

Hybrid Differential Evolutionary Algorithms for Koblitz Elliptic Curves Generating

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Abstract—Elliptic curve cryptography(ECC) is one of the most important public key cryptography. The koblitz curve is a special kind of elliptic curve in ECC. The elliptic curve cryptosystem (ECC) which is based on elliptic curve discrete logarithm problem. As of today the security of an ECC is determined by the cardinality of $E(F_q)$ (the set of rational points of E over F_q). Based on the hybrid differential evolutionary algorithms and the evolutionary cryptography theory, we proposed a new algorithm to generate secure Koblitz ECC. Traveling Salesman Problems (TSP) is the well-known combinatorial optimization problem. And the optimal solution can not be found in polynomial time. So the approximation algorithm with polynomial algorithm for TSP has been an important topic in this field. PODE was proposed for TSP by incorporating Position-Order Encoding(POE) into DE. PODE is effective for small-size TSP and less effective for middle-size TSP. We develop a new hybrid differential evolution algorithm, which improves PODE by using hill-climbing operator as the local search algorithm, is proposed for middle-size TSP. The experimental results show that the generation efficiency of secure curves generated is superior to the parameters recommended by NIST.

Keywords—Koblitz elliptic curve; Differential Evolutionary; Hybrid Differential Evolutionary; Evolutionary Cryptography; Elliptic Curves Generating

I. INTRODUCTION

The elliptic curve cryptosystem (ECC) which is based on elliptic curve discrete logarithm problem was proposed by Neal Koblitz[1] in 1987. It has advantage of high security, small occupied bandwidth and low computational complexity, so it has gradually been included in standard recommended by IEEE, ANSI, ISO, NIST etc. Especially, 15 curves recommended by NIST have been frequently chosen by the engineering applications.

Cloud-Computing[2] developed rapidly in recent years, The hacker can easily get high-performance computing ability with the cloud-computing open service and powerful computing ability to attack a cryptosystems. So it is necessary to search a new method to easily and quickly generate secure ECC curves. The secure level

should be higher than the current secure curves recommended by NIST.

In 2002, Zhang Huanguo et al. proposed the Evolutionary cryptography theory[3]. Evolutionary cryptography theory becomes a principal concept for cryptography design and cryptanalysis. Based on the hybrid differential evolutionary algorithms, we proposed a new algorithm to generate secure Koblitz ECC. The experimental results show that the generation efficiency of secure curves generated are superior to the parameters recommended by NIST..

II. KOBLITZ ELLIPTIC CURVES

The Koblitz elliptic curve is a curve defined in domain F_2 , its definition is as follows:

$$E_0 : y^2 + xy = x^3 + 1 \quad (1)$$

$$E_1 : y^2 + xy = x^3 + x^2 + 1 \quad (2)$$

That is to say, $a=1$ or $a=0$. When l is a factor of m , then $E_a(F_l)$ is a subgroup of $E_a(F_m)$, so $\#E_a(F_m)$ can be divided exactly by $\#E_a(F_l)$, we know that $\#E_0(F_2) = 4$ and $\#E_1(F_2) = 2$, we can easily obtain that $\#E_0(F_{2^m})$ is the multiple of 4, and $\#E_1(F_{2^m})$ is the multiple of 2.

In 2000 NIST FIPS 186-2[4] recommended 5 security Koblitz ECs in domain $F(2^{163})$, $F(2^{233})$, $F(2^{283})$, $F(2^{409})$ and $F(2^{571})$. At present, secure ECs selecting methods can be divided into two kinds: complex multiplication (CM) method and random curve selection method. The security of EC depends on the size of the EC order. The common methods for computing order include Schoof's algorithm[5], SEA (Schoof-Elkies-Atkin) algorithm[6], Satoh algorithm[7] and so on.

Overall, there is no better method proposed in recent years. The SEA algorithm is still the most secure but time-consuming method and the traditional pure mathematics severely restricts the development of ECC. So we need to

search for other new methods. We design an hybrid differential evolutionary model for searching safe general field by referring the application in TSP (Traveling Salesman Problems).

III. THE PROPOSED HYBRID DIFFERENTIAL EVOLUTIONARY ALGORITHMS(HDE)

Differential Evolutionary Algorithm(DE)[8] is a new evolutionary computational method proposed by Storm in 1995.PODE[9]was proposed for TSP by incorporating Position-Order Encoding(POE) into DE. POE is effective for small-size TSP and less effective for middle-size TSP. A new hybrid differential evolution algorithm, which improves POE by using hill-climbing operator as the local search algorithm is proposed for middle-size TSP. It is composed of two steps.

Step1. The use of POE

Firstly, Generate initialize population $\{X_{i0}|i=1, \dots, NP\}$.

Secondly, use the operation of mutation, crossover and selection, respectively. The rules of mutation are described by the following equations:

$$V_{i,g} = X_{r_1,g} + F \times (X_{r_2,g} - X_{r_3,g}) \quad (3)$$

Where the indices r_1, r_2 and r_3 are uniformly chosen from the set $\{1, 2, \dots, NP\} \setminus \{i\}$, are distinct integers. F is mutation factor which is fixed parameter.

The rules of crossover are described by the following equations:

$$u_{j,i,g} = \begin{cases} v_{j,i,g}, & \text{if } \text{rand}(0,1) \leq CR \text{ or } j = j_{rand} \\ x_{j,i,g}, & \text{otherwise} \end{cases} \quad (4)$$

Where $\text{rand}(0,1)$ is uniform random number on the interval $[0,1]$, j_{rand} is an random integer chosen from 1 to N and new for each i and the crossover probability CR is a fixed parameter.

The rules of selection are described by the following equations:

$$X_{i,g+1} = \begin{cases} U_{i,g}, & \text{if } f(\text{Ord}(U_{i,g})) < f(C_{i,g}) \\ X_{i,g}, & \text{otherwise} \end{cases} \quad (5)$$

Step 2 the use of Hill-Climbing operator

Before the Hill-Climbing operator, we need the Position-Order Operator: At generation g , this operator creates a solution $C_{i,g}$ for TSP based on the current population $\{X_{i,g}|i=1, 2, \dots, NP\}$ in DE. The following is the form of position-order operator.

$$C_{i,g} = \text{Ord}(X_{i,g}) = (\text{Ord}(x_{1,i,g}), \text{Ord}(x_{2,i,g}), \dots, \text{Ord}(x_{N,i,g})) \quad (6)$$

where, $\text{Ord}(x_{j,i,g})$ is the index of the element $x_{j,i,g}$ after all the elements in vector $X_{i,g} = (x_{1,i,g}, x_{2,i,g}, \dots, x_{N,i,g})$ are sorted from small to large.

Based on experimental evidence, we believe that DE with Position-Order operator performances poorly when solving middle-size TSP. In view of local search algorithm improving the solutions for TSP[10], a new hill-climbing operator is proposed to improve DE with position-order operator. In the hill-climbing operator, the neighborhood of the current solution is generated and the better of the two solutions is preserved for every iterative. In order to get the neighborhood solution, swap operator, reverse edge operator and insert operator are used in hill-climbing operator.

a) Swap Operator:

The operator generate the neighborhood solution by reversing the cities of two locations in the current solution for TSP.

b) Reverse Edge Operator:

The operator generate the neighborhood solution by swapping the order of two edges in the current solution for TSP. The neighborhood is the solution after reversing edge. Edges is served as the operation object in Reverse Edge operator. So it causes large change of the current solution.

c) Insert Operator:

The operator generate the neighborhood solution by inserting the city with the specified location into another specified location in the current solution for TSP.

Based on the above three operators, the algorithm of hill-climbing is shown as following (Algorithm 1.).

Algorithm 1: The Algorithm of Hill-climbing

1	X= a feasible solution of N cities	12	if $f(X_{-1}) < f(X)$ then
2	$j_{-1} = \text{randint}(1, 2N/3)$	13	$X = X_{-1}$
3	for $j = j_{-1}$ to $j_{-1} + N/3$	14	else
4	for $k = 1$ to N	15	$X_{-1} = \text{Insert}(X, m_1, m_2)$; // insert operator
5	$X_{-1} = \text{Swap}(X, j, k)$; // swap operator	16	if $f(X_{-1}) < f(X)$ then
6	if $f(X_{-1}) < f(X)$ then	17	$X = X_{-1}$;

7	$X=X_1;$	18	end
8	end	19	end
9	$m_1=\min(j,k);$	20	next k
10	$m_2=\max(j,k);$	21	next j
11	$X_1=ReverseEdge(X,m_1,m_2);$	22	return X;

Hybrid differential evolutionary algorithm is composed of two steps: firstly DE with position-order operator is called as a global optimization algorithm; secondly hill-

climbing operator is called on the basis of the solution gotten from the first step. The pseudo-code of HDE is shown as following(Algorithm 2.).

Algorithm 2: The Algorithm of HDE

	//first step:PODE	11	$X_{i+1,g}$
1	generate initialize population $\{X_{i,0} i=1,\dots, NP\}$	12	$C_{i+1,g}=C_{i,g}$
2	$C_{i,0}=Ord(X_{i,0}) \{i=1,\dots, NP\}$	13	end
3	for g=0 to max_iterations	14	next i
4	for i=1 to NP	15	next g
5	$V_{i,g}$ gotten from $\{X_{i,g} i=1,\dots, NP\}$ DE mutation		//second step: HillClimbing operator
6	$U_{i,g}$ gotten from $\{X_{i,g}, V_{i,g} i=1,\dots, NP\}$ //DE crossover	16	for i=1 to NP
7	if $f(Ord(U_{i,g})) < f(C_{i,g})$ then //DE selection	17	$New_C_i=HillCliming(C_i, max_iterations)$
8	$X_{i+1,g}=U_{i,g}$	18	next i
9	$C_{i+1,g}=Ord(U_{i,g})$	19	$C_{best}=\text{the best from } \{New_C_i i=1 \dots NP\}$

IV. THE EXPERIMENTAL RESULT AND ANALYSIS

PC:T5450@1.66GHz 1.67GHz, RAM:3.0G, HDD:500G.

Software platform: Matlab 2013b.

In our experiments, we employ the same selecting standards recommended by the ANSI[27],so it is secure enough for our elliptic curves.

we search secure base fields for both kinds of the Koblitz ECs over $[2^{160}, 2^{600}]$, and we obtain the secure EC base field exceeding 571 bit.

As the kind of $a=0, b=1$ Koblitz ECs, we find a total of 15 secure base fields:5,7,13,19,23,41,83,97, 103, 107, 131,239,349,409,571. There are four base fields whose size goes beyond 163. For the kind of $a=1, b=1$ Koblitz ECs. we find a total of 15 secure base fields:5,7,11,17,19,23,101,107,131, 163,283,311,359. There are 4 base fields whose size goes beyond 163. Here we list the specific parameters of the Koblitz elliptic curve in domain $F(2^{163})$, $F(2^{233})$, $F(2^{409})$ and $F(2^{571})$ in Figure 1.

Figure 1. the specific parameters of the special Koblitz elliptic curve .

a,b,	m	p(t)	n	Gx	Gy
a=0, b=1	233	$t^{233}+t^{74}+1$	345087317339528189371737713 85127605709409888622521263 28087024741343	0X1CD4147A6FF9F38FD22AA 837A7CAA837A7C779FC97BF9 96D22F9E73E4B0424F66C3	0X16920A80536B1CC4792B1611 C0A78D79F7823CFDBAEBF0CB FBC940DF423
	409	$t^{409}+t^{87}+1$	330527984395124299475957654	0X1067E7B22DAB059BD122D	0X4EEE2AB519E518A978E5A35

		1	016385519914202341482140609 642324395022807112892491910 506732584577774580140963665 906177315867	14C49E14A008D3C926ED4DC1 05F0C2B65985099A11B97C200 A43F6F465F7A4A8F6A3A9121 BD71B614	E7B72F96C787E15F92FC6AA72D 9DE68B3E2A0ED1AEC286D67B3 C24AC71494DF34E381D67BDBF E2A
	571	$t_{71}+t_{10}+t_5$ $+t_2+1$	193226876150862917234767594 546599367214946366485321749 932861257257595711447802122 681339785227067067118347067 128008253514612736749740666 173119296824216170925035557 33685276673	0X69E202A15A4739E0FEEECD A1B171AB07AC08EC36369770 18FCF52D2BF797DFD9E2919E EA9541D832EE8E37DDC92700 379F5CBDBF1468B63582FECA BDADA8AD94A21EF894D82F4 54	0X28C3E1D87E305274B9AC6279 532E328BE6A607CAB089FC3430 08E22E46E9ADD451DFCBF8798 E765A44340D9195B0DBE98B08B 95D7377AF5B0EBDD1CF13DAD 6DC8A3D5EA7FF0A71
a=1, b=1	163	$t_{163}+t_7+t_3$ $+1$	584600654932361167281474175 3598448348329118574063	0X6243C77BD6DACAC2D474C 9CF4E30725773B777EB8	0X3E996C6AB516545F86D4B7C EE7633B358C5F793D9

V. CONCLUSIONS

we proposed a secure curve selection algorithm based on Hybrid differential evolutionary algorithm to select secure base field of Koblitz elliptic curves. We have preliminarily completed base field and base point generating experiment for koblitz elliptic curve over[2163,2600]. The experiment results contain the 4 Koblitz elliptic curves recommended by NIST.

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