

DCU development of diesel engines under V-type procedure

Cao Lin^{1,a}, Fan Wei^{1,b}, Yue Guangzhao^{2,c} and Lei Yan^{3,d}

¹Shipbuilding information center of China, Beijing 100012, China

²College of Environmental and Energy Engineering, Beijing University of Technology, Beijing 100124, China

³Institute of Engineering (Baotao), College of Engineering Peking University, Baotou 014030, China

^aemial: 18504725480@163.com, ^bemial: 13811445560@139.com, ^cemial: leiyan@bjut.edu.cn, ^demial: leiyan@bjut.edu.cn

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Abstract. Aimed at the selective catalytic reduction (SCR) system, an electronic control unit (DCU) was developed under V-type procedure. Development of DCU software and hardware were carried out simultaneously, shortening largely the development cycle. The self-developed DCU, integrated with Bosch SCR system, has a high NO_x conversion efficiency without ammonia leakage, reaching almost 90% at mid and high engine load.

Introduction

The air pollution produced by nitrogen oxides, which comes from stationary and mobile combustion sources, has become a worldwide environmental problem [1][2][3][4]. For diesel engines, applying optimization technology in cylinders can not meet more stringent emission regulations any longer. After-treatment devices are equipped to largely reduce nitrogen oxides in exhaust gases. The application of SCR has been widely used in diesel engines [5]. The principle of SCR system is spraying aqueous urea solutions into the exhaust pipe of the diesel engine, reacting with nitrogen oxides and making it into harmless nitrogen and aqueous vapor [6][7]. The conversion efficiency of nitrogen oxides has its limit which is determined by the temperature of the catalyst and space speed. Therefore, the amount of aqueous urea should be enough to reduce nitrogen oxides, meeting harsh emission regulation limit. At the same time, usage dosage should not be excessive to cause ammonia leakage [8]. Therefore, the dosing strategy of aqueous urea solutions is an important part of DCU control algorithm.

DCU is a key component in the SCR system, especially its control algorithm. In this paper, a DCU was developed under V-type procedure. Comparing with the traditional development mode, V-type development is of more advantage. V-type development is model-based, which is able to verify control algorithm in the early development. Development of DCU software and hardware are synchronous, shortening the cycle of the whole DCU development.

V-type procedure

Fig. 1 shows the V-type development procedure of SCR in diesel engines. The first step is to define the functions of the SCR system, which is the control object. Secondly, development of DCU software and hardware are carried out simultaneously. The verification of DCU software algorithm is completed on rapid control prototype (RCP). The prototype PROtroniC is used in this paper, in which Matlab/Simulink 2012b is embedded. Thirdly, the code of DCU software algorithm is generated by using RTW tool in Matlab. With adding hardware drive code and manual amendment, the tool generated code can be download into DCU. Fourthly, DCU is tested in-the-loop on a testing platform. At last, experiments are conducted on the engine test bench.

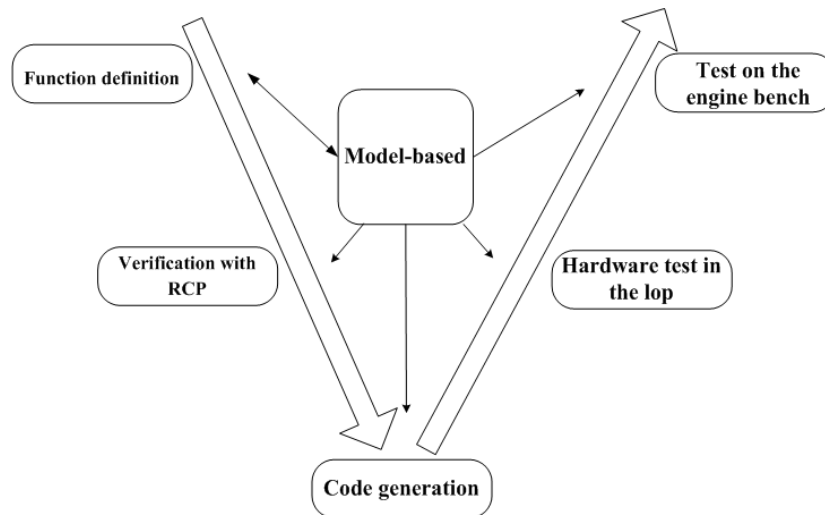


Fig. 1 block scheme of V-type procedure

DCU function definition

The function of DCU is shown in Fig. 2. The input of DCU are sensor signals in SCR system and signals acquired from ECU through CAN bus. Sensors mainly include urea pump pressure sensor, exhaust gas temperature sensors before and after SCR converter, urea temperature sensor and urea liquid level sensor. Signals acquired from ECU are engine speed, torque, air intake temperature and pressure, exhaust gas mass flow, etc. The output of DCU is electric driving to several actuators, including the urea nozzle, the urea pump, return valve and heating relays of the urea tank, the urea pump, the urea nozzle and urea pipes. The main chip of DCU adopts Freescale microcontroller MC9S12XS256. The DCU circuit includes power drive circuit, input signal process, CAN communication and electric drive modules.

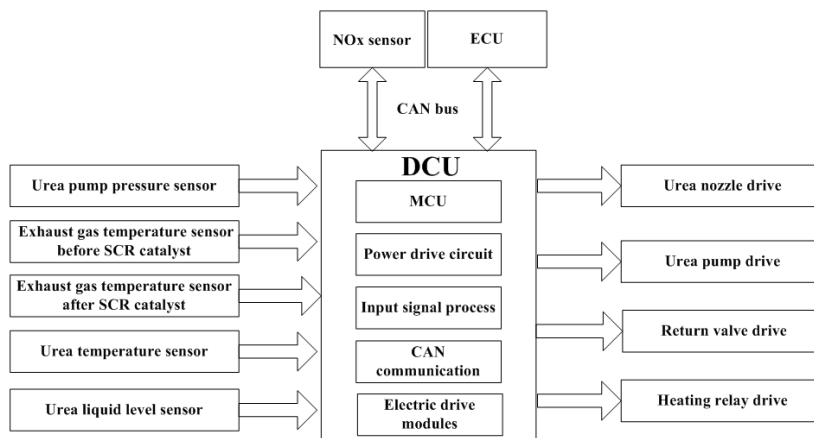


Fig. 2 block scheme of DCU functions

Software development

DCU software is developed based on Matlab/Simulink. The control strategy is completed in form of Simulink modules, including signal input process, signal output control, urea injection strategy and urea injection control. The function of injection strategy includes original NOx emission acquired through look-up table, required ammonia and urea mass flow calculation, the NOx conversion efficiency of the SCR catalyst estimation, etc. The function of urea injection control

mainly includes dew point detection, operating state coordinate of SCR system, urea pressure control of the urea pump, control of the urea injection and the heating system, etc.

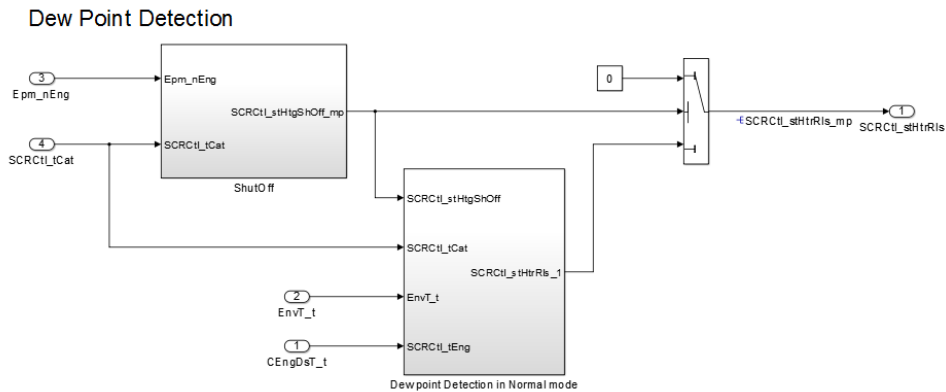


Fig. 3 Simulink module of dew point detection

Fig. 3 shows the simulink module of dew point detection. After engine cold starts, there is a risk that the NOx sensor ceramics, which is heated at 800°C is damaged or destroyed by condensing water droplets due to thermal shock. Depending on catalyst temperature and exhaust gas mass flow, the function of this module decides whether droplet formation in the exhaust gas system can be expected and supplies the release bit for NOx sensor heating which is the output block of this module 'SCRctl_stHtrRls'.

Hardware development

DCU hardware is developed simultaneously as software development. In the following, urea nozzle drive is introduced, which is the most important drive module in the DCU circuit.

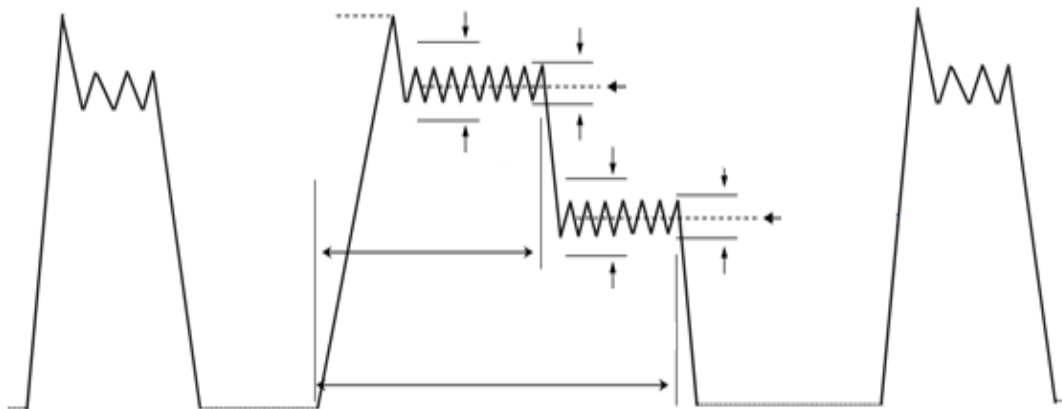


Fig. 4 Current flow of urea nozzle

The urea nozzle drive module is composed of high-end drive and low-end drive. The current flow of urea nozzle is shown in Fig. 4. In order to control accurately the peak current and the hold current, the urea nozzle drive adopts two periods of high-end drive. One is to make the current reaching the peak current in a short time, the urea nozzle opening quickly. The second is to achieve the hold current accurately, controlling the opening time of the urea nozzle.

In DCU circuit, UA9 chip is used to acquire such current to drive the urea nozzle. The peripheral circuit of the chip UA9 is shown in Fig. 5. Fig. 6 shows DCU physical picture.

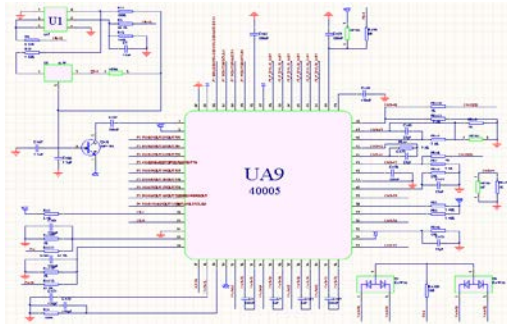


Fig. 5 the peripheral circuit of the chip UA9



Fig. 6 DCU physical picture

In this paper, the prototype PROtroniC is used to verify the control strategy of DCU. The control strategy is embodied in the Simulink model, implementing the function of the SCR system. The model is divided into many sub-models for different functions. Upon completing one sub-model, verification of the sub-model with PROtroniC is conducted. If error existing, the model is modified promptly. Such developing mode removes error of DCU strategy quickly and shortens DCU development cycle. Using the RTW tools to generate code from the Simulink model, which can be downloaded to DCU hardware after manual amendment and adding hardware drive code.

Experiments on the engine test bench

To test the NO_x treatment of the DCU developed in this paper, a test rig was constructed (see Fig. 7). Weichai WP 10 diesel engine was used. Table 1 shows the detailed engine specifications. The SCR system adopted Bosch product, only DCU was self-developed.

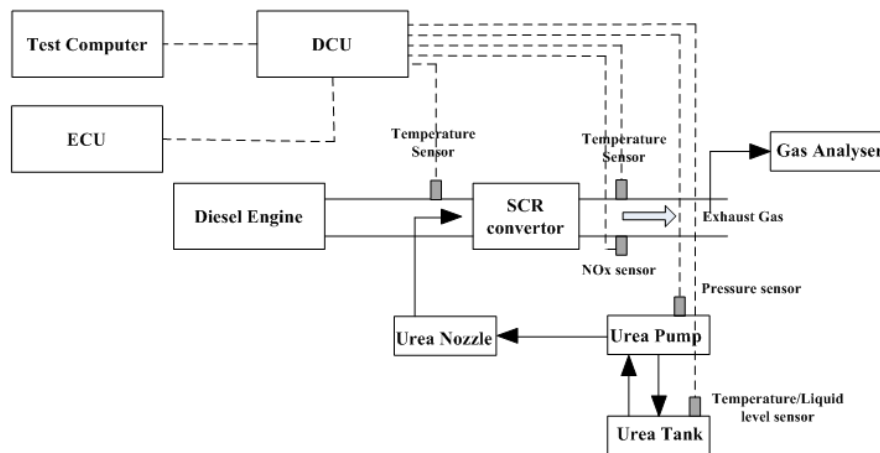


Fig. 7 Schematic of diesel engine test rig

Table 1 Engine specification

Property	Value
Number of cylinder	6
displacement L	9.726L
Rated power (kW)/(rpm))	247/2200
Maximum torque ((Nm)/(rpm))	1250/1200-1600
Air intake	Turbocharged, intercooled

At the engine test bench, a series of tests under various operating conditions were conducted. A NO_x sensor was seated on the exhaust gas pipe after the SCR converter to measure NO_x emission

after treated by the SCR system. The NO_x emission of the engine is acquired through a look-up MAP which is determined mainly by the engine speed and torque. In this paper, the NO_x conversion efficiency is calculated based on the NO_x emission of the engine and that after the SCR converter. The gas analyser measured the NH₃ emission, which is caused by excessive urea dosage.

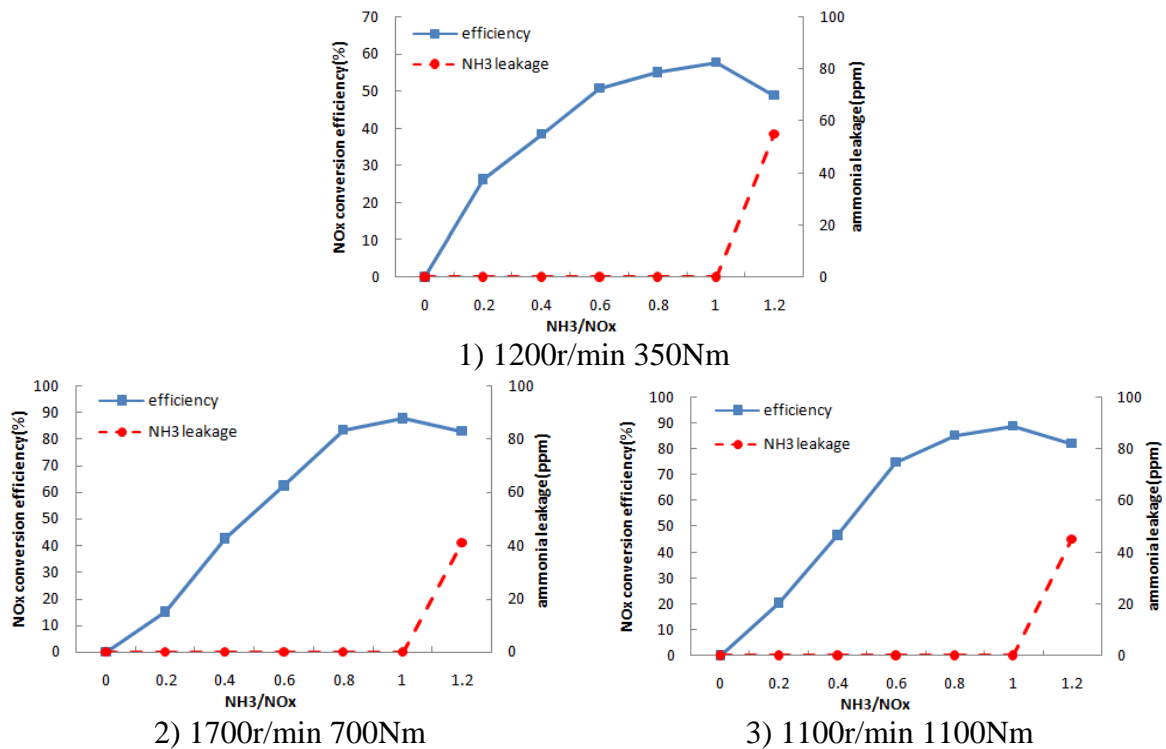


Fig. 8 the NO_x conversion efficiency under three different operating conditions

As shown in Fig. 8, experiments under three different operating conditions were conducted. As urea injection amount increasing, the ratio of NH₃ hydrolyzed by urea to NO_x emission of engine increases. The NO_x conversion efficiency gets higher as the ratio of NH₃ to NO_x increases from 0 to 1. After the ratio of NH₃ to NO_x getting bigger than 1, NH₃ leakage occurs and the NO_x conversion efficiency decreases. In fact, the NH₃ dosage is excessive and the SCR converter gets maximum capacity for reducing NO_x emission. Because the NO_x sensor is cross-sensitive for NH₃, the NO_x conversion efficiency decreases as NH₃ leakage occurs. Therefore, the maximum of NO_x conversion efficiency is obtained at the ratio of NH₃ to NO_x reaching to 1. From Fig. 8, it is found that the NO_x conversion efficiency can reach 57% at 1200r/min, 350N.m and almost 90% at the other two operating condition. That is because the NO_x conversion efficiency of the SCR converter is mainly determined by the SCR temperature. At the operating condition of 1200r/min, 350N.m, the temperature of exhaust gases before the SCR converter is 260C, which is measured by the temperature sensor before the SCR converter. And at the operating condition 2 and 3, the temperature reaches to 400C and 490C, respectively. Therefore, the NO_x conversion efficiency at middle and high engine load can gets a high level, approximately 90%.

Conclusions

This paper developed a DCU under V-type procedure. The DCU developed in this paper, integrated with Bosch SCR system, has a high conversion efficiency in NO_x treatment, reaching almost 90% at middle and high engine load.

Acknowledgement

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