

Combining RMT-based filtering with time-stamped resampling for robust portfolio optimization

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Abstract

Finding the optimal weights for a set of financial assets is a difficult task. The mix of real world constrains and the uncertainty derived from the fact that process is based on estimates for parameters that likely to be inaccurate, often result in poor results. This paper suggests that a combination of a filtering mechanism based on random matrix theory with time-stamped resampled evolutionary multiobjective optimization algorithms enhances the robustness of forecasted efficient frontiers.

Keywords: Portfolio optimization, Filtering, Robustness, Multi-objective optimization.

1. Introduction

The choice of the right allocation of funds among alternatives is a major topic of interest for both practitioners and researchers focused in finance. The number of alternative distributions funds, portfolios, might be large and their profiles are likely to be dif-

ferent. The topic is complex and it can be analysed from different points of view. Bearing that in mind, this work fits in the literature in the specific area of robust portfolio optimization. The intended contribution is an analysis of the potential benefits derived from a combination of a resampled approach based on evolutionary algorithms with a filtering mecha-

nism derived from random matrix theory.

The amount of research devoted to portfolio optimization is ample and it is mostly based on core contributions made by Markowitz^{1,2}. This author frames the problem of asset allocation as multiobjective optimization task where the investor tries to balance two opposing objectives, the minimization of risk and the maximization of return of the portfolio as a whole.

Formally, the basic version of the bi-objective problem could be defined as:

- Minimize portfolio risk:

$$\sigma_p^2 = \sum_{i=1}^n \sum_{j=1}^n w_i w_j \sigma_{ij} \quad (1)$$

- Maximize portfolio return:

$$E(R_p) = \sum_{i=1}^n w_i \mu_i \quad (2)$$

- Subject to the following constraints:

$$\sum_{i=1}^n w_i = 1 \quad (3)$$

$$0 \leq w_i \leq 1; i = 1 \dots n \quad (4)$$

where n is the number of available assets, μ_i the expected return of asset i , σ_{ij} the covariance between asset i and j , and w_i are the weights for the components of the portfolio. These weights are the decision variables. For practical purposes, risk is represented with the standard deviation σ_p . The constraints referenced in equations 3 and 4 represent requirements for the full investment of funds and the prohibition from shorting any asset, respectively.

This framework may be extended to consider some additional real world constraints³ such as:

- Cardinality constraint: it is possible to define the maximum C_{max} and minimum C_{min} number of assets in which it is possible to invest ($w_i \neq 0$):

$$C_{min} \leq \sum(w_i \neq 0) \leq C_{max} \quad (5)$$

- Values limit constraint: each weight w_i must have a value in the interval $[lim_{inf}, lim_{sup}]$, where:

$$0.0 \leq lim_{inf} \leq w_i \leq lim_{sup} \leq 1.0 \quad (6)$$

The solution for this problem consists of a set of portfolios that defines a Pareto front, which is usually referred to as the efficient frontier. The points of this curve represent portfolios that have the minimum amount of risk given a certain expected return, and viceversa. Given that the preference for one objective over the other one is conditioned by the attitudes of the decision maker, these portfolios are neither better or worse than the rest of the components of the solution. These portfolios, plotted in the *risk-return* space, define a curve similar to fig. 1.

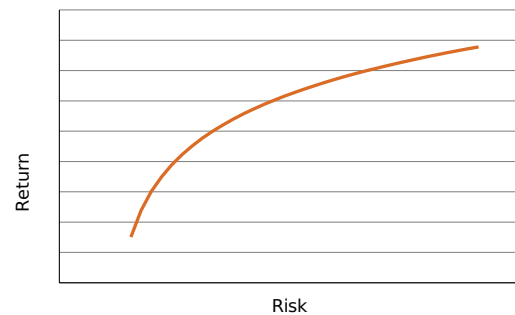


Fig. 1. Efficient frontier

The difficulty of tackling this optimization problem varies widely depending on the assumptions. Once the basic model is extended with real world ones, the limitation of standard exact approaches becomes apparent. For this reason, both academics and practitioners have been exploring for decades the possibilities offered by evolutionary computation.

The multiobjective nature of the problem makes it well suited for Multiobjective Evolutionary Algorithms (MOEAs). As reflected in a paper by Metaxiotis and Liagkouras⁴, there is a large number of recent papers exploring their performance in portfolio optimization. Among them, we could mention Skolpadungket *et al.*⁵, Radziukyniene and Xilinskas⁶, Anagnostopoulos and Mamanis⁷ or Deb *et al.*⁸.

Despite all this research effort on MOEAS for portfolio optimization there are still open issues that require further investigation such as the problem of robustness⁹. The lack of robust solutions is one of the main concerns regarding optimization; in consequence some approaches have emerged that deals with that issue¹⁰. Focusing on asset allocation, we find that the reliability of the solutions provided by

the algorithms is subject to the accuracy of the estimates for two key parameters that underlie the optimization process: the expected asset returns and their associated variance-covariance matrix. Their true values are difficult to predict, and this often results on expected efficient frontiers that turn out to lie far from the observed ones.

The problem of finding robust portfolios has already been studied in literature¹¹. Among the different authors who have tackled this issue we could mention Costa et al.¹² who deals with the problem of robust optimal portfolio selection, or Nguyen et al.¹³ who introduce a generic robust ranking model and apply it to portfolio optimization. Literature shows some other studies which work in the optimization of the worst-case scenarios such as Ghaoui et al.¹⁴, who consider the problem of computing and optimizing (by using conic optimization) the worst-case mean-variance, or Zymler et al.¹⁵, who suggest a novel robust optimization model for designing portfolios, that model trades off weak and strong guarantees on the worst-case portfolio return.

Summarizing, most of the literature on robust portfolio optimization falls into two fields: papers that emphasize the need for robust estimates for the parameters or those where authors try to manage uncertainty in the optimization process itself. The first one usually tries to filter the estimates to control, for instance, the influence of extreme past events on their computation¹⁶. We also find many authors who focus on a second way, handling the uncertainty in parameters during the optimization process^{17,18,19,20}. Other efforts regarding the second line were made to introduce robustness in multi-objective optimization²¹. For instance Deb et al.²² launched a robust adaptation for NSGA-II algorithm to optimize portfolios and then Garcia et al.²³ dealt with the problem of robustness but using resampling and a third objective as a time-stamp.

In this paper we suggest combining both, time-stamped resampling and filtering the variance-covariance matrix or, more exactly, the associated correlation matrix. Details of this new approach will be provided in the next section. Then, a wide set of experiments is shown in order to validate the approach. Finally, the last section will be focused on

conclusions and future work.

2. Robust Approach

As we already discussed in the introduction, the portfolio optimization process depends on imperfect forecasts for two key sets of parameters, future returns and the variance-covariance matrix. Given that this usually has a major impact in the reliability of the results, there is a clear need for control mechanisms. In this section we introduce two approaches that have never been tested together: a set of filters based on random matrix theory and time-stamped resampling strategy based on MOEAs. This will be followed by an introduction to robustness metrics.

2.1. RMT Filtering

The origins of Random Matrix Theory (RMT) can be traced back to efforts by nuclear physicists during 50's and 60's in the context of gaining understanding the energy levels of complex nuclei. More recently, these studies on the statistical properties of matrices based on independent random elements have been tested on the context of portfolio optimization by the econophysics community^{24,25,26,27}.

These authors, among others, show that empirical variance-covariance matrices of financial returns are affected by spurious correlations. The cross-correlation matrix, directly connected to the variance-covariance matrix, shows a mix of noise, correlation among the random component of the returns series, and signal. As Laloux *et al.* report²⁵, the consequence of using the correlation matrix directly obtained from historical data is an underestimation of real risk. Hence, the need of using a corrected one.

RMT provides the tools to identify the mentioned two components analysing the eigenvalues, λ , of the correlation matrix. Given that theoretical limits for the distribution of eigenvalues for random matrices are known²⁸, it is possible to identify most of purely random component. Plerou *et al.*²⁴ review the original analytical results and conclude that for return series where the number of assets, n , is larger than the number of time periods considered, p , the

lower limit, λ_{\min} , and the upper one λ_{\max} , are given by the analytical expression:

$$\lambda_{\max/\min} = 1 + \frac{1}{q} \pm 2\sqrt{\frac{1}{q}} \quad (7)$$

where $q = p/n$.

These authors suggest a reconstruction process where the original noisy correlation matrix, C , is replaced by a filtered one. It starts with the construction of a diagonal matrix Λ , with n eigenvalues for C . Then, those values in the range defined by equation 7 are replaced with zeros and the resulting structure, Λ' , gets transformed to the basis of C . Using the eigendecomposition theorem with the original eigenvectors E we would obtain the filtered cross-correlation matrix C' using the expression

$$C' = E\Lambda'E^{-1} \quad (8)$$

The final step would be setting the diagonal elements of C' to 1 in order to make sure that both C and C' have the same trace. The outcome of all this is a clean correlation matrix that can subsequently be used in the optimization process.

While different authors suggest different approaches to get to C' , the core ideas are the same. They tend to differ only in the choice of the values used to replace the eigenvalues in the range $\lambda_{\min/\max}$ in Λ to get Λ' .

Daly *et al.*²⁷ review several filtering approaches and introduce a new one based on Krzanowski stability²⁹. The method is very similar to the one described above. The difference is that the replacement eigenvalues for Λ' are given by the expression

$$\lambda'_i = \lambda'_1 + (i - 1)k \quad (9)$$

In this context, k is a constant defined as

$$k = 2\frac{a - \lambda'_1}{r - 1} \quad (10)$$

where r is the number of noisy eigenvalues to be replaced and a is their mean ($\bar{\Lambda}_{\text{noisy}}$).

The key parameter to be defined is the minimum value λ'_1 , which the authors define in terms of a fraction of a . KR2, therefore, would correspond to

a Krzanowski stability-based filter with $\lambda'_1 = a/2$, KR4 to a filtering with $\lambda'_1 = a/4$ etc.

Daly *et al.* report that, in their experiments, KR2, KR4 and KR8 showed the highest potential for realised risk reduction. For this reason, we will consider them, together with the RMT filtering by Plerou *et al.*, in our experimental analysis. The filtering methods described above will be combined with a time-stamped resampled optimization strategy

2.2. Optimization Algorithm

The multiobjective nature of the optimization problem to be solved, together with the complexity derived from the real-world constraints, makes strategies based on MOEAs very appropriate. A basic modelling would provide approximations to the efficient frontier that would suffer from the unreliability discussed before, hence our choice of complementing them with a time-stamped resampling strategy.

This approach, proposed by García *et al.*²³, generates sets of likely scenarios, pairs of expected returns and variance-covariance matrices, based on historical data following the nonparametric bootstrap process described in algorithm 1²³. Each candidate portfolio faces a number of scenarios during the evolution process and the algorithm weeds out those that are too sensitive to deviations in expected returns and variance-covariance matrix. This general process limits the possibility of selecting portfolios that are overspecialized in a scenario, the expected asset returns and the forecasted variance-covariance matrix, that will differ from reality with a high probability. The algorithm also considers the age of candidate portfolios, and favors those that have performed better for a longer time. This time-stamped component of the approach, together with the resampling, improves the robustness of the solu-

tions.

Algorithm 1: Resampling method

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1:  $S$ : original sample set with a size  $N_s$ .
2:  $S'$ : new sample set with a size  $N'_s$ . At the beginning,
    $S' = \emptyset$  and  $N'_s = 0$ .
3: while  $N'_s \neq N_s$  do
4:   Select one instance  $X_i$ , at random, from  $S$ .
5:   Add instance to the new set.  $S' = S' + X_i$ .
6: end while
7: return ( $S'$ )

```

Given that the combination of RMT filtering and time-stamped resampling that we suggest is compatible with many MOEAS, we will test the approach with four of the most popular: NSGA-II, SPEA2, GDE3 and SMPSO. These metaheuristics represent three different algorithm families, genetic algorithms, differential evolution and particle swarm optimization, and we introduce them next.

Genetic algorithms have two representatives in the set. The first one is the Non-dominated Sorting Genetic Algorithm II, NSGA-II, proposed by Deb *et al.* ³⁰. It is a multi-objective genetic algorithm that operates applying the standard genetic operators (selection, crossover, and mutation) to a basic population. Then, it sorts both the individuals in the new and old populations according to a dominance rank. The best solutions are chosen to create a new population. In case of tie in terms of rank, the algorithm considers a density estimation based on the crowding distance to the surrounding individuals belonging to the same rank. The second one is the Strength Pareto Evolutionary Algorithm 2, SPEA2. It was proposed by Zitzler *et al.* ³¹ and one of its core features is that each individual has a fitness value that is the sum of its strength raw fitness plus a density estimation. It also uses a population of solutions plus an external archive. The algorithm applies the mentioned standard operators to a population of solutions to fill the archive of individuals; then, the nondominated individuals from the combination are copied into a new population. If the number of nondominated individuals happens to be greater than the population size, a truncation operator based on the distances to the k -th nearest neighbor is used.

Multiobjective particle swarm optimization al-

gorithms are represented by the Speed-constrained Multi-Objective PSO algorithm, SMPSO ³². In PSO algorithms a set (swarm) of candidate solutions (particles) to the problem navigate through the solution space. This navigation is guided by a velocity equation, which specifies the way particles update their location. Two key elements in this equation are the current position of the particle and the best positions visited so far. Usually, both the best position visited by the particle and the best position visited by any particle in the swarm are taken into account. The algorithm uses an external archive to store non-dominated solutions and extends the basic framework adding a constraining mechanism, already applied in mono-objective PSO algorithms, that modulates the speed at which particles fly ³³.

Finally, we will consider differential evolution by means of the Generalized Differential Evolution 3 algorithm, GDE3 ³⁴. This alternative starts with a population of random solutions, which becomes current population. Every generation, the algorithm extends current population with an offspring population obtained using the differential evolution operators. The result is subsequently reduced to maintain the size stable using nondominated sorting and a pruning technique aimed at diversity preservation.

For this work, in order to ensure fair comparisons, we will use the same encoding and repair operator across core algorithms. Portfolios will be represented by arrays of as many floats as available investment alternatives, where w_i , represents the percentage invested in asset i . Solutions would consist of sets of nondominated portfolios in terms of risk and return that approximate the efficient frontier. As for the repair operator, the need to meet the set of hard constraints (Eqs. 3 to 6) requires a way to deal with unfeasible solutions. The approach to be used will be relying on the operator both after the initialization of the population and the use of the genetic operators.

Whenever the number assets where $w_i > 0$ is out of the interval $[C_{min}, C_{max}]$, the individual goes through an adjustment process to ensure compliance with the cardinality constraint. This is done adding or dropping assets until the requirement is met. In case the sum of weights per individual is not

1.0, $\sum_{i=1}^n w_i \neq 1$, the algorithm adjusts the holdings adding or subtracting random amounts up to the required adjustment. These processes are described in detail in ²³.

2.3. Robustness Evaluation

The evaluation of robust solutions requires specific quality indicator that differ for the the most commonly used on in multiobjective optimization such as Hypervolume (HV) or Spread ³⁵. We will consider four indicators to measure robustness that mostly capture the divergence between expected results and actual results. These are Estimation Error, Stability, Unrealized Returns, and Extreme Risk ²³. We outline their main features.

The first one to be considered is *Estimation Error*. This indicator measures the average Mahalanobis distance ³⁶ between the expected risk and return for every portfolio in the efficient frontier and the actual risk and return a posteriori, once the real values of the parameters are observed. As a result, the smaller the value, the closer that the expected behaviour of the optimized portfolios would be to the real one observed a posteriori.

The second quality indicator is *Stability*. In this case, metric measures the average difference between the Pareto front obtained for the expected scenario, and S feasible alternatives generated using the nonparametric bootstrap described in algorithm 1. Given that the use of a large set of scenarios is likely to result on a good approximation to the real potential distribution of parameters, high values of this metric would imply higher sensitivity to likely deviations from the expected scenario and, therefore, lower reliability.

The *Extreme Risk* metric is closely connected to the previous one. Both share the same definition, but they differ in the set scenarios that is considered. In this case, it considers the behaviour of the portfolios in the solution when they face the worst-case scenarios. These are defined as the w resampled scenarios, out of a S sample, with the highest average Mahalanobis distance between the risk/return of the portfolios evaluated with these parameters and the expected risk/return of the same portfolios. The higher the metric, the lower the robustness.

Finally, *Unrealized Returns* evaluates, for every portfolio in the solution, the difference between its realized return and the maximum potential return for that risk level. It represents potential income left on the table. Hence, the higher the value for this indicator, the larger the unrealized potential returns. This means a low value for this indicator would be considered desirable.

3. Experimentation

The combined approach described before was tested with historical financial data using the four mentioned core algorithms: NSGA-II, SPEA2, GDE3 and SMPSO. In this section we report details on the experimental design, sample used, parametrization and results.

3.1. Experimental Setup

The approach was tested on a set of historical returns for the components of the Spanish broad financial index IBEX-35. The experiments were performed using a sample of 240 monthly returns, 20 years worth of data, covering the period from January 1994 to December 2013. Given that the composition of the index changed during the period, we selected the companies in the index as of the end of 2013 for which the was complete data. That meant that original set of 35 companies was reduced to 18. The source for the data was the commercial provider *Datastream*.

The cardinality constraints $[C_{min}, C_{max}]$ and the limits to the minimum and maximum weight that each asset can potentially have in the portfolios that are part of the solution $[lim_{inf}, lim_{sup}]$, were set to $[2,16]$ and $[0.1,0.8]$ respectively.

In order to assure that the algorithms face a wide range of historical situations, we decided to use a sliding window approach. This means that the algorithm relies on data from t_1 to t_n to identify the best possible allocations for the period t_{n+1} . For this purpose, the size of the mentioned window was set to $n = 120$ return periods, that is, to 10 years of data. Therefore for each experiment the 10-year window will move one month, 120 times in total. It is worth noting that this is not a single testing ground for

a dynamic multi-period approach over 120 months, but a set of 120 different single-period portfolio optimization problem instances. Given the stochastic nature of the algorithms used, all the experiments were repeated 30 times.

The implementation was made in jMetal³⁷. This Java framework, designed for multiobjective optimization includes several different metaheuristics. By reusing the base classes of jMetal we ensure a fair comparison as all the alternatives share the same basic core components (solution encodings, operators, etc.). Table 1 shows the parameters used for each algorithm. These have not been optimized and are the default values provided in the framework.

Table 1. Parameters. $L = 18$ (size of individuals). The termination condition is performing 300 iterations.

SPEA2	
Population size	200 individuals
Archive size	200 individuals
Crossover	SBX, $p_c = 0.9$
Mutation	Polynomial, $p_m = 1/L$
Selection of Parents	Binary tournament
NSGA-II	
Population size	200 individuals
Crossover	SBX, $p_c = 0.9$
Mutation	Polynomial, $p_m = 1/L$
Selection of Parents	Binary tournament
SMPSO	
Archive size	200 particles
Swarm size	200 particles
Mutation	Polynomial, $p_m = 1/L$
GDE3	
Population size	200 individuals
Crossover	DE crossover, $CR = 0.9$
Mutation	DE mutation, $F = 0.5$
Selection of Parents	DE selection

Regarding the parameters needed to compute the metrics, the number of scenarios S necessary to compute Stability and Extreme Risk will be set to 500. The second indicator would also require the specification the percentage of worst-case scenarios, out of those 500, to be considered. In this case, the metric will be based on the worst 1%, that is, $w = 5$.

3.2. Results

The combined approach was tested on the four MOEAS already introduced (SPEA2, NSGA-II,

GDE3 and SMPSO) using four different filters: KR2, KR4, KR8 plus the one based of Plerou *et al.*. The robustness of the solutions was assessed using EE, ST, ER and UR. For each of these metrics, we report the average, median and variance obtained with every setup over the 30 runs in tables 2 to 5. We also report the results for the basic algorithms and tested the statistical significance of the differences between the basic algorithm and the robust versions. Due to the lack of normality of the distribution, we relied on the Wilcoxon test.

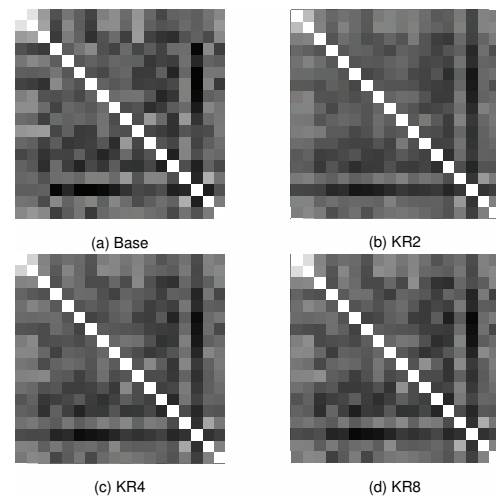


Fig. 2. Correlation matrices. Base vs KR filtering.

The effect of KR2, KR4 and KR8 filters on the correlation matrix is illustrated in figure 2. This panel shows a graphic representation of correlation matrices in gray-scale. Given that we have 18 investment alternatives, each graph consists of a 18x18 symmetric grid. The lighter the color, the larger the number, hence the fact that the main diagonal, where the correlations are always equal to one, is white. This way, we can observe the differences between the original noisy matrix and the filtered versions. In this example, the underlying data corresponds to the first time period considered in the sliding window, that is, returns from January 1994 to December 2003. As we can see, the cross correlations of the returns for the 18 companies tend to be low. We can infer from the graphs that KR2 filtering affects the original matrix to a higher degree than the rest. Among the other two, KR8 reconstruction leads to more subtle changes.

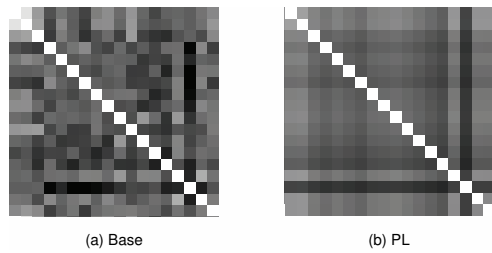


Fig. 3. Correlation matrices. Base vs Plerou *et al.* filtering.

Figure 3 is very similar. It compares side-by-side the original correlation matrix with the reconstructed one once we used the approach by Plerou *et al.* In this case, the scale of the differences in the color pattern makes apparent that this second strategy leads to changes of a larger magnitude than the suggested KR alternatives.

Table 2. *ST* - Stability metric.

SPEA2	Average	Median	Variance
Base	3.9767	3.5364	3.3538
Combined KR2	2.2052	1.9873	0.7706
Combined KR4	2.2154	2.0039	0.7776
Combined KR8	2.2144	2.0080	0.7656
Combined PL	2.2159	2.0007	0.7780
NSGAII	Average	Median	Variance
Base	3.9771	3.5246	3.3746
Combined KR2	2.1250	1.9601	0.6073
Combined KR4	2.1161	1.9395	0.6118
Combined KR8	2.1144	1.9537	0.6008
Combined PL	2.1494	1.9631	0.6131
GDE3	Average	Median	Variance
Base	3.2202	2.9744	1.3919
Combined KR2	2.5142	2.2699	1.0856
Combined KR4	2.5242	2.2935	1.0553
Combined KR8	2.5241	2.2910	1.0459
Combined PL	2.5241	2.2961	1.0371
SMPSO	Average	Median	Variance
Base	3.5175	3.2155	1.6320
Combined KR2	2.3057	2.1029	0.7250
Combined KR4	2.3055	2.1090	0.7431
Combined KR8	2.3064	2.1258	0.7174
Combined PL	2.3301	2.1410	0.7686

Table 2 shows the main descriptive statistics for the Stability robustness indicator. In terms of stability, NSGA-II is the core algorithm that obtains the best values for both the metric and the largest average improvement. The Daly *et al.*-based KR filters combined with the time-stamped resampled ap-

proach offer the best performance for all the core algorithms with the exception of GDE3. The results for the same filters are similar, but the filter described by Plerou *et al.* tends to offer slightly worse results. Combined KR8 over NSGA-II improves the basic value of the metric by 46.8%. It is worth noting that the combined approach offers, in addition to a lower mean value for the metric, a clearly smaller variance.

Table 3. *EE* - Estimation Error metric.

SPEA2	Average	Median	Variance
Base	1.2068	0.8152	1.2250
Combined KR2	0.8843	0.7421	0.5085
Combined KR4	0.8742	0.7461	0.5087
Combined KR8	0.8664	0.7340	0.4984
Combined PL	0.9035	0.7470	0.5435
NSGAII	Average	Median	Variance
Base	1.2038	0.8630	1.0827
Combined KR2	0.8541	0.7090	0.4956
Combined KR4	0.8402	0.6923	0.4920
Combined KR8	0.8412	0.6926	0.4854
Combined PL	0.8787	0.7078	0.5409
GDE3	Average	Median	Variance
Base	1.2314	1.0071	0.7354
Combined KR2	1.0840	0.9054	0.6934
Combined KR4	1.0777	0.9086	0.6717
Combined KR8	1.0788	0.9177	0.6885
Combined PL	1.1398	0.9472	0.8058
SMPSO	Average	Median	Variance
Base	1.2943	1.0869	0.7762
Combined KR2	1.0137	0.8998	0.5291
Combined KR4	1.0131	0.8751	0.5268
Combined KR8	1.0048	0.8756	0.5046
Combined PL	1.0426	0.9122	0.5432

The indicator that captures the discrepancy between the expected behavior of the selected portfolios and reality, EE, shows clear pattern of improvement across basic algorithms and filtering strategies. Having said that, the contribution of the combined approach is more variable and tends to be relatively lower if we compare it to the previous metric. Out of the four basic algorithms, NSGA-II provides the best starting point with an average error of 1.2 (very close to the result of the naked version on SPEA2). The combined robust approaches also tend to be specially appropriate with this algorithm as it offers the lowest average value for the metric. In this case, the improvement in relative terms is not as sizeable as it

was for ST. PL filtering clearly offers results that are worse than KR alternatives. KR4 and KR8 tended to offer the best results. The former one with NSGA-II and GDE3, and the latter with SMPSO and SPEA2.

Table 4 shows the results regarding the sensitivity of the solution to a set of worst-case scenarios where the deviations in terms of risk and return are especially relevant, the robustness indicator labeled Extreme Risk. Given that ER and EE are so closely linked, it is not surprising that they show a similar behavior. Once again, the combined approach improves the robustness of the basic algorithms across the board, but the degree to which these algorithms benefit varies. NSGA-II offers the best results followed by the other genetic algorithm, SPEA2, SMPSO and GDE3. The best combinations were also consistent and KR4 and KR8 resulted in lower values for the metric than PL.

Table 4. ER - Extreme Risk metric.

SPEA2	Average	Median	Variance
Base	1.5884	1.2105	1.2846
Combined KR2	1.2174	1.0547	0.6234
Combined KR4	1.2014	1.0504	0.6028
Combined KR8	1.2000	1.0404	0.6026
Combined PL	1.2087	1.0600	0.6668
NSGAII	Average	Median	Variance
Base	1.5944	1.2877	1.1464
Combined KR2	1.1823	1.0095	0.6262
Combined KR4	1.1710	1.0011	0.6077
Combined KR8	1.1746	1.0132	0.6037
Combined PL	1.1866	1.0155	0.6839
GDE3	Average	Median	Variance
Base	1.6226	1.4283	0.9005
Combined KR2	1.4616	1.2669	0.9286
Combined KR4	1.4484	1.2774	0.8906
Combined KR8	1.4489	1.2697	0.9054
Combined PL	1.4813	1.2649	0.9846
SMPSO	Average	Median	Variance
Base	1.6961	1.5109	0.8972
Combined KR2	1.4381	1.2716	0.7167
Combined KR4	1.4425	1.2509	0.7200
Combined KR8	1.4350	1.2503	0.7055
Combined PL	1.4575	1.2724	0.7765

The combined approach also has a positive impact on the divergence between the Pareto front defined by the selected portfolios and the actual observed efficient frontier once the key parameters were known. Table 5 shows that the addition of the combined ap-

proach designed to increase robustness reduces the amount of money left of the table for all cases. The best results were obtained with SMPSO. The multi-objective PSO, combined with the time-stamped resampling and a KR8 filtering, achieved a 34.7% improvement over the basic SMPSO. As we can see in the variances, the algorithm also turns out to be, by far, the most consistent alternative among algorithm runs. Consistently with the rest of the quality indicators, the performance of PL filtering was slightly worse than the Daly *et al.*-based KR alternatives

Table 5. UR - Unrealized Returns metric.

SPEA2	Average	Median	Variance
Base	8.4864	7.3674	24.3744
Combined KR2	5.9254	5.3010	8.6752
Combined KR4	5.9204	5.2848	8.6298
Combined KR8	5.8911	5.2439	8.4073
Combined PL	5.9489	5.3033	8.8232
NSGAII	Average	Median	Variance
Base	8.4063	7.4374	22.6234
Combined KR2	5.8588	5.2758	8.3047
Combined KR4	5.8228	5.2553	8.0605
Combined KR8	5.8288	5.2678	8.0573
Combined PL	5.9400	5.3924	8.9086
GDE3	Average	Median	Variance
Base	6.2664	5.6185	12.3380
Combined KR2	4.7809	4.1935	9.5771
Combined KR4	4.7840	4.2502	8.9486
Combined KR8	4.7521	4.1845	8.8256
Combined PL	4.7894	4.2482	9.1235
SMPSO	Average	Median	Variance
Base	6.6458	5.8349	13.3521
Combined KR2	4.3572	3.8316	5.3117
Combined KR4	4.3420	3.8478	5.4500
Combined KR8	4.3850	3.8172	5.4756
Combined PL	4.3859	3.8898	5.2117

The results of the experimentation suggest that the combined strategy improves the robustness of the solutions. The gain obtained depends on the metric and core algorithm, but the final effect is always positive. The choice of the filtering mechanism affects the results, and there is a clear pattern that shows that KR filtering contributes to enhance robustness to a greater degree than PL. Among KR options, KR4 and KR8 generally are the best alternatives. Despite these differences, in every instance the combined approach led to sizable improvements in all metrics with respect to the non-robust standard

algorithms. All the reported median differences between the baseline values of the metric for the standard MOEAs and the robust versions were significant at 1%.

4. Conclusions

The issue of robustness is one of the most important open research lines in financial portfolio optimization. The fact that traditional methods tend to be very sensitive to deviations on the estimates for future returns and the associated variance-covariance matrix often leads to unreliable forecasts for the efficient frontier. For this reason, in this paper we suggested using a combined approach that adds time-stamped resampling over four evolutionary multiobjective algorithms and random matrix theory based filtering.

The combined approach was run on four filtered set of parameters. Out of these, three corresponded to the strategy based on Krzanowski stability suggested by Daly *et al.* and the fourth to the alternative introduced by Plerou *et al.*. The first three were specifically KR2, KR4 and KR8, the combination of parameters that offered the best results in previous financial portfolio optimization tasks. All of these reconstruction strategies were tested on a 20-year return series on the components of the Spanish broad index, IBEX-35, using four core algorithms: two genetic algorithms NSGA-II and SPEA2, a representative of multiobjective differential evolution, GDE3, and a multiobjective particle swarm optimization algorithm, SMPSO.

The stability of the solutions was assessed based on four different metrics: stability, estimation error, sensitivity to extreme scenarios and unrealised returns. The use of the combined approach improved significantly the stability of the final solution regardless of the filtering chosen. Having said that, KR strategies, specially KR4 and KR8, clearly outperformed Plerou *et al.* The choice of the basic metaheuristic did not have any impact on that regard, as the mentioned pattern was very prevalent. It made, however, a big difference in terms of obtaining the most robust portfolios. No core algorithm offered better results than the rest across all of the four ro-

bustness indicators, but NSGA-II turned out to be the dominant one. This genetic algorithm offered the best performance for ER, EE and ST. SMPSO provided the best results in terms of UR, as its portfolios tended to be closer to the actual efficient frontier. For this reason, unless the decision maker had a very special interest in UR, among the reviewed alternatives we would recommend NSGA-II.

Future extensions of this work might include the increase of range of core algorithms tested, a comprehensive optimization effort on the parameters of each algorithm or the analysis of the scalability of the approach with larger sets of investment alternatives.

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