augmented design, shape-morphing surfaces, and real-time control systems. As simulation fidelity improves and sensors provide more in-situ data, the convergence of digital and physical testing will lead to more responsive, efficient, and

high-performing aerodynamic solutions. Ultimately, the iterative loop of simulation, experimentation, and on-track validation will continue to drive innovation and performance in competitive motorsport environments.

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