# Moments of Record Values and Characterizations of Marshall-Olkin Extended Distribution

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Moments of the  $m^{th}$  upper record value  $X_{U(m)}$ ,  $m \ge 1$ , and the joint moments of the  $m^{th}$  and  $n^{th}$  upper record values  $X_{U(m)}$  and  $X_{U(n)}$ ,  $n > m \ge 1$ , of a random variable X with Marshall-Olkin Extended distribution are presented. Certain characterizations of this distribution based on hazard function and a simple relationship between two truncated moments are established.

Keywords: Moments of Upper Record Values, Truncated moments

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### 1. Introduction

Adding parameters to a well-defined model is a novel way of constructing flexible families of univariate and bivariate distributions. For a better understanding of this point, we refer the interested reader to Marshall and Olkin works. Marshall-Olkin Extended (MOE) distribution, introduced by Al-Jarallah et al. [1] has pdf (probability density function) and cdf (cumulative distribution function) given respectively by

$$f(x) = f(x; \alpha, \delta) = \frac{\alpha \delta k(x) \left[\alpha \overline{K}(x)\right]^{\delta - 1}}{\left[1 - \overline{\alpha} \overline{K}(x)\right]^{\delta + 1}}, \quad x \in \mathbb{R}$$
(1.1)

and

$$F(x) = F(x; \alpha, \delta) = 1 - \left[\frac{\alpha \overline{K}(x)}{1 - \overline{\alpha} \overline{K}(x)}\right]^{\delta}, \quad x \in \mathbb{R}$$
(1.2)

where  $k(x) = \frac{d}{dx}K(x)$  is the baseline pdf,  $\overline{K}(x) = 1 - K(x)$  and  $\alpha > 0$  ( $\overline{\alpha} = 1 - \alpha$ ),  $\delta > 0$  are parameters.

The pdf of the  $m^{th}$  upper record value,  $X_{U(m)}$ , of a random variable with pdf (1.1) is given by

$$f_{X_{U(m)}}(x) = \frac{\alpha^{\delta} \delta^{m}}{(m-1)!} \left( -\log\left(\frac{\alpha \overline{K}(x)}{1-\overline{\alpha} \overline{K}(x)}\right) \right)^{m-1} \frac{k(x)(\overline{K}(x))^{\delta-1}}{(1-\overline{\alpha} \overline{K}(x))^{\delta+1}}, \quad x \in \mathbb{R}$$
(1.3)

On the other hand, the joint probability density function of the  $m^{th}$  and  $n^{th}$  upper record values  $X_{U(m)}$  and  $X_{U(n)}$ ,  $n > m \ge 1$ , of a random variable with pdf (1.1) is given by

$$f_{X_{U(m)},X_{U(n)}}(x,y) = \frac{\alpha^{\delta} \delta^{n}}{(m-1)!(n-m-1)!} \left( -\log \frac{\alpha \overline{K}(x)}{1-\overline{\alpha}\overline{K}(x)} \right)^{m-1} \\ \times \left( -\log \left( \frac{1-\overline{\alpha}\overline{K}(x)}{\overline{K}(x)} \cdot \frac{\overline{K}(y)}{1-\overline{\alpha}\overline{K}(y)} \right) \right)^{n-m-1} \\ \times \frac{k(x)k(y)\left(\overline{K}(y)\right)^{\delta-1}}{\overline{K}(x)(1-\overline{\alpha}\overline{K}(x))(1-\overline{\alpha}\overline{K}(y))^{\delta+1}}, \ x < y.$$

The rest of the paper is organized as follows. In Section 2, we derive the moments of the  $m^{th}$  upper record value  $X_{U(m)}$ ,  $m \ge 1$  and the joint moments of the  $m^{th}$  and  $n^{th}$  upper record values  $X_{U(m)}$  and  $X_{U(n)}$ ,  $n > m \ge 1$ . Then we present certain characterizations of MOE distribution in Section 3.

#### 2. Moments of Record values of the MOE family of distributions

As we mentioned in the Introduction, we derive, in this Section, the moments of the  $m^{th}$  upper record value  $X_{U(m)}$ ,  $m \ge 1$  and the joint moments of the  $m^{th}$  and  $n^{th}$  upper record values  $X_{U(m)}$  and  $X_{U(n)}$ ,  $n > m \ge 1$  of a random variable X which has pdf given by (1.1). Let us first consider the single moments. The moments of the random variable  $X_{U(m)}$  are given by the following two theorems.

**Theorem 2.1.** Let us suppose that a random variable X has the pdf given by (1.1). Let us suppose that the inverse function of the survival function  $\overline{K}(x)$  can be rewritten in power series form as  $\overline{K}^{-1}(x) = \sum_{i=0}^{\infty} a_i(x-x_0)^i$ , 0 < x < 1,  $x_0 \in [0,1]$ . Let  $\{c_i\}$  and  $\{b_k\}$  be two sequences given by  $c_0 = a_0^l$ ,  $b_0 = 1$ ,  $c_i = (ia_0)^{-1} \sum_{j=1}^{i} (lj-i+j)a_jc_{i-j}$  and  $b_k = k^{-1} \sum_{j=1}^{k} (ij-k+j)\overline{\alpha}^j b_{k-j}$ . If  $0 < \alpha < 2$ , then the moments of the random variable  $X_{U(m)}$  are given as

$$E\left(X_{U(m)}^{l}\right) = \delta^{m} \sum_{i=0}^{\infty} c_{i} \sum_{j=0}^{i} {i \choose j} (-x_{0})^{i-j} \sum_{k=0}^{\infty} b_{k} \sum_{r=0}^{k} {k \choose r} (-1)^{r} (\delta+j+r)^{-m}.$$

**Proof.** The  $l^{th}$  moment of the random variable  $X_{U(m)}$  is given by

$$E\left(X_{U(m)}^{l}\right) = \frac{\alpha^{\delta}\delta^{m}}{(m-1)!} \int_{-\infty}^{\infty} x^{l} \left(-\log\frac{\alpha\overline{K}(x)}{1-\overline{\alpha}\overline{K}(x)}\right)^{m-1} \frac{k(x)(\overline{K}(x))^{\delta-1}}{(1-\overline{\alpha}\overline{K}(x))^{\delta+1}} dx$$

Setting  $t = -\log\left(\frac{\alpha \overline{K}(x)}{1 - \overline{\alpha} \overline{K}(x)}\right)$ , the above integral can be rewritten as

$$E\left(X_{U(m)}^{l}\right) = \frac{\delta^{m}}{(m-1)!} \int_{0}^{\infty} \left(\overline{K}^{-1}\left(\frac{e^{-t}}{\alpha + \overline{\alpha}e^{-t}}\right)\right)^{l} t^{m-1}e^{-\delta t} dt.$$
(2.1)

Using the power series expansion of the inverse function  $\overline{K}^{-1}(x)$  and equation (0.314) of [5], we obtain

$$\left(\overline{K}^{-1}\left(\frac{e^{-t}}{\alpha+\overline{\alpha}e^{-t}}\right)\right)^{l} = \left(\sum_{i=0}^{\infty}a_{i}\left(\frac{e^{-t}}{\alpha+\overline{\alpha}e^{-t}}-x_{0}\right)^{i}\right)^{l} = \sum_{i=0}^{\infty}c_{i}\left(\frac{e^{-t}}{\alpha+\overline{\alpha}e^{-t}}-x_{0}\right)^{i}$$

Replacing the last equation into (2.1), the  $l^{th}$  moment of the random variable  $X_{U(m)}$  can be rewritten as

$$E\left(X_{U(m)}^{l}\right) = \frac{\delta^{m}}{(m-1)!} \sum_{i=0}^{\infty} c_{i} \sum_{j=0}^{i} {i \choose j} (-x_{0})^{i-j} \int_{0}^{\infty} (\alpha + \overline{\alpha}e^{-t})^{-j} t^{m-1} e^{-(\delta+j)t} dt.$$
(2.2)

Let us consider the function  $(\alpha + \overline{\alpha}e^{-t})^{-j}$ . Using the fact that  $0 < \alpha < 2$ , equation (0.314) of [5] and the binomial expansion we arrive at

$$(\alpha + \overline{\alpha}e^{-t})^{-j} = (1 - \overline{\alpha}(1 - e^{-t}))^{-j} = \left(\sum_{k=0}^{\infty} \overline{\alpha}^k (1 - e^{-t})^k\right)^j = \sum_{k=0}^{\infty} b_k \sum_{r=0}^k \binom{k}{r} (-1)^r e^{-rt}.$$

Replacing the last equation into (2.2), we obtain

$$E\left(X_{U(m)}^{l}\right) = \frac{\delta^{m}}{(m-1)!} \sum_{i=0}^{\infty} c_{i} \sum_{j=0}^{i} {i \choose j} (-x_{0})^{i-j} \sum_{k=0}^{\infty} b_{k} \sum_{r=0}^{k} {k \choose r} (-1)^{r} \int_{0}^{\infty} t^{m-1} e^{-(\delta+j+r)t} dt$$
$$= \delta^{m} \sum_{i=0}^{\infty} c_{i} \sum_{j=0}^{i} {i \choose j} (-x_{0})^{i-j} \sum_{k=0}^{\infty} b_{k} \sum_{r=0}^{k} {k \choose r} (-1)^{r} (\delta+j+r)^{-m}.$$

**Theorem 2.2.** Let us suppose that a random variable X has pdf given by (1.1). Let us suppose that the inverse function of the survival function  $\overline{K}(x)$  can be rewritten in power series form as  $\overline{K}^{-1}(x) = \sum_{i=0}^{\infty} a_i(x-x_0)^i$ , 0 < x < 1,  $x_0 \in [0,1]$ . Let  $\{c_i\}$  and  $\{d_k\}$  are two sequences given by  $c_0 = a_0^l$ ,  $d_0 = 1$ ,  $c_i = (ia_0)^{-1} \sum_{j=1}^{i} (lj-i+j) a_j c_{i-j}$  and  $d_k = k^{-1} \sum_{j=1}^{k} (ij-k+j) (1-\frac{1}{\alpha})^j d_{k-j}$ . If  $\alpha > 1/2$ , then the moments of the random variable  $X_{U(m)}$  are given as

$$E\left(X_{U(m)}^{l}\right) = \delta^{m} \sum_{i=0}^{\infty} \frac{c_{i}}{\alpha^{i}} \sum_{j=0}^{i} {i \choose j} (-x_{0})^{i-j} \sum_{k=0}^{\infty} d_{k} (\delta+j+k)^{-m}.$$

**Proof.** The proof is similar to that of Theorem 2.1. The difference is that the series expansion of the function  $(\alpha + \overline{\alpha}e^{-t})^{-j}$  is now given by

$$(\alpha + \overline{\alpha}e^{-t})^{-j} = \alpha^{-j} \left( 1 - \left(1 - \frac{1}{\alpha}\right)e^{-t} \right)^{-j} = \alpha^{-j} \left( \sum_{k=0}^{\infty} \left(1 - \frac{1}{\alpha}\right)^k e^{-kt} \right)^j = \alpha^{-j} \sum_{k=0}^{\infty} d_k e^{-kt}.$$

Using this expansion we obtain the expression for the  $l^{th}$  moment of the random variable  $X_{U(m)}$ . 

Example 2.1. Let us suppose that a random variable X has the Marshall-Olkin extended exponential distribution, i.e. let us suppose that the survival function is  $\overline{K}(x) = e^{-x}$ ,  $x \ge 0$ . The first two moments of the  $n^{th}$  upper record value have been considered in Jose et al. [9]. Here we will present formula for derivation of  $l^{th}$  moments,  $l \ge 1$ . The inverse survival function is

$$\overline{K}^{-1}(x) = -\log x = \sum_{i=1}^{\infty} \frac{(-1)^i}{i} (x-1)^i.$$

Thus, we have that  $x_0 = 1$  and the coefficients  $a_i$  are given as  $a_i = (-1)^i/i$ ,  $i \ge 1$ . For derivation of moments we need the recurrence formulas for coefficients  $c_i$ . We have that  $c_0 = c_1 = c_{l-1} = 0$ ,  $c_l = (-1)^l$ , and

$$c_{l+i} = \frac{1}{i} \sum_{j=0}^{i} (lj - i + j) \frac{(-1)^j}{j+1} c_{l+i-j}, \ i \ge 1.$$

Then the expression for moments follows from the above two theorems.

**Example 2.2.** Let us suppose that a random variable X has the Marshall-Olkin extended Pareto distribution. Parent survival function is given as  $\overline{K}(x) = x^{-\gamma}$ ,  $x \ge 1$ ,  $\gamma > 0$ , and the corresponding inverse function is

$$\overline{K}^{-1}(x) = (1-x)^{-1/\gamma} = \sum_{i=0}^{\infty} (-1)^{-1/\gamma} \binom{-1/\gamma}{i} (x-1)^i.$$

The coefficients  $a'_i$  are given as  $a_i = \binom{-1/\gamma}{i}$ ,  $i \ge 1$ , and the coefficients  $c_i$  are given as  $c_0 = 1$  and

$$c_i = \frac{1}{i} \sum_{j=1}^{i} (lj - i + j) {\binom{-1/\gamma}{j}} c_{i-j}, \ i \ge 1.$$

Now, we will derive the joint moments of the  $m^{th}$  and  $n^{th}$  upper record values  $X_{U(m)}$  and  $X_{U(n)}$ ,  $n > m \ge 1$ , of a random variable X with Marshall-Olkin Extended distribution. These joint moments are given by the following two theorems.

**Theorem 2.3.** Let us suppose that a random variable X has pdf given by (1.1). Let us suppose that the inverse function of the survival function  $\overline{K}(x)$  can be rewritten in power series form as

 $\overline{K}^{-1}(x) = \sum_{i=0}^{\infty} a_i (x - x_0)^i, \ 0 < x < 1, \ x_0 \in [0, 1]. \ Let \{c_i\} \ and \ \{d_k\} \ be \ two \ sequences \ given \ by \ c_0 = a_0^l, \ d_0 = 1, \ c_i = (ia_0)^{-1} \sum_{j=1}^i (lj - i + j) a_j c_{i-j} \ and \ d_k = k^{-1} \sum_{j=1}^k (ij - k + j) \overline{\alpha}^j d_{k-j}. \ If \ 0 < \alpha < 2, \ then \ the \ joint \ moments \ of \ the \ random \ variables \ X_{U(m)} \ and \ X_{U(n)}, \ n > m \ge 1, \ are \ given \ as$ 

$$E\left(X_{U(m)}^{r}X_{U(n)}^{s}\right) = \delta^{n}\sum_{i=0}^{\infty}\sum_{j=0}^{\infty}c_{i}c_{j}\sum_{k=0}^{i}\sum_{l=0}^{j}\binom{i}{k}\binom{j}{l}(-x_{0})^{i+j-k-l} \\ \times \sum_{p=0}^{\infty}\sum_{w=0}^{\infty}d_{p}d_{w}\sum_{q=0}^{p}\sum_{h=0}^{w}\binom{p}{q}\binom{w}{h}(-1)^{q+h}(\delta+l+h)^{-n+m} \\ \times (k+l+\delta+q+h)^{-m}.$$

**Proof.** The joint moment of the random variables  $X_{U(m)}$  and  $X_{U(n)}$  is given by

$$E\left(X_{U(m)}^{r}X_{U(n)}^{s}\right) = \frac{\alpha^{\delta}\delta^{n}}{(m-1)!(n-m-1)!} \int_{-\infty}^{\infty} x^{r} \left(-\log\frac{\alpha\overline{K}(x)}{1-\overline{\alpha}\overline{K}(x)}\right)^{m-1} \\ \times \frac{k(x)dx}{\overline{K}(x)(1-\overline{\alpha}\overline{K}(x))} \int_{x}^{\infty} y^{s}\frac{k(y)(\overline{K}(y))^{\delta-1}}{(1-\overline{\alpha}\overline{K}(y))^{\delta+1}} \\ \times \left(-\log\left(\frac{1-\overline{\alpha}\overline{K}(x)}{\alpha\overline{K}(x)}\cdot\frac{\alpha\overline{K}(y)}{1-\overline{\alpha}\overline{K}(y)}\right)\right)^{n-m-1} dy.$$

Letting  $u = -\log\left(\frac{\alpha \overline{K}(x)}{1-\overline{\alpha}\overline{K}(x)}\right)$  and

$$v = -\log\left(\frac{1 - \overline{\alpha}\overline{K}(x)}{\alpha\overline{K}(x)} \cdot \frac{\alpha\overline{K}(y)}{1 - \overline{\alpha}\overline{K}(y)}\right),\,$$

the above integral can be rewritten as

$$E\left(X_{U(m)}^{r}X_{U(n)}^{s}\right) = \frac{\delta^{n}}{(m-1)!(n-m-1)!} \int_{0}^{\infty} \left(\overline{K}^{-1}\left(\frac{e^{-u}}{\alpha+\overline{\alpha}e^{-u}}\right)\right)^{r} u^{m-1}e^{-\delta u} du$$
$$\times \int_{0}^{\infty} \left(\overline{K}^{-1}\left(\frac{e^{-(u+v)}}{\alpha+\overline{\alpha}e^{-(u+v)}}\right)\right)^{s} v^{m-1}e^{-\delta v} dv.$$

Now, following the same techniques used in Theorem 2.1 we obtain the proof of theorem.  $\Box$ 

**Theorem 2.4.** Let us suppose that a random variable X has pdf given by (1.1). Let us suppose that the inverse function of the survival function  $\overline{K}(x)$  can be rewritten in power series form as  $\overline{K}^{-1}(x) = \sum_{i=0}^{\infty} a_i(x-x_0)^i$ , 0 < x < 1,  $x_0 \in [0,1]$ . Let  $\{c_i\}$  and  $\{d_k\}$  are two sequences given by  $c_0 = a_0^l$ ,  $d_0 = 1$ ,  $c_i = (ia_0)^{-1} \sum_{j=1}^{i} (lj-i+j)a_jc_{i-j}$  and  $d_k = k^{-1} \sum_{j=1}^{k} (ij-k+j) (1-\frac{1}{\alpha})^j d_{k-j}$ . If  $\alpha > 1/2$ , then the joint moments of the random variables  $X_{U(m)}$  and  $X_{U(n)}$  are given as

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$$E\left(X_{U(m)}^{r}X_{U(n)}^{s}\right) = \delta^{n}\sum_{i=0}^{\infty}\sum_{j=0}^{\infty}c_{i}c_{j}\sum_{k=0}^{i}\sum_{l=0}^{j}\binom{i}{k}\binom{j}{l}(-x_{0})^{i+j-k-l}\alpha^{-(k+l)}$$
$$\times \sum_{p=0}^{\infty}\sum_{q=0}^{\infty}d_{p}d_{q}(\delta+l+q)^{-n+m}(k+l+\delta+p)^{-m}.$$

**Proof.** Proof is similar to the proofs of Theorems 2.2 and 2.3.

### **3.** Characterization Results

In designing a stochastic model for a particular modeling problem, an investigator will be vitally interested to know if their model fits the requirements of a specific underlying probability distribution. To this end, the investigator will rely on the characterizations of the selected distribution. Generally speaking, the problem of characterizing a distribution is an important problem in various fields and has recently attracted the attention of many researchers. Consequently, various characterization results have been reported in the literature. These characterizations have been established in many different directions. In this section, we present characterizations of MOE distribution. These characterizations are based on: (i) hazard function; (ii) a simple relationship between two truncated moments. We like to mention that the characterization (ii) which is expressed in terms of the ratio of truncated moments is stable in the sense of weak convergence. It also serves as a bridge between a first order differential equation and probability.

### 3.1. Characterizations based on hazard function

The following definition is stated here for the sake of completeness.

**Definition 3.1.** Let *F* be an absolutely continuous distribution with the corresponding pdf f. The hazard function corresponding to *F* is denoted by  $h_F$  and is defined by

$$h_F(y) = \frac{f(y)}{1 - F(y)}, \quad y \in Supp F, \qquad (3.1)$$

where Supp F is the support of F.

It is obvious that the hazard function of a twice differentiable function satisfies the first order differential equation

$$\frac{h_{F}^{\prime}\left(\mathbf{y}\right)}{h_{F}\left(\mathbf{y}\right)}-h_{F}\left(\mathbf{y}\right)=q\left(\mathbf{y}\right)\;,$$

where q(y) is an appropriate integrable function. Although this differential equation has an obvious form since

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$$\frac{f'(y)}{f(y)} = \frac{h'_F(y)}{h_F(y)} - h_F(y) , \qquad (3.2)$$

for many univariate continuous distributions (3.2) seems to be the only differential equation in terms of the hazard function. The goal of the characterization based on hazard function is to establish a differential equation in terms of hazard function, which has as simple form as possible and is not of the trivial form (3.2). For some general families of distributions this may not be possible.

**Proposition 3.1.** Let  $X : \Omega \to \mathbb{R}$  be a continuous random variable. The random variable X has pdf(1.1) if and only if its hazard function  $h_F(x)$  satisfies the differential equation

$$h'_{F}(x) - k'(x)(k(x))^{-1}h_{F}(x) = \frac{\delta(k(x))^{2}\left[1 - 2\overline{\alpha}\overline{K}(x)\right]}{\left\{\overline{K}(x)\left[1 - \overline{\alpha}\overline{K}(x)\right]\right\}^{2}}, \quad x \in \mathbb{R}.$$
(3.3)

**Proof.** If X has pdf (1.1), then clearly (3.3) holds. Now, if (3.3) holds, then

$$(k(x))^{-1}h'_F(x) - k'(x)(k(x))^{-2}h_F(x) = \frac{\delta(k(x))\left[1 - 2\overline{\alpha}\overline{K}(x)\right]}{\left\{\overline{K}(x)\left[1 - \overline{\alpha}\overline{K}(x)\right]\right\}^2},$$

or

$$\frac{d}{dx}\left\{\left(k(x)\right)^{-1}h_{F}(x)\right\} = \frac{d}{dx}\left\{\delta\left[\overline{K}(x)\left(1-\overline{\alpha}\overline{K}(x)\right)\right]^{-1}\right\},$$

or

$$\frac{f(x)}{1-F(x)} = h_F(x) = \frac{\delta k(x)}{\overline{K}(x)(1-\overline{\alpha}\overline{K}(x))} = \frac{\delta k(x)}{\overline{K}(x)} + \frac{\delta\overline{\alpha}k(x)}{1-\overline{\alpha}\overline{K}(x)}$$

Integrating both sides of the above equation from  $-\infty$  to x, we arrive at

$$-\log(1 - F(x)) = -\delta \log(\overline{K}(x)) + \delta \log(1 - \overline{\alpha}\overline{K}(x)) + \delta \log(\alpha)$$

from which we have

$$1 - F(x) = \left(\alpha \overline{K}(x)\right)^{\delta} \left(1 - \overline{\alpha} \overline{K}(x)\right)^{-\delta}.$$

## 3.2. Characterizations based on two truncated moments

In this subsection we present characterizations of MOE distribution in terms of a simple relationship between two truncated moments. We like to mention here the works of Glänzel [2, 3], Glänzel et al. (1984), Glänzel and Hamedani [4] and Hamedani [6–8] in this direction. Our characterization results presented here will employ an interesting result due to Glänzel [2] (Theorem 3.1 below).

The advantage of the characterizations given here is that, cdf F need not have a closed form and are given in terms of an integral whose integrand depends on the solution of a first order differential equation, which can serve as a bridge between probability and differential equation.

**Theorem 3.1.** Let  $(\Omega, \mathscr{F}, \mathbf{P})$  be a given probability space and let H = [a, b] be an interval for some a < b  $(a = -\infty, b = \infty$  might as well be allowed). Let  $X : \Omega \to H$  be a continuous random variable with the distribution function F and let g and h be two real functions defined on H such that

$$\mathbf{E}[g(X) \mid X \ge x] = \mathbf{E}[h(X) \mid X \ge x] \boldsymbol{\eta}(x), \quad x \in H,$$

is defined with some real function  $\eta$ . Assume that g,  $h \in C^1(H)$ ,  $\eta \in C^2(H)$  and F is twice continuously differentiable and strictly monotone function on the set H. Finally, assume that the equation  $h\eta = g$  has no real solution in the interior of H. Then F is uniquely determined by the functions g, h and  $\eta$ , particularly

$$F(x) = \int_{a}^{x} C \left| \frac{\eta'(u)}{\eta(u)h(u) - g(u)} \right| \exp\left(-s(u)\right) du,$$

where the function *s* is a solution of the differential equation  $s' = \frac{\eta' h}{\eta h - g}$  and *C* is a constant, chosen to make  $\int_H dF = 1$ .

We like to mention that this kind of characterization based on the ratio of truncated moments is stable in the sense of weak convergence, in particular, let us assume that there is a sequence  $\{X_n\}$  of random variables with distribution functions  $\{F_n\}$  such that the functions  $g_n$ ,  $h_n$  and  $\eta_n$  $(n \in \mathbb{N})$  satisfy the conditions of Theorem 3.1 and let  $g_n \to g$ ,  $h_n \to h$  for some continuously differentiable real functions g and h. Let, finally, X be a random variable with distribution F. Under the condition that  $g_n(X)$  and  $h_n(X)$  are uniformly integrable and the family  $\{F_n\}$  is relatively compact, the sequence  $X_n$  converges to X in distribution if and only if  $\eta_n$  converges to  $\eta$ , where

$$\eta(x) = \frac{E[g(X) \mid X \ge x]}{E[h(X) \mid X \ge x]}.$$

This stability theorem makes sure that the convergence of distribution functions is reflected by corresponding convergence of the functions g, h and  $\eta$ , respectively. It guarantees, for instance, the 'convergence' of characterization of the Wald distribution to that of the Lévy-Smirnov distribution if  $\alpha \to \infty$ , as was pointed out in Glänzel and Hamedani [4].

A further consequence of the stability property of Theorem 3.1 is the application of this theorem to special tasks in statistical practice such as the estimation of the parameters of discrete distributions. For such purpose, the functions g, h and, specially,  $\eta$  should be as simple as possible. Since the function triplet is not uniquely determined it is often possible to choose  $\eta$  as a linear function. Therefore, it is worth analyzing some special cases which helps to find new characterizations reflecting the relationship between individual continuous univariate distributions and appropriate in other areas of statistics.

**Remark 3.1.** (a) In Theorem 3.1, the interval H need not be closed since the condition is only on the interior of H. (b) Clearly, Theorem 3.1 can be stated in terms of two functions g and  $\eta$  by taking  $h(x) \equiv 1$ , which will reduce the condition given in Theorem 3.1 to  $E[g(X) | X \ge x] = \eta(x)$ . However, adding an extra function will give a lot more flexibility, as far as its application is concerned.

**Proposition 3.2.** Let  $X : \Omega \to \mathbb{R}$  be a continuous random variable and let  $h(x) = [1 - \overline{\alpha}\overline{K}(x)]^{\delta+1}$ and  $g(x) = h(x)\overline{K}(x)$  for  $x \in \mathbb{R}$ . The pdf of X is (1.1) if and only if the function  $\eta$  defined in Theorem 3.1 has the form

$$\eta\left(x
ight)=rac{\delta}{\delta+1}\overline{K}\left(x
ight)\,,\quad x\in\mathbb{R}$$

**Proof.** Let X have pdf(1.1), then

$$(1-F(x)) \mathbf{E}[h(X) | X \ge x] = [\alpha \overline{K}(x)]^{\delta}, \quad x \in \mathbb{R}$$

and

$$(1 - F(x)) \mathbf{E}[g(X) \mid X \ge x] = \frac{\delta}{\alpha(\delta + 1)} \left[\alpha \overline{K}(x)\right]^{\delta + 1}, \quad x \in \mathbb{R}$$

and finally

$$\eta(x)h(x) - g(x) = -\frac{1}{\delta} \left[ 1 - \overline{\alpha}\overline{K}(x) \right]^{\delta+1}\overline{K}(x) < 0, \quad x \in \mathbb{R}.$$

Conversely, if  $\eta$  is given as above, then

$$s'(x) = \frac{\eta'(x) h(x)}{\eta(x) h(x) - g(x)} = \frac{\delta f(x)}{\overline{K}(x)}, \quad x \in \mathbb{R},$$

and hence

$$s(x) = -\log(\left[\overline{K}(x)\right]^{\delta}), \quad x \in \mathbb{R}.$$

Now, in view of Theorem 3.1, X has pdf (1.1).

**Corollary 3.1.** Let  $X : \Omega \to \mathbb{R}$  be a continuous random variable and let h(x) be as in Proposition 3.2. The pdf of X is (1.1) if and only if there exist functions g and  $\eta$  defined in Theorem 3.1 satisfying the differential equation

$$\frac{\eta'(x)h(x)}{\eta(x)h(x)-g(x)} = \frac{\delta f(x)}{\overline{K}(x)}, \quad x \in \mathbb{R}.$$

Published by Atlantis Press Copyright: the authors 123 **Remark 3.2.** (a) The general solution of the differential equation in Corollary 3.1 is

$$\boldsymbol{\eta}\left(x\right) = \left[\overline{K}\left(x\right)\right]^{-\delta} \left[-\int \delta f\left(x\right) \left[\overline{K}\left(x\right)\right]^{\delta-1} \left[1 - \overline{\alpha}\overline{K}\left(x\right)\right]^{-(\delta+1)} g\left(x\right) dx + D\right],$$

for  $x \in \mathbb{R}$ , where D is a constant. One set of appropriate functions is given in Proposition 3.2 with D = 0.

(b) Clearly there are other triplets of functions  $(h, g, \eta)$  satisfying the conditions of Theorem 3.1. We presented one such triplet in Proposition 3.2.

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