

A design of pulse condition simulation device based on squeeze mode

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ABSTRACT: With a view to the fact that the traditional Chinese medicine (TCM) pulse diagnosis learning is difficult, which takes a lot of time as well, and the current pulse simulation device is expensive, it is hard to popularize the device to help the TCM teaching and learning. In this paper, bionics, mechanics, hydraulic systematic, computer technology and sensor technology will be integrated to design a new pulse simulation device with low cost and high precision, which successfully simulates several types of human pulse. In the meantime, an auxiliary developed software will be introduced in the teaching, learning and examination of pulse diagnosis. The project has got great achievement that it has high value of practical application and great prospects, and will help to advance the development of education and research of TCM as well.

Introduction

In normal TCM pulse-taking teaching, the essential features of the human pulse patterns are described in detail. However, the course provides students with little practical experience, which has been a defect in the succession of traditional Chinese medicine. So developing pulse condition simulators has become a hot issue among TCM researchers. There are two essential types of pulse condition simulation system in China and abroad[1-6]. One is to simulate the effect of pulse condition using hydraulic pressure system, and the other is to simulate it using the vibrations produced by mechanical structure. While those systems gradually improved the precision of the simulation to human pulse after considering fully of its device features, the intelligence of the pulse condition simulation still need to be improved and the cost still need to be reduce. This paper introduce a new design of pulse condition simulation instrument used in teaching with low cost and high precision after doing market survey roundly. It combines all these merits but does not have the defects. It will benefit to shorten time of learning feeling pulse, reduce the learning curve of TCM and increase efficiency of studying TCM and the skills of feeling pulse. It will also be conducive to the development of sphygmology and scientific investigation.

The design of the system

This is a design of low-power and intelligentized pulse simulation (shown in Figure 1), established on the basis of physiology and Chinese medicine, fused with the technology of modern medical signal detection, computer, and the subject of flushbonading, mechanical, hydromechanics. The simulation platform of heart and meridian blood circulation system are designed to use micro controller unit(MCU) to imitate cardiac automaticity, use the bladder with liquid(the bladder will be named artificial blood chamber) with the help of mechanical structure and pump to imitate heart, and use check valve to imitate the membrane flap of heart and stop the liquid to flow backwards. Moreover, a small size of latex tube is used to imitate blood vessel. When the system works, the pump provides the power of flowing back, and the power plant squeeze artificial blood chamber, producing a variable hydraulic pressure as a result, and the hydraulic pressure flow through the hydraulic system and pour into imitate blood vessel, making the artificial blood vessel filling or shriveled, consequently, producing the simulative pulse. Furthermore, to make the education of pulse-taking more visualized and intelligentized, a visible and manageable upper-computer software, which is based on LabVIEW, is written to show pulse waveform and realize the function of test on-line.

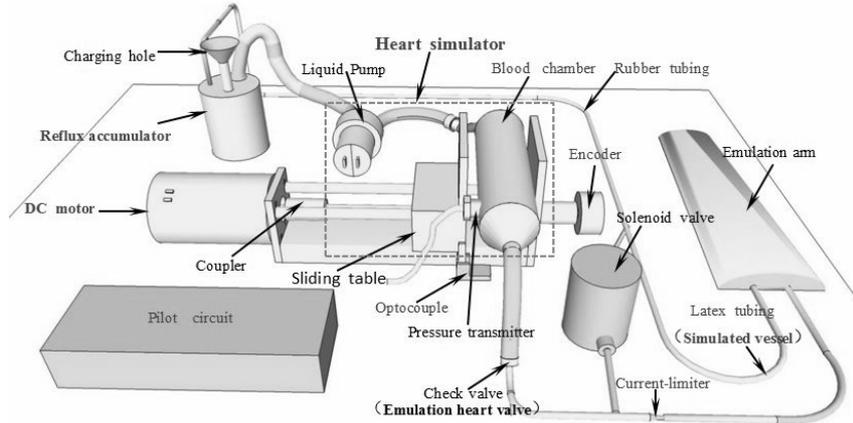


Figure 3. System hardware structure

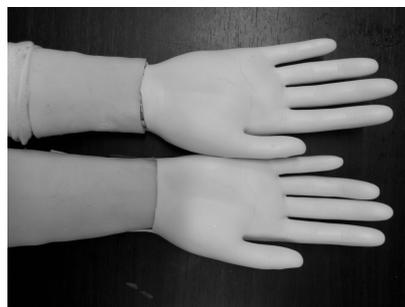


Figure 4. Artificial hand

Pint-sized hydraulic system

Hydraulic system, including the micro pump, the artificial blood chamber, magnetic valve, liquid storage tank and rubber hoses which connect all parts of the hydraulic system, is a key part for simulating the system of heart and meridian blood circulation system. Specially, the artificial blood vessels inside the artificial hand is made of soft and small latex tube [1, 3, 5]. All parts of the hydraulic system is connected into a ring. The check valve is adopted to simulate the human heart periosteal flap, so the liquid can only flow in one direction. What's more, the flow rate of liquid is under control by the flow limited component, which can realistically simulate the heart vessel structure and blood flow model. All above condition has laid the foundation for simulating human pulse with high precision.

Hardware circuit

On the basis of the function of the overall design of system , hardware circuit mainly includes the main controller, motor driver module, sensors module, input control module and power module.

The STM32F401 of ST Semiconductor company is adopted as the center controller. Power module is supplied by 24V DC voltage regulator module , and LM2576 chip is selected to design into buck circuit converting 24V to 12V and 5V. It only needs few peripheral devices to built efficient regulating circuit, and three different value of voltage are set for the need of different equipment. Motor driver module includes 24V DC motor driver circuit[8] (to make the motor work), and 12V driver circuit[9] (to make pump and magnetic valve work). In consideration of characteristic of peripheral devices such as power, VNH3SP30 chip is selected to design into 24V driver circuit and L298N chip is selected to design into 12V driver circuit. Additionally, a variety of protective measures are taken to guarantee the reliability and security of the circuit.

Data acquisition and interaction modules include the sensors and the human-computer interaction interface. The STM32 reads the value of voltage from its pins which connect to the sensors. The human-computer interaction interface comprises matrix keyboards, switches, and LED lights. When the device is set to the training mode, user can control the device through the keyboards to make it generate several types of pulse , and when device is set to the test mode, user

can choose the answer with the keyboards. The different displays of two LED lights mean different working states of the device.

Artificial hand model

The hand model is made by the material of TPE. Sensory experiments show that it is more lifelike than the traditional latex[1] or silicone material. Furthermore, the hand feeling is more fine and smooth with a little glutinousness, so it is similar with human hand skin. Inside the hand model, there are hard plastic panels, plastic bag wire ropes, small size latex tubes respectively as a simulation of human body skeleton, blood vessels, arm tendons. The tube wall of latex tube is thin, which can better shows the change of pressure of the internal liquid. The artificial hand is shown in Figure 4.

The design of the software

The function module diagram of the system is shown in Figure 5.

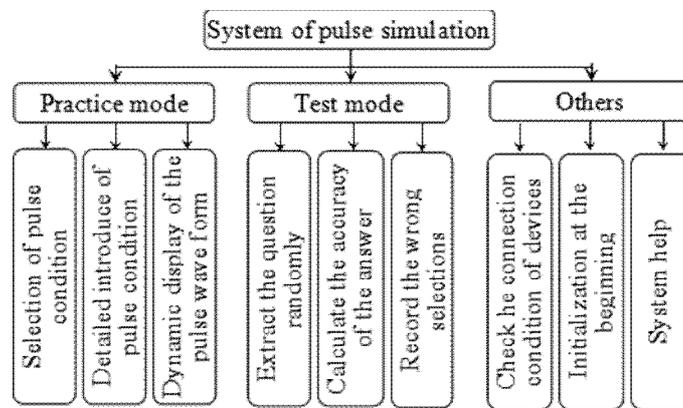


Figure 5. The system function module diagram

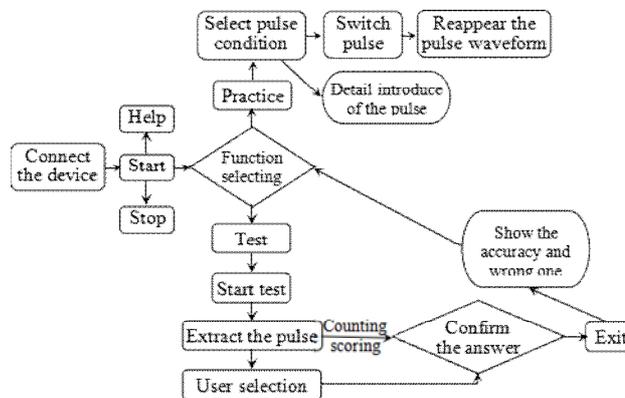


Figure 6. Upper-computer software flow diagram

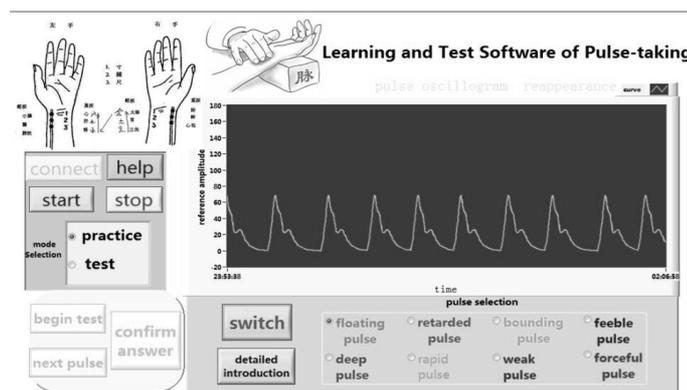


Figure 7. visible control software interface

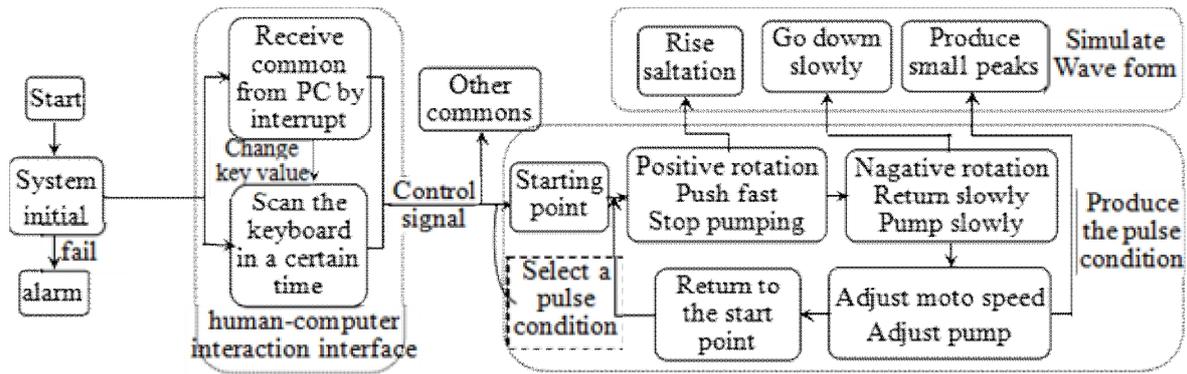


Figure 8. Flow chart of Lower machine

Lower machine control is realized by using STM32 programming[10], while upper-computer software using LabVIEW to develop visible software, and they communicate through the serial port. Upper-computer software includes the functions of pulse-taking practice and test. In the practice mode, users can learn specific human pulse waveform through the equipment by using the software. The software can synchronously display oscillograph on the screen and there is a part for learners to test and evaluate. The flow diagram of upper-computer software is shown in Figure 6 above and the visible control software interface is shown in Figure 7 above.

The main functions of a machine are to control DC motor reversing and rotate speed, pump working frequency, magnetic valve, etc, receiving the signals of man-machine interface and PC hardware, and reading the sensor data to realize the feedback control. Lower machine control program flow chart is shown in Figure 8.

In order to reproduce the human pulse, from the very beginning, the amplitude, frequency, pulse condition rise time, the time that generate lower peak of pulse wave and amplitude from the human pulse wave are extracted and then translated them into control parameters as the system control input parameters. Then the MCU control DC motor rotate quickly based on the technology of PWM speed regulation[11]. Within the given time, motor drives screw-sliding table fast to squeeze the simulation chamber in a specific distance, and the simulation blood vessel would generate a type of mutationally rising pulse condition. During this process, the pump does not work. And then slow down the motor speed to drive sliding table returned slowly, while the pump draw the liquid in the storage tank back to the blood chamber slowly. When the second or third small wave peak arrived, program control motor and the pump speed change together to drop the pressure inside the simulation blood vessel. Finally, during a given period of time, sliding table will return to the starting point, and then adjust control parameters according to the pressure feedback signal and proceed into the next cycle. In motor speed control, of course, to effectively avoid external factors (such as friction between the screw and sliding table), PID control algorithm is adopted.

Results

Using pulse sensor to test simulation pulse signal, compared with human pulse and the record in TCM, through a large number of experiments, the result shows that the simulation is almost identical to human pulse at high stability. Just as Figure 9 shows.

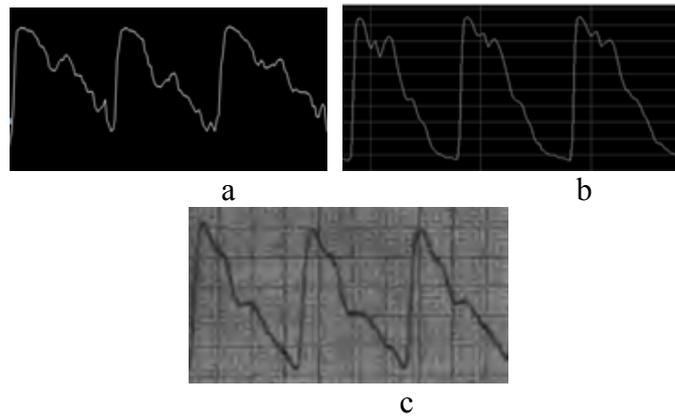


Figure 9. pulse waves. a: the pulse-wave detected from the imitate hand; b: the pulse-wave detected from the real hand; c: the pulse-wave recorded in data[12]

This new kind of pulse simulation device realize the imitation of 8 kinds of typical pulse. Since the control parameter of the device can be fine tuning, the device can expend the quantity of imitate pulse. The pulse simulation was detected by famous veteran doctor of TCM with blind detection method. It turns out that the feeling of finger are identify to the real one actually. The simulation results are shown in figure 10, taking the floating-pulse, deep-pulse, retarded-pulse, and rapid-pulse as examples.

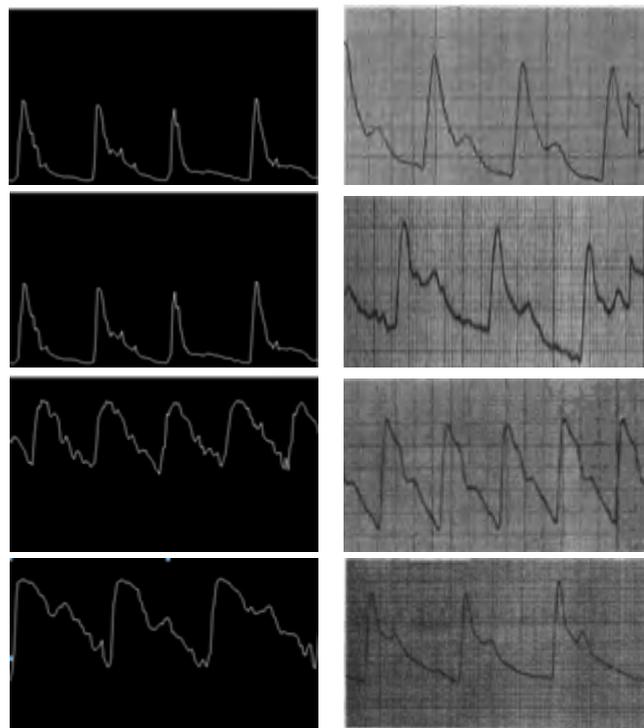


Figure 10. pulse waves.

Notes: In Figure 10, from top to bottom are floating-pulse, deep-pulse, retarded-pulse, and rapid-pulse. And the imitate pulse in simulation hand are shown on the left, the recorded pulse in database are shown on the right.

Summary

This device emphasizes on the high-quality but low-cost idea to realize the simulation of human pulse condition, By improving the control algorithm, it breaks down the barrier that traditional pulse simulation device must adopt precise but unusual hardware structure and reduces the cost. It can change the pulse potential, frequency, pulse shape and so on to realize multiple pulse condition in

high precision by adjusting the parameters. Visualization software interface is intuitive and can see a detailed introduction of the pulse condition and the characteristics of pulse condition waveform clearly, which can improve the quality of TCM education and efficiency of pulse-taking learning. The simulation wave is nearly agreed with the human pulse. Additionally, the device provides a user-friendly interface. Also, this device is easy to operate, move and maintain because of its simple mechanical structure. It will become an auxiliary tool of TCM education and learning. This device solves the problem that pulse instrument is not easy to widespread use. Hopefully, this study will help to roll out pulse simulation device in teaching, learning and be a catalyst for development of traditional Chinese medicine.

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