

Figure 5. Time histories of the drag body depth

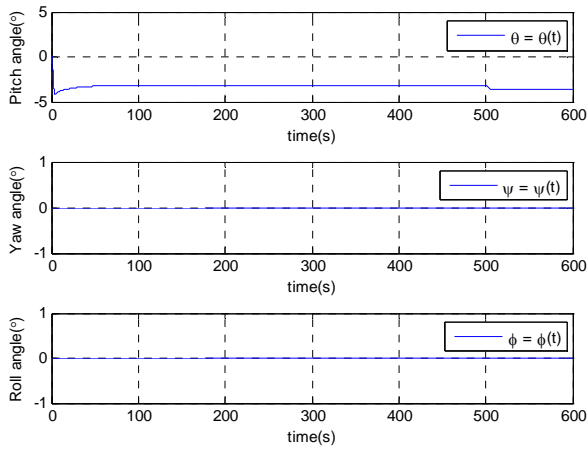


Figure 6. Time histories of the drag body posture angle

It can be seen that the motion of the navigation body, the cable and the drag body are coupling during the recycling; at the beginning of the recycling, due to the effect of the cable and the control the navigation body sinks slightly and the pitch angle of the navigation body increases until the cable is entirely recycled; the pulling force on the navigation body by the cable increases rapidly at the start and then decreases evenly in

course of recycling; the drag body rises gradually and the pitch angle of the drag body keeps in a steady value.

#### IV. CONCLUSIONS

A three-dimensions dynamic model of a typical underwater towed system is studied, and also the numerical simulation of the cable recycling is given which the towed system navigates at the fixed depth of 2.5 metres underwater by 6kn straightly. Via the figures shown above, it comes to the conclusions:

First, the motion of the navigation body, the cable and the drag body are coupling during the recycling;

Second, due to the pulling force by the cable, the navigation body sinks slightly, in order to navigate at the fixed depth, the control makes its' pitch angle increasing, the system will get to steady until the cable is totally recycled;

Third, at the beginning of the recycling, the pulling force on the navigation body by the cable grows rapidly because of the start of recycling, after getting to the maximum value when the relative velocity get steady to 0.4m/s, the force decreases gradually for the fluid resistance on the cable decreases greatly, the force will keep in a stable value when the cable is totally recycled;

At last, the depth of the drag body rises gradually and the pitch angle of the drag body keep in a stable value during the recycling, the depth and the pitch angle of the drag body will keep steady after the cable is completely recycled.

#### REFERENCES

- [1] Ablow C M, Schechter S. Numerical simulation of under sea cable dynamics. *Ocean Engineering*, 1983, 10(6): 443-457.
- [2] LIU Yu-qiang, SHENG Yan-feng, WANG Jun-qin,. Static Analysis and Attitude Calculation of Marine Submersible Buoy System and Its Application Development[J]. *OCEAN TECHNOLOGY*, 2010, 29 (3): 34-37..
- [3] Cao Shengwen, Min Qiangli. Numerical Calculation Analysis of Ocean Submersible Buoy Mooring System[J]. *MINE WARFARE & SHIP SELF-DEFENCE*, 2009, 17 (1): 27-30.
- [4] Ranmuthugala, S.D., Gottschalk, S.A., 1993, Dynamic Simulation of a Two-Part Underwater Tow. *Offshore Australia Conference*, 1-16..