

Development of the Communication Interface for the Cognitive Model of Complicated Human-Computer Interaction Task

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Abstract. The cognitive modeling of the HCI task has been a hot area in HCI research. And it is an important method to understand the cognitive decision process and mechanism behind operators' behavior. Since the software of HCI task and the software of cognitive modeling generally run on different platforms, it is critical to develop the communication interface between different platforms, especially in the cognitive modeling research of the simulated manual RVD task. To realize a real-time interaction between the cognitive model developed by Common Lisp language and the task simulator developed by VC++ language, this paper developed the communication interface between these two platforms. And the interface is developed based on UDP and the multicast technique. This paper proposed a solution with the foreign-function interface feature of Common Lisp Language to solve the problem that Common Lisp Language doesn't support the multicast technique directly. Test results showed that the communication interface could support data sending and receiving and fulfill the requirement of the real-time communication.

Introduction

Manual RVD (Rendezvous and Docking) task is a complicated human-computer interaction task for astronauts. Also this task is a critical research content for space ergonomics and long-duration space flight in the future [1] [2]. Baozhi Wang, Guohua Jiang, Jiangang Chao (ET al.) designed and realized a semi-physical ergonomics experimental system for the purpose of studying ergonomics problem in manned RVD task. This platform accurately simulated the RVD task in dynamics and could automatically generate behavior and performance data of human [3].

Recently, the method called cognitive modelling becomes more and more popular in the research of cognitive science [4]. In this method, a calculation model is established to evaluate the cognitive theory and phenomenon. Compared with traditional experimentation, cognitive modeling costs much less and can predict task performance, workload and probable fault quantitatively, which is a new way to evaluate the design of human-computer interface. For this reason, we built a cognitive model for RVD task and this model was established based on the cognitive architecture of Adaptive Control of Thought-Rational (ACT-R) [5]. The cognitive architecture is an expatiation for the architecture of brain at the abstract level, which explains how the brain think [6].

In order to evaluate and verify the cognitive model, we should guarantee that the cognitive model and the subjects work at the same environment. So the cognitive model should communicate with the simulator in real time. The method of communication is usually based on network. Internationally, people usually take the method of UDP (User Datagram Protocol) [7, 8].

For the purpose of realizing real-time communication between cognitive model and simulator [9], we developed the interface between them. And the UDP can satisfy the requirement of real-time interaction. Compared with TCP (Transmission Control Protocol), the UDP is faster in the transmission speed and costs less to run in the system. However, the UDP is less reliable in the data transmission. UDP supports unicast, broadcast and multicast. Multicast means sending datagram to a mainframe unit in the network. And a mainframe can join in one or several multicast unit [10]. So multicast satisfies the requirement of dynamics and can save network bandwidth to reduce the

workload of network.

The architecture of ACT-R is established based on Common Lisp language. Unfortunately, the ACT-R architecture doesn't supply the network communication interface. So we have to realize the communication protocol based on Common Lisp language. In this paper, Allegro Common Lisp was chosen to realize the communication protocol. It supports the TCP and UDP, but can't support multicast directly [11].

In this paper, we took use of the characteristic of supporting Foreign-Function Interface (FFI) in Common Lisp language to realize the UDP multicast protocol. Using C++ language to realize the UDP multicast protocol has been a mature technology, so it is not a key point in our paper.

Overall scheme

In this simulated Manual RVD task, cognitive model simulates the astronaut to do the manual RVD task. The simulator stands for the task environment. In terms of communication interface, the cognitive model based on ACT-R architecture is a client and the simulator is a server. The overall scheme is shown in Fig. 1.

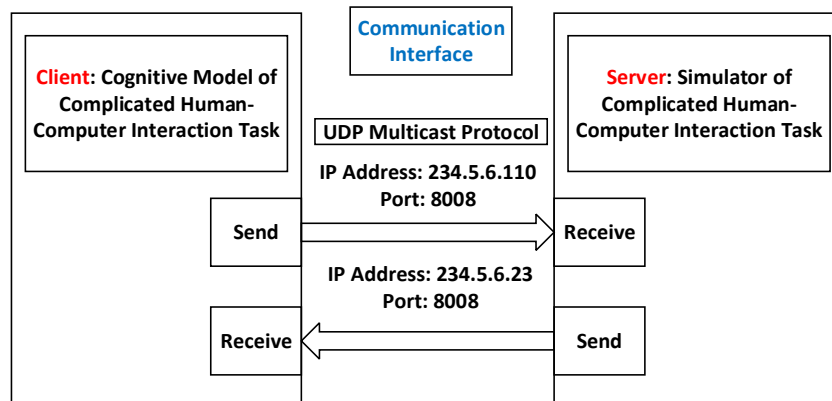


Fig.1. Overall scheme of the communication interface

In this scheme, two multicast units were established. And the unit-1's address is "234.5.6.110" with a port of "8008", which is used to send message to server. While, the unit-2's address is "234.5.6.23" with a port of "8008", which is used to send message to client. The workflow of the system is followed: (1) client receives the real-time task information from server; (2) the cognitive model simulates human's cognitive behavior and send out control commands; (3) the sever receive control commands from client and change the real-time task information based on the commands; (4) circulate from (1) to (3) until the task completes.

In the case of sever, UDP multicast communication protocol was realized based on Winsock 2 using C++ language [12]. As a mature technology, this part won't be repeated here. Now, we talk about how to establish UDP multicast communication protocol through Common Lisp language.

The realization of client's communication interface

The cognitive model based on ACT-R is developed by Common Lisp language. Common Lisp supports the characteristic of Foreign-Function Interface (FFI). FFI allows the running Common Lisp program to load code file from foreign language to realize the function of foreign language.

Common Lisp can't support multicast directly, so this paper attends to realize the client's UDP multicast protocol using the characteristic of FFI in Common Lisp. The protocol includes the UDP sending function and UDP receiving function. Firstly, realize the UDP sending function and UDP receiving function based on Winsock 2. Then, compile the source files to DLL (Dynamic Link Library) files. And with that, load these two DLL files into Common Lisp code. In the end, define corresponding Common Lisp function using FFI. As a result, we can call corresponding functions in Common Lisp.

The client run in the Windows 7 system. The development environment of cognitive model is

Allegro Common Lisp 9.0 and the development environment of C++ is Microsoft Visual Studio 2010. The corresponding Winsock 2 functions are shown in Table 1.

Table 1 Introductions of the Winsocks 2 functions used

Name	Description
bind	Bind a socket at an address.
closesocket	Close an existing socket.
recvfrom	Receive a datagram and save the source address.
sendto	Send data to specified destination address.
setsockopt	Set options of a socket.
socket	New a specified type of socket.
WSACleanup	Stop to use the DLL file, Ws2_32.DLL
WSAStartup	Initiate to use DLL file, Ws2_32.DLL

3.1 UDP multicast sending function

The flow chart of UDP multicast sending function based on Winsock 2 is shown in Fig. 2 (a).

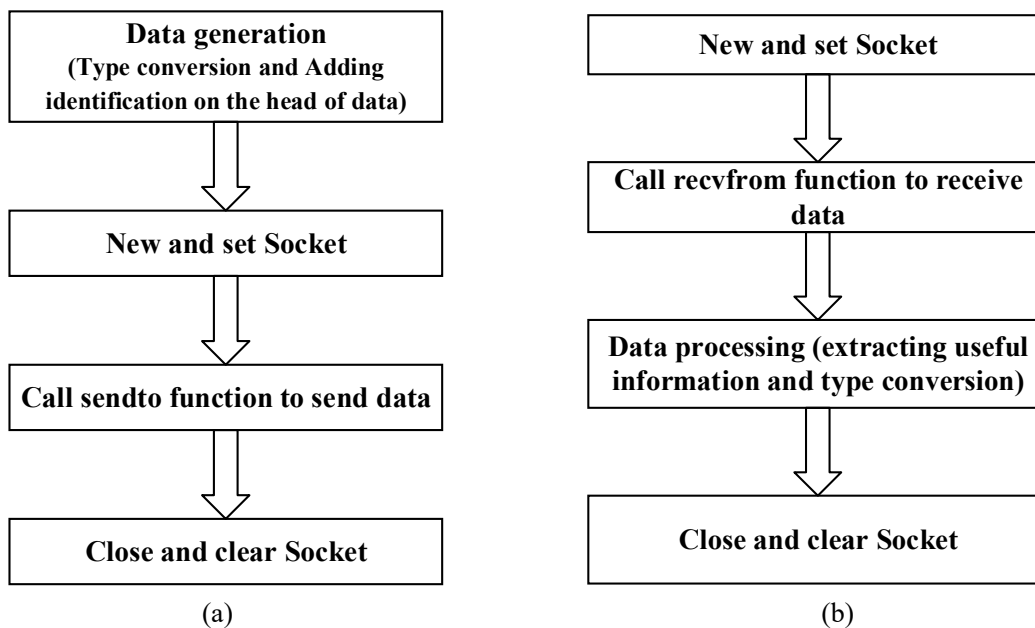


Fig. 2. Flow charts of two functions: (a) flow chart of UDP multicast sending function; (b) flow chart of UDP multicast receiving function

Data generation means changing the 6 DoF (Degree of Freedom) control instructions of cognitive model into char data that can be sent by UDP protocol. And there are two progress: conversion of data from float to char and add identification on the head of char data. Then, call WSAStartup function and socket function to new a socket. And with that, call setsockopt function to complete the setting of address allowed to be reused. Once again, call sendto function to send char data to multicast address 1 (234.5.6.100, port 8008). In the end, call closesocket function to close socket and call WSACleanup function to clear data.

The statement of sending function is: *int sendFloatArray (float original_control_out[6])*. The formal parameter stands for the output of 6 DoF control instructions which is generated from cognitive model.

UDP multicast receiving function

As shown in Fig. 2 (b), it is the flow chart of UDP multicast receiving function based on Winsock 2. Firstly, call WSAStartup and socket functions to new a socket. Secondly, call setsockopt function twice to complete the setting of address allowed to be reused and join in the setting of multicast. Thirdly, call bind function to bind the new socket to multicast address 2 (234.5.6.23, port 8008). And with that, call recvfrom function to receive the char data sent from multicast address 2 in the server. Then conduct data processing to delete the identification on the head of char data and extract the useful data to converse the char data into float data. In the end, close the socket and clear the data.

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