# Electricity Peak Load Forecasting using CGP based Neuro Evolutionary Techniques

### Gul Muhammad Khan, Rabia Arshad

Centre for Intelligent Systems and Networks Research(CISNR), UET Peshawar Email:gk502@uetpeshawar.edu.pk, rabia.arshad@nwfpuet.edu.pk

Received 2 June 2015

Accepted 27 January 2016

### Abstract

Proficient Economic and Financial planning is critical to the successful and efficient operation of power generating and distributing units. This planning becomes quite facile if the accurate and precise knowledge regarding the required power load is ascertained. This research is an innovative effort to bring forward different electric peak load forecasting models based on the Neuroevolutionary technique known as the Cartesian Genetic Programming Evolved Artificial Neural Network(CGPANN). Although CGPANN in itself is not novel but its application to power load forecasting is quite unique because of its innate ability to identify the best computationally efficient predictive model along with the recognition of the best appropriate features for load forecasting. Both the Feedforward and Recurrent CGPANN setups have been evolved here for peak load forecasting on a daily basis. The different setups developed have been trained and tested on the peak load data of United Kingdom National Grid. The models developed in this research have been tested and compared against previously proposed machine learning models. In comparison to contemporary models in the field, a more efficient and accurate peak load forecasting model has been produced using CGPANN based prediction methods.

Keywords: load forecasting, evolutionary algorithm, Cartesian Genetic Programming, CGPANN.

### 1. Introduction

Efficient and optimal utilization of electric power is directly dependent upon practical knowledge of the user consumption needs and requirements. Accurate and complete estimation of the required electricity loads is compulsory for the competent operation of a power generation unit. A number of important and critically complex issues become prevalent when an increase in the growth of power generation capacity is considered. The most important problem among these issues is the maximization of optimal performance achievement with increased operation of electric power utilities. Precise Load Forecasting has thus become necessity for the power utilities

to deal with future economic growth while maintaining maximum operational efficiency. Moreover a competent load forecasting technique is not only beneficial for the suitable design of an adept power production and supply system, but also aides in the management of electric power with correct financial and monetary planning during power generation. Accurate forecasts have nowadays become crucial while planning the maintenance schedule and strategy of power generators. This also assists in making the choice for a correct combination of the available on-line capacity.

Load forecasting can be distinctively divided into three different kinds or categories. The first kind is the long term load forecasting which predicts the loads for a time frame of a year or more. The second kind is the medium term load forecasting which forecasts load for a month ahead time, and the third is the short term load forecasting which gives the load predictions on half-hourly, hourly, daily or on a weekly basis. The current research is an initiative to develop intuitive and smart systems for the short-term daily peak load forecasting using an efficient Neuroevolutionary technique known as the Cartesian Genetic Programming Evolved Artificial Neural Network(CGPANN). Neuro-Evolution is an innovative approach that leads to the artificial evolution of the entire structure as well as the components of an Artificial Neural Network(ANN). A CGPANN is a technique developed by incorporating the features of both Cartesian Genetic Programming(CGP) 23 and ANNs, while using Neuroevolution to evolve the final network. The CGPANN inherits many important features of the ANN along with the quality of being Feedforward or Recurrent. The use of both the Feedforward as well as Recurrent CGPANN for short term daily peak load forecasting is quite innovative as it helps in identifying computationally efficient models. Moreover it helps in selecting the appropriate features on the basis of which the best decision regarding the required optimal load can be taken. The CGPANN based forecasters provide better accuracy than most models introduced till date as they have the flexibility of complete network parameter optimization with the best feature selection. Thus the introduction of CG-PANN to the said application of load forecasting is quite noteworthy. The current research is therefore an effort to develop four different kind of forecasters using both the Feedforward as well as Recurrent CGPANN models. A comparison of the models proposed here with previously short term peak load forecasters greatly highlights the superior performance of the CGPANN models over previously proposed methodologies.

### 2. Literature Review

### 2.1. Electric Power Load Forecasting

Forecasting has been addressed in many different ways in literature. Mostly the techniques discussed

involve financial and power load forecasting. Forecasting has also been applied to stock exchange in order to predict the future currency trends. Harrald and Kamstra 35 have evolved Artificial Neural Networks(ANNs) to combine the financial forecasts. They compared the evolved ANNs against various linear methods with ANN models giving a superior performance as compared to the linear forecasting models like Least Mean Square Method. Wagner et al. <sup>36</sup> have developed a Dynamic forecasting genetic programming model for time series prediction and have tested the forecasting efficiency using both real-time and simulated data. The choice of fitness measure plays a significant role in their forecasting model. Yu et al. 37 have used Genetic Programming to produce a Least Square Support Vector Machine(LSSVM) for predicting stock market trends. The LSSVM input features during learning are selected by a Genetic Algorithm. The developed model outperforms many of the previously proposed forecasting models in terms of hit ratio. Huang et al. <sup>14</sup> have developed a Hierarchical Co-evolutionary Fuzzy Predictive Model(HiCEFS) for forecasting financial time series. The developed model uses a careful strategy for trading on the basis of Percentage Price Oscillator(PPO).

Nogales et al. <sup>38</sup> have used time series analysis tools, namely dynamic regression and transfer function models for prediction of electricity prices for the next day. Both techniques have been compared against each other on real world case data of Spanish and Californian Markets. The developed models give 3-5% prediction error. Conejo et al. <sup>39</sup> proposed a day ahead electricity price forecasting model using wavelet transform and Autoregressive Integrated Moving Average (ARIMA) model. The model has been tested on the real time pricing data of main land Spain within the year 2002 producing competitive performance.

Kalman filtering based load forecasting are one of the oldest predictive techniques utilized for power load forecasting. One of the most common form of Kalman filtering based predictive technique is the Phase Locked Loop filter <sup>1</sup>. It utilizes pattern recognition techniques along with weather patterns to predict hourly electric load. Zhang et al. <sup>2</sup> used a hybrid

technique based on the combination of Kalman filter and wavelets to develop two models for prediction of load on hourly basis. One of these models is weather sensitive and the other insensitive. Another hybrid technique involving a combination of the Kalman Filter along with Elman Neural Network was proposed in <sup>3</sup>. It uses Kalman filter to predict the linear parameters and Elman Neural Network the non-linear parameters.

Al-Hamadi and Soliman 4 utilized a technique based on the hybridization of the Kalman Filter and Fuzzy logic to predict the short term peak load based on the current weather patterns as well as the recent past history. Multiple regression based techniques utilizing more than one parameter can also be utilized for load forecasting. A short term load forecasting model has been proposed by Charytoniuk et al. <sup>5</sup> using a non parametric regression model. It was beneficial and uncomplicated, since it required easily calculated small number of parameters. Papalexopoulos and Hesterberg <sup>6</sup> developed a new kind of hourly load forecasting model using regression models which initially predicted the maximum daily load and then this value was used to predict peak load on an hourly basis. Hagan and Behr <sup>16</sup> used time series analysis application methods for load forecasting. They used the Box-Jenkins ARMA model. The average mean error obtained by them was 3.37%.

One of the traditional approaches employed for load forecasting is the exponential smoothing. It can either be used for time series smoothing or directly for load forecasting. Christiaanse <sup>8</sup> proposes a predictive model based on General Exponential Smoothing (GES). Training of the system is performed on hourly data and the developed model predicts peak load based on a lead time range of 1 to 24 hours. A short term load forecasting prediction model has been proposed by El-Keib et al. <sup>12</sup>based on Adaptive General Exponential Smoothing (AGES). AGES in the proposed system has been combined with power spectrum analysis for development of a forecasting model that is quite adaptable and robust. Infield and Hill <sup>13</sup> have introduced optimal smoothing based on a trend removal technique for the prediction of load on a short term basis. The proposed model reduced the root mean square error RMSE for forecasting by 12%. Jong-Hun Lim <sup>9</sup> developed an improved short-term load forecasting algorithm for an arbitrary education institute for fluctuations in the daily, weekly, and yearly load patterns. He analyzed and correlated it with temperature trends during the respective periods. An optimal exponential smoothing coefficient according to the selected period was used for the building load forecasts. The estimated optimal exponential smoothing coefficient derived for each selected period was then compared with past load patterns. The proposed algorithm was verified by simulation of the electric demands showing that the forecasting accuracy of the proposed algorithm is improved comparing with traditional exponential smoothing analysis having a MAPE value of 3.61%.

Ramos et al.<sup>11</sup> developed a load forecasting method for short-term load forecasting (STLF), based on Holt-Winters exponential smoothing and an artificial neural network (ANN). His main contributions was the application of Holt-Winters exponential smoothing approach to the forecasting problem and, as an evaluation of the past work, data mining techniques were also applied to short-term Load forecasting. Both ANN and Holt-Winters exponential smoothing approaches were compared and evaluated obtaining a MAPE of 7.6% being the best performance.

Support Vector Machine (SVM) based supervised learning methods have also been employed for Daily Load Forecasting. Chen et al. <sup>17</sup> developed an SVM based model for daily peak load estimation based on a lead time of 31 days. The error recorded for the proposed model was within 2-3%. Pai and Hong <sup>18</sup> introduced a load forecasting model that was a combination of the Genetic Algorithm (GA) and Recurrent SVMs (RSVMG). The GA in the model predicted the free parameters of the SVM. The proposed model was claimed to produce better results than SVMs, Artificial Neural Networks (ANNs) and regression models.

Artificial Neural Networks(ANN) based load forecasting is one of the most popular techniques for load forecasting. Peng et al. <sup>19</sup> developed an ANN model for load forecasting in which they in-

corporated the effect of holidays and "sudden environmental changes" factor. S.T Chen et al. <sup>20</sup> developed an ANN based forecasting model for 24 hours of a day with a lead time of 168 hours. Their model forecasted the weather sensitive load only. It was claimed to perform better than most of the ANN based forecasting models. Bakirtzis et al. <sup>21</sup> proposed a Bayesian Combined Predictor (BCP) having ANN based estimators with regression predictors for short term load forecasting. The average error obtained with BCP was estimated to be 2.07%.

Hong et al. <sup>7</sup> proposed three key elements of long term load forecasting: predictive modeling, scenario analysis, and weather normalization. The predictive models attained high accuracy from hourly data, in comparison to classical methods of forecasting using monthly or annual peak data. Further development of probabilistic forecasts through cross scenario analysis has enhanced the results. They have achieved an accuracy of 4.2% on average.

Panday et al. 10 proposed procuring of Power through energy exchange based on forecasting of day-ahead load demand. There work discussed the role of ANN in day-ahead hourly forecast of the power system load in Uttar Pradesh power corporation India ltd(UPPL) so as to minimize the error in demand forecasting. A new artificial neural network (ANN) has been designed to compute the forecasted load of UPPCL. The data used in the modeling of ANN are hourly historical electricity load data. The ANN model is trained on hourly data from UPPCL from April, 2014 to June, 2014 and tested on outof-sample data of two weeks. Simulation results obtained have shown that a day-ahead hourly forecast of load using proposed ANN was very accurate having an average MAPE of 3.05%.

Sahay et al.<sup>15</sup> designed a new artificial neural network (ANN) to compute the forecasted load. The data used in the modeling of ANN were hourly historical data of the temperature and electricity load. The ANN model was trained on hourly data from Ontario Electricity Market from 2007 to 2011 and tested on out-of-sample data from 2012. Simulation results obtained have shown that day-ahead hourly forecasts of load using proposed ANN generated an average MAPE of 2.05% with temperature and

2.23% without temperature.

Chen et al. <sup>29</sup> proposed a two-stage identification and restoration method to detect the typical patterns of inaccurate measurement and abnormal disturbance based on statistical criteria independent with normal distribution in first stage and Historical trend in second stage using frequency domain decomposition. The deviations of the data measurements from the typical daily curve obey normal distribution and were used as criteria in the second stage. The effectiveness of the proposed methodology has been confirmed by examples in real bus load forecasting systems obtaining a MAPE of 1.8%.

This section highlighted various load forecasting models introduced in the field, and indicated there performance in terms of MAPE values. These models are also tabulated in Table .3, 4 for comparison with the proposed models. The next section will provide a detailed overview of Cartesian Genetic Programming(CGP) the genetic programming method used in this work for evolution of Neural Networks.

### 2.2. Cartesian Genetic Programming (CGP)

Cartesian Genetic Programming developed by Miller and Thompson <sup>23</sup> is a kind of genetic programming originally introduced for the evolution of feed forward digital circuits. CGP is composed of nodes or genes that make up a genotype. The genotype is a 2D grid having rows and columns. Every gene or node within this grid has inputs and a function operating on the inputs. Each node produces an output, which can then be fed as inputs to the nodes of the next columns. A CGP genotype also called a chromosome is represented as a stream of bits or integers giving information regarding each node connectivity and functions. The phenotype representation is the directed graph which shows the connectivity of the system inputs via the nodes to the system's outputs. The fitness of each genotype determines its selection as a parent for future generation. It also determines whether the parent should be mutated to populate the next generation of offspring or should be selected as the best evolved solution. The mutation in CGP is via a single parent only. Mutation of parent involves either the mutation of an entire node, its inputs or node functions. During evolution such nodes may arise whose outputs are neither connected to the inputs of the following nodes or to system outputs. These are the junk nodes. This gives a very unique property of CGP that each and every node in CGP might not be contributing to the overall evolved circuitry. CGP has been used to develop many efficient applications <sup>30</sup>, <sup>31</sup>, <sup>32</sup>.

### 2.3. Neuro-Evolution

Neuro Evolution is a phenomenon which leads to the artificial evolution of Neural Networks. Such process leads to the complete component-wise evolution of a Neural Network framework as it embodies a change in the system inputs, outputs, neuron functions, neuron's input, weights and the complete network topology. Evolution of a specific single parameter like neuron functions, while keeping all other components fixed limits the search space leading to an ineffective solution <sup>24</sup>. Gomez et al. propose the creation of a genotype that represents the entire network solution by using Conventional Neural Evolution (CNE) <sup>25</sup>. An obvious advantage of their proposed method is that rather than evolving the chromosomes at the Neural level, it evolves them at the network level. This results in a possibly global solution. Symbiotic Adaptive Neural Evolution (SANE) <sup>26</sup> proposed by Moriarty has the ability to evolve network topology along with the neural population. Gomez et. al have proposed an extension to SANE by the name of Enforced Sub-Population (ESP) <sup>25</sup>, having the capability to evolve a subpopulation of hidden layer neurons. Polani and Miikkulainen has proposed an extension to SANE known as Eugenic SANE (EuSANE) 48 having reinforced learning as its base concept.

Stanley and Miikkulainen have presented Neuro Evolution of Augmented Topologies(NEAT) resolving the issues of gene tracking by including historical marking, using speciation to retain innovation and lead to the formation of a complex network while starting at a simple one <sup>49</sup>. Stanley later presented a real time NEAT(rtNEAT) performing real time Neuro evolution <sup>28</sup>. Reisinger et al. then presented modular NEAT, which divided the large search space into sub parts for finding solution to a complex problem <sup>50</sup>.

# 3. Cartesian Genetic Programming evolved Artificial Neural Network (CGPANN)

The methodology proposed for the purpose of peak load forecasting involves the use of Cartesian Genetic Programming evolved Artificial Neural Networks(CGPANN) <sup>33</sup>, <sup>34</sup>. Proven to be an efficient Neuro-Evolutionary technique, CGPANN has the strength to artificially evolve all the parameters of an Artificial Neural Network(ANN). The evolution with the CGPANN algorithm is a continuous process, which is halted only if a reasonably accurate solution is reached.

The CGPANN inherits key characteristics of a conventional Artificial Neural Network(ANN) i.e system inputs, nodes/neurons, node's inputs, connection weights, activation functions within the node, node's outputs and system outputs. It also inherits the ANNs mode of operations i.e. the CG-PANN can also operate in a Feedforward or Recurrent mode like an ANN. As the name implies a Feedforward CGPANN (FCGPANN) does not have any recurrent nodes as input to the network. While on the other hand a Recurrent CGPANN (RCGPANN) along with the system inputs also has feedback or recurrent nodes as input to the network. A conventional node/neuron within an FCGPANN takes in as input the outputs of preceding nodes or system inputs, multiplies these with a certain weight lying in the range [-1,1] and sums up the weighted inputs. An activation function finally operates on the weighted sums to produce the node output. A simple node within the RCGPANN behaves in the same manner, however it can also take in as input the output from a recurrent node. A recurrent node within an RCGPANN operates by taking in as input all the main system outputs and the rest of it's functionality remains the same as that of a conventional/simple node. The number of recurrent nodes in a RCG-PANN are decided upon by setting a feed-back rate. In the current research both the FCGPANN and the RCGPANN algorithms are demonstrated using the peak load data of ten previous days to predict the peak load of the eleventh day. The future populations produced during evolution of FCGPANN and RCGPANN employ the  $1+\lambda$  (one parent with  $\lambda$  offspring) strategy <sup>23</sup>. The connections within the FCGPANN or RCGPANN are decided upon during evolution. At different evolutionary stages, such networks may arise in which the outputs from the simple nodes are not being utilized as inputs to the following nodes or being connected to the system outputs. Such nodes are termed as junk nodes or redundant nodes. These nodes may or may not become operational in future network evolutions. A node within the FCGPANN is shown in Fig. 1. The figure shows that the inputs to the nodes are represented by  $I_{10r2}$  and are multiplied by the weights  $W_{10r2}$ . The function F operates on weighted sum of these inputs to produce the output O. A simple node within an RCGPANN is the same as the one shown in Fig. 1 and the difference between a simple and a recurrent node in an RCGPANN can be seen from Fig. 3. The recurrent node takes in as input the system outputs, while a simple node within the RCGPANN can take input from system inputs, preceding node inputs or recurrent node outputs.

The genotype in an FCGPANN or an RCGPANN gives a coded algorithmic representation of the network, that is then evolved to a phenotype which gives the structural representation of the same network. The genotype and phenotype representation of an FCGPANN and RCGPANN can be viewed from Fig. 2 and Fig. 4. From Fig. 2(a), it can be seen that all the columns except the last one represent the nodes within the genotype and the last column gives the connectivity of the system outputs. The node is represented by node inputs with their respective weights followed by the activation function. Fig. 2(b) represents the phenotype inferred from the genotype of Fig. 2(a). In Fig. 2(a) the column with grey color and in Fig. 2(b) the neuron within the dotted boundary are representations of junk nodes. For the RCGPANN genotype in Fig. 4(a), the first column shows that the 2nd output of the system is being fed back to the system and is being utilized as an input to the first node. Fig. 4(b) shows the phenotype representation of the genotype specified in Fig. 4(a). Junk nodes also exist in an RCGPANN, as can be viewed from the gray color column (genotype) and the dotted boundary gene (phenotype) of Fig. 4. Recurrent junk Neurons also exist in an RCGPANN. In

fact there may arise a system during evolution where all recurrent neurons/nodes are redundant.

### 3.1. FCGPANN and RCGPANN Algorithm

The FCGPANN and RCGPANN algorithm can be explained from the following scheme of implementation.

### i START

### INPUTS

- (a)  $N_{node}$ : Total number of neurons in a genotype.
- (b)  $S_{Input} = [i_1, i_2, ..., i_k]$ : System Inputs Vector. Where k = 1, 2, ..., K, with K being the total number of system inputs.
- (c)  $N_{geno}$ : Total number of genotypes produced within a single evolutionary run.
- (d) act<sub>F</sub> = [a<sub>f1</sub>, a<sub>f2</sub>,....., a<sub>fp</sub>]: Chromosome activation function list. Where p = 1,2,...,P, with P being the number of activation functions in the list. Here only log-sigmoid is used as activation function, since it's output is in the range of 0 and 1. The input data is also normalized in the same range. Log-sigmoid function is given by the following expression:

$$y = \frac{1}{1 - \exp(-x)}$$

- (e)  $I_{node}$ : Total number of neuron inputs.
- (f)  $\mu\%$ : Mutation rate.
- (g)  $fit_{thresh}$ : A fitness threshold value for stopping evolution process.
- (h)  $R_{\mu}$ %: Feedback rate (input for RCGPANN only).

### • OUTPUTS

- (a) System Output Vector Array  $S_{OV} = [op_1, op_2, ....., op_l]$ , where l = 1, 2, ...., L, with L being the total number of system outputs.
- (b) System Recurrent Nodes S<sub>Recurr</sub> (output for RCGPANN only).
- ii INITIAL Populate  $N_{geno}$  genotypes by using a pseudo random number generator  $^{51}$ . Initialize the  $I_{neu}$  inputs of  $N_{neu}$  neurons of all  $N_{geno}$  genotypes using Equation. 1 in FCG-PANN and using Equation. 3 in RCGPANN. In both the equations,  $\delta$  is the index of input being initialized ( $\delta = 1, 2, ..., I_{neu}$ ),  $\zeta$  is the index of the node whose input is being initialized ( $zeta = 1, 2, ..., N_{neu}$ ) and  $\chi$  is the genotype whose node's input is being initialized ( $\chi = 1, 2, ..., N_{geno}$ ). The inputs in the FCG-PANN are randomly assigned either the outputs of the preceding nodes or the values from system input vector  $S_{Input}$ , while in the RCGPANN, in addition to the preceding nodes and values from  $S_{Input}$ , output of System Recurrent Nodes  $S_{Recurr}$  can also be assigned.

$$ch_{geno}(\chi, \zeta, \delta) = PRG([S_{Input} ch_{geno}(\chi, \zeta - 1) \\ \dots, ch_{geno}(\chi, 1)])$$
(1)

Initialize the activation function of the  $N_{node}$  neurons of  $N_{geno}$  genotypes using equation 2. This equation randomly assigns an activation function from the list of activation functions  $act_F = [a_{f1}, a_{f2}, ....., a_{fp}].$ 

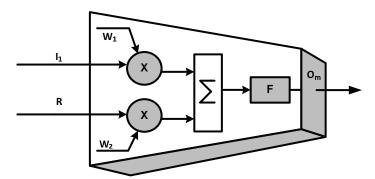


Figure 1: A Simple Neuron within the FCGPANN

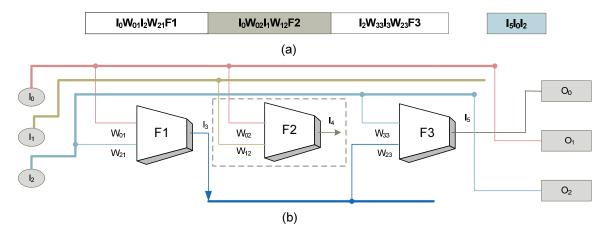


Figure 2: (a) Genotype (b) Phenotype Representation of FCGPANN

$$ch_{geno}(\chi, \zeta, function) = PRG(act_F = [a_{f1}, a_{f2}, \dots, a_{fp}])$$
 (2)

$$ch_{geno}(\chi, \zeta, \delta) = PRG([S_{Input} ch_{geno}(\chi, \zeta - 1) \\ \dots, ch_{geno}(\chi, 1) S_{Recurr}])$$
(3)

Initialize the activation function of the  $N_{node}$  neurons of  $N_{geno}$  genotypes using equation 4. This equation randomly assigns an activation function from the list of activation functions  $act_F = [a_{f1}, a_{f2}, ....., a_{fp}].$ 

$$ch_{geno}(\chi, \zeta, function) = PRG(AF = [a_{f1}, a_{f2}, a_{f2}]$$
 (4)

For each  $\chi$  genotype initialize the system outputs (equation 5) by forming a connection of the system output with either a

system input or with a neuron output. These connections are formed by using pseudo random number generator.

$$S_{OV}(\chi, m) = PRG([S_{Input} : ch_{geno}(\chi, \zeta = 1, .... N_{geno}0)])$$
(5)

iii FITTEST GENOTYPE SELECTION From a total  $N_{geno}$  genotypes, select the genotype that produces the least Mean Absolute Percentage Error(MAPE)  $^{40}$  in a single evolutionary iteration. This genotype is selected as a parent for the next generation. If a parent and child from the current generation have identical minimum MAPE, then choose the child as the new parent  $^{23}$ . The same minimum MAPE used for parent selection is also compared against  $fit_{thresh}$  and if the MAPE value is less than the threshold then the selected parent is chosen as the best evolved system followed by the termination of evolution process. If the best evolved system is not produced then the parent is mutated in step iv to continue evolution towards the best system.

iv **MUTATION** The genotype selected in the preceding step is mutated by  $\mu\%$  to produce  $N_{geno}-1$  offspring. Mutation can be performed by modifying any of its characteristics (i.e neuron inputs, connection weights, activation functions, genotype output connections) selected via a pseudo random number generator. These cataleptics are mutated using equations 1, 2, 3, 4 and 5. After mutation return to step. iii for fitness evaluation of the  $N_{geno}$  genotypes (Parent and Offspring).

v END

### 4. Simulation Setup

Four independent experiments are performed for generating separate prediction models to forecast the daily peak loads. One of the experiment is performed using the FCGPANN, and the other three experiments are performed to evolve RCGPANN setups with different feedback rates.

### 4.1. Setup 1: FCGPANN

The FCGPANN setup(see Fig. 5) evolved for daily peak load forecasting takes in as inputs the peak load data of past ten days to predict the peak load of the next calender day. For the training and system testing hourly load data has been obtained from the United Kingdom National Grid, which operates under extremely variant weather patterns, thus resulting in frequently varying daily peak loads. From this data the daily required peak load has been extracted. The input data is normalized between 0 and 1 in order to synchronize it with the neuron output being in the same range. The FCGPANN model has been trained on the daily peak load data of the complete year 2006 while the testing has been performed and evaluated against the daily peak load data of the years 2007,2008 and 2009. The system has been trained to take in as input peak loads of past ten days and compute the maximum load for the next day. For the evolution of the FCGPANN, the  $1 + \lambda$  approach specified for FCGPANN algorithm <sup>34</sup> is utilized. Where  $\lambda$  is taken as 9 since sufficiently optimal results have been observed for this value <sup>34</sup>. Initially a random population of ten genotypes is produced. The mutation rate is set at 10%. Training and testing has been performed by changing the size of the FCGPANN, i.e. by varying the total number

# 4.2. Setup 2: RCGPANN with 10% Feedback Paths

The next experimental setup is that of a RCGPANN setup (see Fig. 6) having a single recurrent node (i.e. 10% feedback paths). The testing and training of the RCGPANN is done using the same data scenarios as were taken in the case of the FCGPANN setups. Evolutionary strategy of  $1 + \lambda$  as specified in Section. 4.1 is used here. The major difference in this setup and that of FCGPANN of Section. 4.1 is that a recurrent node has been added to the genotypes during evolution.

# 4.3. Setup 3: RCGPANN with 50% Feedback Paths

This setup is practically the same as the previously discussed RCGPANN setup. The only difference lies in the feedback paths, which have now been changed to 50% i.e. 5 recurrent nodes, rather than a single recurrent node as was the case with the setup in Section. 4.2. Fig. 7 shows the RCGPANN setup with 50% feedback paths.

# 4.4. Setup 4: RCGPANN with 100% Feedback Paths

This setup has 10 recurrent nodes as feedback inputs during evolution. All other characteristic of the setup remain the same as the ones specified in Sections. 4.2 and 4.3. The RCGPANN setup with 10 feedbacks can be seen from Fig. 8.

of nodes in the network from 50 to 500, every time with an increment of 50. The total number of inputs per node are set at 5. The FCGPANN networks produce 10 outputs which are then averaged for the final forecast value. During the training phase, the experiments on the different sized FCGPANN setups were performed for a total of two million generations each.

<sup>\*</sup> http://www.tutiempo.net

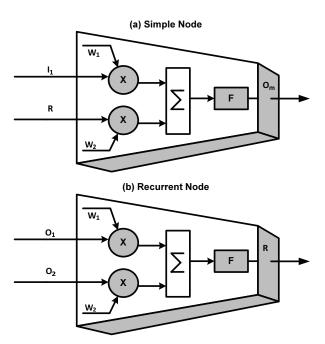


Figure 3: (a) A Simple Neuron within an RCGPANN (b) A Recurrent Node/Recurrent Neuron within an RCG-PANN

### 5. Simulations and Results

Training and testing of the Load forecasting setups has been carried out on a seasonal as well as on yearly basis. For training the data of year 2006 has been utilized, while the testing has been carried out against the data obtained for the years 2007, 2008 and 2009. For training the Root Mean Square Error (RMSE) was utilized for fitness evaluation, while MAPE, Mean Square Error (MSE) and Root Mean Square Error (RMSE) were used for performance evaluation during testing of the setups. The training error for the four types of setups with varying number of nodes can be seen from Table. 1. From the table it can be seen that the minimum RMSE obtained for the FCGPANN steup training is for a total of 350 nodes scenarios. For the RCGPANN setup with single feedback, the best RMSE is obtained for the setup with 250 nodes, while for RCGPANN setups with 5% and 10% feedback paths give the best RMSE with 100 and 250 total nodes respectively.

Table. 2 gives the MAPE values obtained for all the four setups during testing. The FCGPANN setup

with 350 nodes gives the best annual MAPE value for the year 2008. This setup can be seen in Fig. 9. The setup only has two active nodes and calculates the peak load using the expression provided in Equation. 6. The difference between actual and estimated peak load values for the year 2008 using this setup can be seen from Fig. 10. The same setup also gives the minimum MAPE value for the winter season of year 2007. The actual versus estimated forecasts of peak load for winter 2007 with this setup can be observed from Fig. 11. The irregularities between actual and estimated forecasts lie within the period of end November and mid-December of 2007 and can be removed by further fine tuning during training. The data for this specific period can be removed and used to train another network that will serve as forecaster for that time period only. This will enhance the ability for the networks to accurately forecast the data; though will increase the computational cost having two independent networks.

$$Load_{peak} = \frac{1}{10} \left\{ 6i_3 + i_4 + 2i_9 + \left(1 + e^{-2.9977i_3 + 0.9996i_1 + 0.9999(1 + e^{2.4475i_3 - 1.9987i_1})^{-1}}\right)^{-1} \right\}$$
(6)

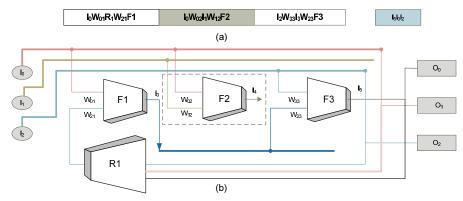


Figure 4: (a) Genotype (b) Phenotype Representation of RCGPANN

Table 1: Training Values MAPE, MSE and RMSE for the four kinds of setups with different Number of Nodes

Model	Feedback Outputs	No of Nodes									
		50	100	150	200	250	300	350	400	450	500
MAPE	0	2.4540	2.4206	2.4538	2.4424	2.4271	2.4432	2.4097	2.5960	2.4208	2.4332
	1	2.4392	2.4160	2.4331	2.4271	2.4108	2.4493	2.4361	2.4737	2.4525	2.4433
	5	2.4887	2.4153	2.4494	2.4321	2.4311	2.4539	2.4452	2.4308	2.4179	2.4472
	10	2.6985	2.6943	2.4538	2.4396	2.4125	2.4433	2.4540	2.4887	2.4400	2.4098
MSE	0	0.1269	0.1279	0.1269	0.1302	0.1269	0.1271	0.1286	0.1465	0.1277	0.1279
	1	0.1280	0.1284	0.1281	0.1281	0.1279	0.1304	0.1325	0.1288	0.1275	0.1315
	5	0.1276	0.1284	0.1275	0.1281	0.1272	0.1269	0.1274	0.1272	0.1279	0.1304
	10	0.1448	0.1486	0.1269	0.1282	0.1276	0.1271	0.1269	0.1276	0.1270	0.1286
RMSE	0	2.4540	2.4206	2.4538	2.4424	2.4271	2.4432	2.4097	2.5960	2.4208	2.4332
	1	2.6985	2.4160	2.4331	2.4271	2.4108	2.4493	2.4361	2.4737	2.4525	2.4433
	5	2.4887	2.4153	2.4494	2.4321	2.4311	2.4539	2.4452	2.4308	2.4179	2.4472
	10	2.4392	2.6943	2.4538	2.4396	2.4125	2.4433	2.4540	2.4887	2.4379	2.4098

From Table.2, it can be observed that the minimum MAPE value for the RCGPANN setup with a single recurrent node is the setup with a total of 200 nodes. The error value is obtained for peak load forecasting during Autumn 2009. The setup can be seen from Fig. 12. The evolved setup has only 4 active nodes. It can be seen from the figure that the recurrent node is also a junk node as its output is not used in the final setup obtained after all the evolutionary runs. This shows an important property of the RCGPANN that there is not a compulsion on the recurrent nodes to be used as inputs to the network. The decision regarding the use of a recurrent node as input is basically on the basis of selection during the evolutionary process. The peak load estimation for

the setup in Fig. 12 is obtained from the expression given in Equation. 7 to Equation. 11. A comparison of the actual versus estimated values for the setup of Fig. 12 can be seen in Fig. 13.

$$Load_{peak} = \frac{1}{10} \{ 7i_3 + 2i_9 + N_{58} \} \tag{7}$$

$$N_{58} = \{1 + e^{1.9969N_{55} - 0.9946i_4 - 1.5802i_3}\}^{-1}$$
 (8)

$$N_{55} = \left\{1 + e^{1.9956N_{23} + 0.8450i_4 - 0.9980i_1 - 0.9978N_1}\right\}^{-1} \quad (9)$$

$$N_{23} = \left\{1 + e^{3.9885N_1 - 0.9997i_4}\right\}^{-1} \tag{10}$$

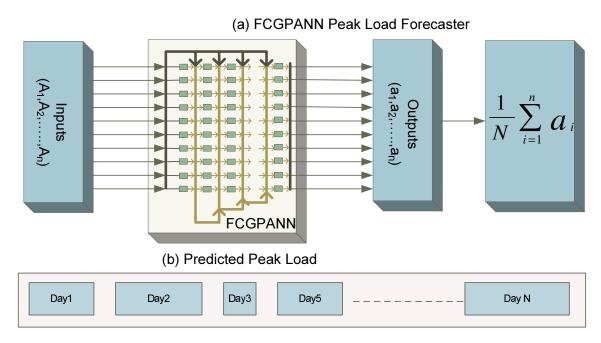


Figure 5: (a) FCGPANN Peak Forecasting Setup (b) Forecasted Peak Loads

$$N_1 = \left\{1 + e^{-1.9947i_1 + 2.6123i_4}\right\}^{-1} \tag{11}$$

A comparison of the currently proposed setups with the contemporary techniques previously introduced can be seen in Table. 3. From the table it is evident that the FCGPANN and RCGPANN are

 $Load_{peak} = \frac{1}{10} \left\{ 6i_3 + 2i_9 + i_4 + \left(1 + e^{-2.9971i_3 - 0.9997i_1 + 0.9999(1 + e^{-2.4522i_3 + 1.9997i_1})^{-1} \right)^{-1} \right\}$ 

It can be further observed from Table.2, that the RCGPANN setup with 5 recurrent node gives the minimum MAPE value for the setup with 150 nodes (see Fig. 14) during August 2009. Equation. 12 gives the expression used for peak load forecasting. The RCGPANN setup with 10 recurrent nodes also gives the minimum MAPE on the seasonal data of Autumn 2009 (see Fig 16). The minimum MAPE for the Spring and Summer seasons is obtained while forecasting values during 2007 and 2008 respectively. For the Spring 2007, the RCG-PANN setup had a total of 250 nodes. The actual versus forecasted values for this setup can be observed from Fig. 15. The expression in Equation. 13 forecasts the estimated values.

Table 4 shows a similar comparison of the Mean Relative Error of RCGPANN-5 setup having a total of 50 nodes with previously proposed techniques showing that the current setup is superior in performance to its predecessors.

competitive in comparison to their predecessors.

### 6. Conclusion

 $Load_{peak} = \frac{1}{10} \left\{ 7i_3 + 2i_9 + \left(1 + e^{-1.9991i_4 - 0.9999i_3 + 1.9996(1 + e^{1.9997i_3 - 2.6203i_1})^{-1}}\right)^{-1} \right\}$ (12)

This work proposes the use of Neuroevolutionary Cartesian Genetic Programming evolved Artificial Neural Networks for the purpose of daily peak load forecasting of electricity loads. The evaluation of the proposed feed-forward and recurrent CGPANN networks for load forecasting is quite

### (a) RCGPANN-1 Peak Load Forecaster (b) Predicted Peak Load Day1 Day2 Day3 Day5 Day N

Figure 6: (a) RCGPANN-1 Peak Forecasting Setup (b) Forecasted Peak Loads

novel and shows very promising results. When compared against previously proposed contemporary techniques, it is observed that the current networks outperform their predecessors and give more than 98% accurate values for daily short term peak load forecasting. The incorporation of the proposed algorithms in power production and distribution units will result in a robust system with sound financial and economical use of power production resources. In future, more parameters such as weather and population growth factor can be added to improve the prediction accuracy even further.

- 1. A. Dehdashti, J. Tudor, and M. Smith, Forecasting of hourly load by pattern recognition a deterministic approach, Power Apparatus and Systems, IEEE Transactions on,101(9),3290 -3294, 1982.
- 2. T. Zheng, A. A. Girgis, and E. B. Makram, A hybrid waveletkalman filter method for load forecasting, Electric Power Systems Research, 54(1), 11-17, 2000.
- 3. Feng Zhao and Hongsheng Su, "Short-Term Load Forecasting Using Kalman Filter and Elman Neural Network", Industrial Electronics and Applications, 1043–1047, 2007.

- 4. Al-Hamadi, H.M. and Soliman, S.A., "Fuzzy short-term electric load forecasting using Kalman filter", IEE ProceedingsGeneration, Transmission and Distribution, 153(2),217 –227,2006.
- 5. W. Charytoniuk, M. Chen, and P. Van Olinda, Non-parametric regression based short-term load forecasting, Power Systems, IEEE Transactions on, 13(3),725-730, 1998.
- A. Papalexopoulos and T. Hesterberg, A regressionbased approach to short-term system load forecasting, Power Systems, IEEE Transactions on, 5(4), 1535 -1547, 1990.
- 7. Tao Hong; Wilson, J.; Jingrui Xie, "Long Term Probabilistic Load Forecasting and Normalization With Hourly Information", IEEE Transactions on Smart Grid, 5(1), 456–462,2014.
- 8. W. Christiaanse, Short-term load forecasting using general exponential smoothing, Power Apparatus and Systems, IEEE Transactions on, 90(2), 900 -911, 1971.
- Jong-Hun Lim, Oh-Sung Kwon, Kyung-Bin Song, Jeong-Do Park, "Short-term load forecasting for educational buildings with temperature correlation", Fourth International Conference onPower Engineering, Energy and Electrical Drives (POWERENG),405

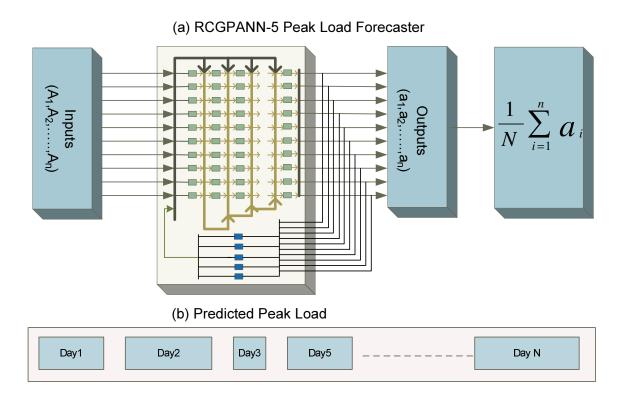


Figure 7: (a) RCGPANN-5 Peak Forecasting Setup (b) Forecasted Peak Loads

- -408, 2013.
- Pandey, A.K.; Sahay, K.B.; Tripathi, M.M.; Chandra, D.,"Short-term load forecasting of UPPCL using ANN", Power India International Conference (PIICON), 2014 6th IEEE, 1 6, 2014.
- 11. Soares, J.; Vale, Z.; Ramos, S., "Short-term load fore-casting based on load profiling", Power and Energy Society General Meeting (PES), IEEE, 1–5,2013.
- 12. A. El-Keib, X. Ma, and H. Ma, Advancement of statistical based modeling techniques for short-term load forecasting, Electric Power Systems Research, 35(1), 51-58, 1995.
- 13. Infield, D.G. and Hill, D.C., "Optimal smoothing for trend removal in short term electricity demand forecasting", IEEE Transactions on Power Systems, 13(3),1115 –1120, 1998.
- 14. S. Huang, Short-term load forecasting using threshold autoregressive models, Generation, Transmission and Distribution, IEE Proceedings-, 144(5), 477 -481, 1997.
- 15. Sahay, K.B.; Kumar, N.; Tripathi, M.M., "Short-term load forecasting of Ontario Electricity Market by considering the effect of temperature", Power India Inter-

- national Conference (PIICON), 2014 6th IEEE, 1 6, 2014.
- 16. M. T. Hagan and S. M. Behr, The time series approach to short-term load forecasting, Power Engineering Review, IEEE, 7(8), 56-57, 1987.
- 17. B.-J. Chen, M.-W. Chang, and C.-J. Lin, Load fore-casting using support vector machines: a study on eunite competition 2001, Power Systems, IEEE Transactions on, 19(4), 1821 -1830, 2004.
- 18. Pai, Ping-Feng and Hong, Wei-Chiang, "Forecasting regional electricity load based on recurrent support vector machines with genetic algorithms", Electric Power Systems Research, 74(3), 417 425, 2005.
- 19. T. Peng, N. Hubele, and G. Karady, Advancement in the application of neural networks for short-term load forecasting, IEEE Transactions on Power Systems, 7(1), 250 -257, 1992.
- 20. S.-T. Chen, D. Yu, and A. Moghaddamjo, Weather sensitive shortterm load forecasting using nonfully connected artificial neural network, IEEE Transactions on Power Systems, , 7(3), 1098 -1105, 1992.
- 21. A. Bakirtzis, V. Petridis, S. Kiartzis, M. Alexiadis, and A. Maissis, A neural network short term load forecast-

# (a) RCGPANN-10 Peak Load Forecaster | The state of the s

Figure 8: (a) RCGPANN-10 Peak Forecasting Setup (b) Forecasted Peak Loads

- ing model for the greek power system, IEEE Transactions on Power Systems, 11(2), 858 -863, 1996.
- 22. L. M. Saini, Peak load forecasting using bayesian regularization, resilient and adaptive backpropagation learning based artificial neural networks, Electric Power Systems Research, 78(7), 1302-1310, 2008.
- 23. J. Miller and P. Thomson, Cartesian genetic programming, in Genetic Programming, ser. Lecture Notes in Computer Science. Springer Berlin Heidelberg, 1802, 121-132, 2000.
- 24. X. Yao, Evolving artificial neural networks, Proceedings of the IEEE, 87(9), 1423 -1447, 1999.
- F. Gomez, J. Schmidhuber, and R. Miikkulainen, Accelerated neural evolution through cooperatively coevolved synapses, J. Mach. Learn. Res., 9, 937 -965, 2008.
- D. E. Moriarty, Symbiotic evolution of neural networks in sequential decision tasks, Ph.D. dissertation, University of Texas at Austin, Austin, TX, USA, uMI

- Order No. GAX98-02963, 1998.
- 27. K. O. Stanley and R. Miikkulainen, Efficient reinforcement learning through evolving neural network topologies, in Proceedings of the Genetic and Evolutionary Computation Conference, ser. GECCO 02, 569 -577, 2002.
- 28. K. O. Stanley, B. D. Bryant, and R. Miikkulainen, Real-time neuroevolution in the nero video game, Trans. Evol. Comp, 9(6),653-668, 2005.
- 29. Xinyu Chen, Chongqing Kang; Xing Tong; Qing Xia; Junfeng Yang, "Improving the Accuracy of Bus Load Forecasting by a Two-Stage Bad Data Identification Method", IEEE Transactions on Power Systems, 29(4), 1634 1641, 2014.
- R. Barzamini, M. Menhaj, A. Khosravi, and S. Kamalvand, Short term load forecasting for iran national power system and its regions using multi layer perceptron and fuzzy inference systems, in Neural Networks, 2005. IJCNN 05. Proceedings. 2005 IEEE In-

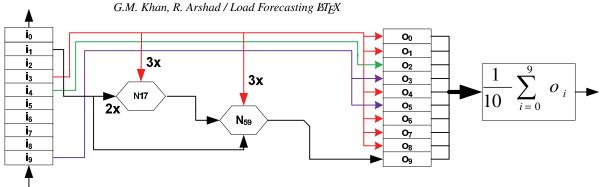


Figure 9: FCGPANN Setup with a total of 350 nodes

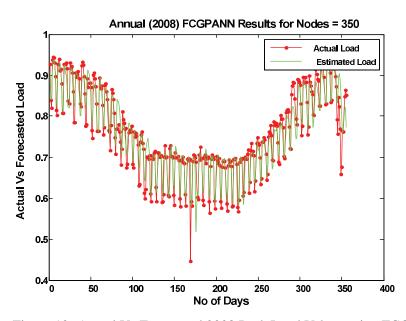


Figure 10: Actual Vs Forecasted 2008 Peak Load Values using FCGPANN setup of 350 Nodes.

- ternational Joint Conference on, 4, 2619 -2624, 2005.
- 31. J. F. Miller, An empirical study of the efficiency of learning boolean functions using a cartesian genetic programming approach, in Proceedings of the Genetic and Evolutionary Computation Conference, vol. 2. Citeseer, pp. 11351142, 1999.
- 32. J. Walker and J. Miller, The automatic acquisition, evolution and reuse of modules in cartesian genetic programming, IEEE Transactions on Evolutionary Computation, 12(4), 397 -417, 2008.
- 33. M. Khan, G. Khan, and J. Miller, Evolution of neural networks using cartesian genetic programming, in Evolutionary Computation (CEC), IEEE Congress on , 1-8, 2010.
- 34. M. M. Khan and G. M. Khan, A novel neuroevolutionary algorithm: Cartesian genetic programming

- evolved artificial neural network (cgpann), in Proceedings of the 8th International Conference on Frontiers of Information Technology, ser. FIT 10, 2010.
- 35. Harrald, P.G. and Kamstra, M.,"Evolving artificial neural networks to combine financial forecasts", Evolutionary Computation, IEEE Transactions on,1(1), 40-52, 1997.
- 36. Wagner, N. and Michalewicz, Z. and Khouja, M. and McGregor, R.R., "Time Series Forecasting for Dynamic Environments: The DyFor Genetic Program Model", IEEE Transactions on Evolutionary Computation, 11(4),433–452, 2007.
- 37. Lean Yu and Huanhuan Chen and Shouyang Wang and Kin Keung Lai,"Evolving Least Squares Support Vector Machines for Stock Market Trend Mining", IEEE Transactions on Evolutionary Computa-

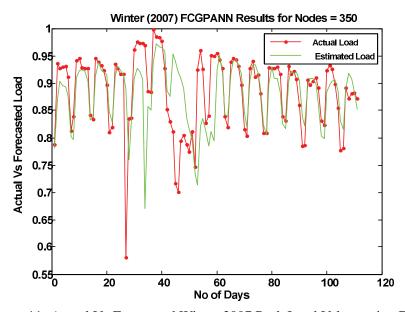


Figure 11: Actaul Vs Forecasted Winter 2007 Peak Load Values using FCGPANN setup of 350 Nodes.

- tion, 13(1), 87 –102, 2009.
- 38. Nogales, F.J. and Contreras, J. and Conejo, A.J. and Espinola, R., "Forecasting next-day electricity prices by time series models", IEEE Transactions on Power Systems, 17(2), 342-348, 2002.
- 39. Conejo, A.J. and Plazas, M.A. and Espinola, R. and Molina, A.B.,"Day-ahead electricity price forecasting using the wavelet transform and ARIMA models", IEEE Transactions on Power Systems, 20(2),1035-1042, 2005.
- 40. J. S. Armstrong and F. Collopy, Error measures for generalizing about forecasting methods: Empirical comparisons, International Journal of Forecasting, 8(1), 69-80, 1992.
- 41. Z. Wang and Y. Cao, Mutual information and non-fixed anns for daily peak load forecasting, in Power Systems Conference and Exposition, PSCE 06. IEEE PES, 1523 -1527, 2006.
- 42. A. Goia, C. May, and G. Fusai, Functional clustering and linear regression for peak load forecasting, International Journal of Forecasting, vol. 26, no. 4, pp. 700-711, 2010.
- 43. M. Ghomi, M. Goodarzi, and M. Goodarzi, Peak load forecasting of electric utilities for west province of iran by using neural network without weather information, in Computer Modelling and Simulation (UK-Sim), 12th International Conference on, pp. 28 -32, 2010.
- 44. L. M. Saini, Peak load forecasting using bayesian regularization, resilient and adaptive backpropagation learning based artificial neural networks, Electric Power Systems Research, 78(7), 1302-1310, 2008.

- 45. N. Amjady and F. Keynia, Short-term load forecasting of power systems by combination of wavelet transform and neuroevolutionary algorithm, Energy, 34(1), 46 57, 2009.
- 46. Y. Zhu and Y. He, Short-term load forecasting model using fuzzy c means based radial basis function network, in Intelligent Systems Design and Applications, 2006. ISDA 06. Sixth International Conference on, 1, 579 -582, 2006.
- 47. C. Hor, S Watson, and S. Majithia. Daily Load Forecasting and Maximum Demand Estimation using ARIMA and GARCH. 9th Probabilistic Methods applied to Power System Conference (PMAPS), Stockholm, Sweden, 11 15, 2006.
- 48. D. Polani and R. Miikkulainen, Eugenic neuroevolution for reinforcement learning, in Proceedings of the genetic and evolutionary computation conference (GECCO-2000), 1041 -1046, 2000.
- K. O. Stanley and R. Miikkulainen, Efficient reinforcement learning through evolving neural network topologies, in Proceedings of the Genetic and Evolutionary Computation Conference, ser. GECCO 02, pp. 569 -577, 2002.
- J. Reisinger, K. Stanley, and R. Miikkulainen, Evolving reusable neural modules, in Genetic and Evolutionary Computation GECCO 2004, ser. Lecture Notes in Computer Science, K. Deb, Ed. Springer Berlin Heidelberg, 3103, 69-81, 2004.
- 51. N. Nisan, Pseudorandom generators for space-bounded computation, Combinatorica, vol. 12, no. 4, pp. 449461, 1992.

Table 2: Minimum MAPE values for the FCGPANN and three RCGPANN setups

Setup	Model	Year	Nodes	MAPE(%)
FCGPANN	Autumn	2009	150	1.4312
	Winter	2007	350	2.6617
	Spring	2007	250	1.5617
	Summer	2008	250	2.2459
	Annual	2008	350	2.1847
RCGPANN-1	Autumn	2009	200	1.5597
	Winter	2007	250	2.6914
	Spring	2007	100	2.5712
	Summer	2008	50	2.235
	Annual	2008	250	2.1884
RCGPANN-5	Autumn	2009	150	1.4652
	Winter	2007	50	2.6740
	Spring	2007	50	1.6107
	Summer	2008	50	2.2486
	Annual	2008	100	2.1904
RCGPANN-10	Autumn	2009	150	1.4310
	Winter	2007	500	2.6611
	Spring	2007	250	1.6012
	Summer	2008	100	2.3988
	Annual	2008	200	2.2058

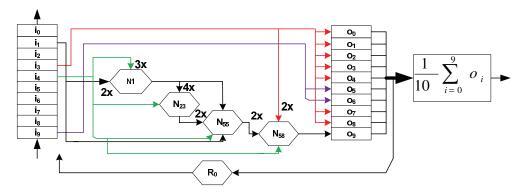


Figure 12: 200 nodes RCGPANN Setup with one feedback

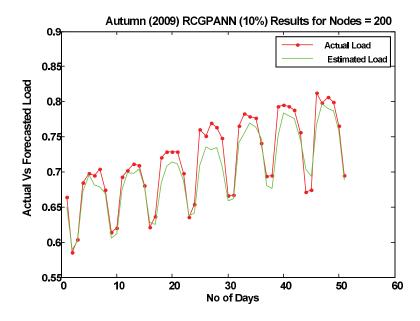


Figure 13: Actaul Vs Forecasted Autumn (2009) Peak Load Values using RCGPANN-1 feedback setup of 200 Nodes.

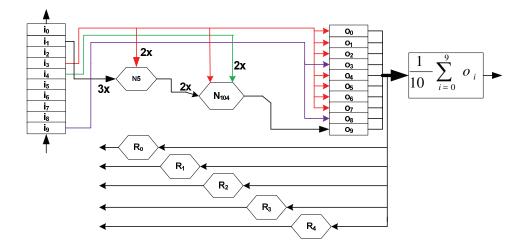


Figure 14: 150 Node RCGPANN Setup with 5 feedbacks

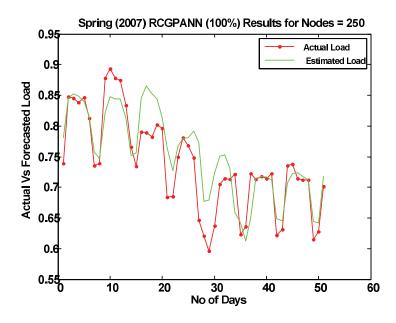


Figure 15: Actaul Vs Forecasted Spring 2007 Peak Load Values using RCGPANN 10 feedback setup of 250 Nodes.

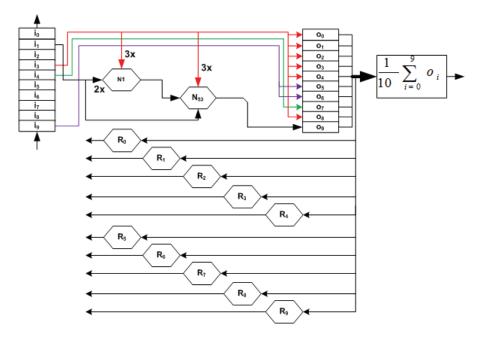


Figure 16: 250 Node RCGPANN Setup with 10 feedbacks

### G.M. Khan, R. Arshad / Load Forecasting LATEX

Table 3: MAPE comparison of FCGPANN AND RCGPANN with previous methods

S.No	Technique	% MAPE	Testing Data	Year	No of Days	Model
1	Non-Fixed ANNs 41	2.45	Hang Zhou Electric Power Company	2001	30	Summer
2	ANN based Models 10	3.05	Uttar pardesh Power Corporation Ltd.	2014	15	Summer
3	Proposed Scheme with FCG-PANN	2.2459	UK National Grid(London)	2008	110	Summer
4	Proposed Scheme with RCGPANN-1	2.235	UK National Grid(London)	2008	110	Summer
5	Proposed Scheme with RCGPANN-5	2.2486	UK National Grid(London)	2008	110	Summer
6	Proposed Scheme with RCGPANN-10	2.3988	UK National Grid(London)	2008	110	Summer
7	Functional clustering and linear regression <sup>42</sup>			2001- 2002	198	Annual
8	Probabilistic forecasts through cross scenario analysis by Hong et al. <sup>7</sup>	4.2	North Carolina Electric Membership Corporation (NCEMC)(USA)	2005- 2006	365	Annual
9	ARIMA and GARCH 47	2.24	UK National Grid(London)	2003	-	Annual
10	Exponential smoothing analysis by Jong-Hun Lim <sup>9</sup>	3.61	Building Energy Management System (BEMS)	2013	365	Annual
11	Holt-Winters exponential smoothing and an artificial neural network (ANN) by Ramos et al. <sup>11</sup>	7.60	FEDER Funds through the Programa Operacional Factores de Competitivi- dade COMPETE program and by Na- tional Funds through FCT Fundao para a Ciłncia e a Tecnologia.	2013	365	Annual
12	ANN models by Sahay et al. 15	2.23	Ontario Electricity Market	2012	365	Annual
13	Proposed Scheme with FCG-PANN	2.1847	UK National Grid(London)	2008	365	Annual
14	Proposed Scheme with RCGPANN-1	2.1884	UK National Grid(London)	2008	365	Annual
15	Proposed Scheme with RCGPANN-5	2.1904	UK National Grid(London)	2008	365	Annual
16	Proposed Scheme with RCGPANN-10	2.2058	UK National Grid(London)	2008	365	Annual

Table 4: Mean Relative Error comparison of FCGPANN and RCGPANN with previous methods

	<u>.</u>		1
S.No	Technique	% MRE	Model
1	Neural Networks with Weather Information 43	1.57	Summer
2	Bayesian regularization, resilient and adaptive back-propagation learning based ANNs 44	2.43	Summer
3	Wavelet transform and neuroevolutionary algorithm <sup>45</sup>	2.02	Summer
4	Fuzzy c means based radial basis function network 46	4.04	Summer
5	Proposed Scheme with RCGPANN-5(50 nodes)	1.5	Summer