A type of the travelling wave solutions of higher-order Camassa-Holm equations

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Abstract

This paper researches the wave equation of higher-order Camassa-Holm equations, the general expression of a type of travelling wave solutions is obtained.

Keywords: higher-order Camassa-Holm equations, the wave equation, the travelling wave solutions

1. Introduction

In 2003,Adrian Constantin and Boris Kolev first got the higher-order Camassa-Holm equations^[1]. Its concrete form is as follows:

$$\partial_t u = B_k(u, u), \tag{1}$$

where
$$k \in \{0\} \cup N$$
,
 $B_k(u,u) := A_k^{-1} C_k(u) - u \partial_x u$,
 $A_k(u) := \sum_{j=0}^k (-1)^j \partial_x^{2j} u$,
 $C_k(u) := -u A_k(\partial_x u) + A_k(u \partial_x u) - 2 \partial_x u A_k(u)$

In 2009, G.M.Coclite,H.Holden and K.H.Karlsen first researched the global Well-Posedness of the higher-order Camassa-Holm equations, and Got a weak

solution^{12]}. In 2010, Dingdanping, Lvpeng researched the existence of global solutions to the higher-order Camassa-Holm equations. Global solution is constructed by the small viscosity method for the frequency localized equations, especially global solution is energy conservative for given

finite band initial data^[3].

The structure of the paper is organized as follows. In Section 2, the formal solutions of higher-order C-H equations are obtained, In Section 3, Energy Conservation of the formal solutions is discussed. In Section 4, a type of travelling wave solutions are given.

2. The formal solution

According to the equation (1), we have

$$\sum_{j=0}^{k} (-1)^{j} [\partial_{x}^{2j}(\partial_{t}u) + u\partial_{x}^{2j}(\partial_{x}u) + 2\partial_{x}u\partial_{x}^{2j}u]$$

= 0 (2)

Let $u = \varphi(\xi) = \varphi(x - ct)$, the travelling wave equation of (2) is

$$\sum_{j=0}^{k} (-1)^{j} [(-c\varphi')^{(2j)} + \varphi(\varphi')^{(2j)} + 2\varphi'\varphi^{(2j)}] = 0$$
(3)

After twice-integration of equation (3), it was differentiated to yield

$$\varphi'(\varphi^{(2k)} - \varphi^{(2k-2)} + \varphi^{(2k-4)} - \cdots - (-1)^k \varphi'' + (-1)^k \varphi) = 0$$

if $\varphi' = 0$, then u = a (*a* is an arbitrary real number), otherwise,

$$\varphi^{(2k)} - \varphi^{(2k-2)} + \dots - (-1)^k \varphi'' + (-1)^k \varphi = 0.$$
 (4)

Equation (4) is ODE, when k = 0, the solution is u = a (a is an arbitrary real number). For $k \ge 1$, its characteristic equation is

$$r^{2k} - r^{2k-2} + r^{2k-4} - \dots - (-1)^k r^2 + (-1)^k = 0.$$
 (5)

According to references [4-6], the roots of (5) have the form as follows:

$$r_i = \pm \alpha_i \pm i \beta_i$$
,

where $||r_i|| = \sqrt{\alpha_i^2 + \beta_i^2} = 1, a_i > 0, \beta_i > 0$, a ndwhen k is even, $i = 1, 2, \dots, \frac{k}{2}$, when k is odd, $i = 1, 2, \dots, \frac{k+1}{2}$.

So when k is even, the formal solution of (2) is

$$u(x,t) = \sum_{i=1}^{k/2} \left[e^{\alpha_i (x-ct)} (c_{i1} \cos \beta_i (x-ct) + c_{i2} \sin \beta_i (x-ct)) + e^{-\alpha_i (x-ct)} (c_{i3} \cos \beta_i (x-ct) + c_{i4} \sin \beta_i (x-ct)) \right]$$

where $c_{i1}, c_{i2}, c_{i3}, c_{i4}$ are coefficients,

when k is odd, the formal solution of (2) is

$$u(x,t) = \sum_{i=1}^{(k+1)/2} \left[e^{\alpha_i(x-ct)} (c_{i1} \cos \beta_i(x-ct) + c_{i2} \sin \beta_i(x-ct)) + e^{-\alpha_i(x-ct)} (c_{i3} \cos \beta_i(x-ct) + c_{i4} \sin \beta_i(x-ct)) \right]$$

where $c_{i1}, c_{i2}, c_{i3}, c_{i4}$ are coefficients.

3. Energy Conservation

According to attenuation of the travelling wave solutions, the formal solution can be reduced to

$$u(x,t) = \sum_{i=1}^{k/2} e^{-|\alpha_i(x-ct)|} [c_{i1} \cos \beta_i(x-ct) + c_{i2} \sin \beta_i(x-ct)] (k \text{ is even}),$$

$$u(x,t) = \sum_{i=1}^{(k+1)/2} e^{-|\alpha_i(x-ct)|} [c_{i1} \cos \beta_i(x-ct) + c_{i2} \sin \beta_i(x-ct)] (k \text{ is odd}).$$

if u(x,t) obeys conservation of energy while k is even, then when k is odd, the same conclusion can be obtained.

Let
$$I(t) = \int_{R} u^2 + (\partial_x u)^2 + \dots + (\partial_x^k u)^2 dx$$
,

then
$$\frac{dI(t)}{dt} = \sum_{l=0}^{k} \int_{R} \partial_{x}^{l} u \partial_{x}^{l} (\partial_{t} u) dx (\partial_{t} u = -c \partial_{x} u)$$
$$= -c \cdot \sum_{l=0}^{k} \int_{R} \partial_{x}^{l} u \partial_{x}^{l+1} u dx ,$$

if
$$u(x,t)$$
 satisfies the condition of
 $\frac{dI(t)}{dt} = 0$ in a certain assumptions, a type
of travelling wave solutions can be ob-
tained. So two independent assumed con-
ditions are given.

3.1.
$$c_{i2} = 0$$

when k is even $(k \neq 0)$, then

$$\int_{-\infty}^{ct} \partial_x^l u \partial_x^{l+1} u dx$$

= $\sum_{1 \le i, j \le \frac{k}{2}} c_{i1} c_{j1} \int_{-\infty}^{ct} e^{(\alpha_i + \alpha_j)(x - ct)} \cos(l\theta_{i1} + \beta_i(x - ct)) \cdot$

$$\cos(\theta_{j1}+l\theta_{j1}+\beta_j(x-ct))dx,$$

where
$$\cos \theta_{i1} = a_i \sin \theta_{i1} = \beta_i , l = 0, 1, 2, \dots, k$$
,

$$\int_{-\infty}^{ct} e^{(\alpha_i + \alpha_j)(x - ct)} \cos(l\theta_{i1} + \beta_i (x - ct)) \cdot \cos(\theta_{j1} + l\theta_{j1} + \beta_j (x - ct)) dx$$

$$= \frac{1}{2} \cos(l\theta_{i1} + \theta_{j1} + l\theta_{j1}) \frac{\alpha_i + \alpha_j}{(\alpha_i + \alpha_j)^2 + (\beta_i + \beta_j)^2}$$

$$+ \frac{1}{2} \sin(l\theta_{i1} + \theta_{j1} + l\theta_{j1}) \frac{(\beta_i + \beta_j)}{(\alpha_i + \alpha_j)^2 + (\beta_i + \beta_j)^2}$$

$$+ \frac{1}{2} \cos(l\theta_{i1} - \theta_{j1} - l\theta_{j1}) \frac{\alpha_i + \alpha_j}{(\alpha_i + \alpha_j)^2 + (\beta_i - \beta_j)^2}$$

$$+\frac{1}{2}\sin(l\theta_{i1}-\theta_{j1}-l\theta_{j1})\frac{(p_i-p_j)}{(\alpha_i+\alpha_j)^2+(\beta_i-\beta_j)^2}$$

$$\int_{ct}^{+\infty} \partial_x^l u \partial_x^{l+1} u dx$$

= $\sum_{1 \le i, j \le \frac{k}{2}} c_{i1} c_{j1} \int_{ct}^{+\infty} e^{-(\alpha_i + \alpha_j)(x - ct)} \cos(l\theta_{i2} + \beta_i (x - ct)) \cdot$

$$\cos(\theta_{j2}+l\theta_{j2}+\beta_j(x-ct))dx,$$

where $\cos \theta_{i2} = -a_i$, $\sin \theta_{i2} = \beta_i$, $\theta_{i2} = \pi - \theta_{i1}$.

$$\int_{ct}^{+\infty} e^{-(\alpha_i + \alpha_j)(x - ct)} \cos(l\theta_{i2} + \beta_i(x - ct)) \cdot \\ \cos(\theta_{j2} + l\theta_{j2} + \beta_j(x - ct)) dx$$
$$= -\frac{1}{2} \cos(l\theta_{i1} + \theta_{j1} + l\theta_{j1}) \frac{\alpha_i + \alpha_j}{(\alpha_i + \alpha_j)^2 + (\beta_i + \beta_j)^2}$$

$$-\frac{1}{2}\sin(l\theta_{i1}+\theta_{j1}+l\theta_{j1})\frac{(\beta_i+\beta_j)}{(\alpha_i+\alpha_j)^2+(\beta_i+\beta_j)^2}$$

$$-\frac{1}{2}\cos(l\theta_{i1}-\theta_{j1}-l\theta_{j1})\frac{\alpha_i+\alpha_j}{(\alpha_i+\alpha_j)^2+(\beta_i-\beta_j)^2}$$

$$-\frac{1}{2}\sin(l\theta_{i1}-\theta_{j1}-l\theta_{j1})\frac{(\beta_i-\beta_j)}{(\alpha_i+\alpha_j)^2+(\beta_i-\beta_j)^2}$$

then
$$\int_{R} \partial_{x}^{l} u \partial_{x}^{l+1} u dx$$
$$= \int_{-\infty}^{ct} \partial_{x}^{l} u \partial_{x}^{l+1} u dx + \int_{ct}^{+\infty} \partial_{x}^{l} u \partial_{x}^{l+1} u dx$$
$$= \sum_{1 \le i, j \le \frac{k}{2}} c_{i1} c_{j1} \cdot 0$$
$$= 0,$$

then
$$\frac{dI(t)}{dt} = -c \cdot \sum_{l=0}^{k} \int_{R} \partial_{x}^{l} u \partial_{x}^{l+1} u dx = 0$$
.

So when k is even, u(x,t) obeys conservation of energy. the same conclusion is obtained while k is odd.

3.2. $c_{i1} = 0$

,

In this case, the same method is used to proof that the formal solution is also obeys conservation of energy.

4. Conclusions

A type of the travelling wave solutions of higher-order Camassa-Holm equations is as follows:

when k is even,

$$u(x,t) = \sum_{i=1}^{k/2} c_i e^{-|\alpha_i(x-ct)|} \cos \beta_i(x-ct),$$

or $u(x,t) = \sum_{i=1}^{k/2} c_i e^{-|\alpha_i(x-ct)|} \sin \beta_i(x-ct);$

when k is odd,

$$u(x,t) = \sum_{i=1}^{(k+1)/2} c_i e^{-|\alpha_i(x-ct)|} \cos \beta_i(x-ct),$$

or

$$u(x,t) = \sum_{i=1}^{(k+1)/2} c_i e^{-|\alpha_i(x-ct)|} \sin \beta_i(x-ct) ,$$

where c_i is an arbitrary real number, $\alpha_i > 0$ and $\beta_i > 0$, them are determined by the following equation:

$$r^{2k} - r^{2k-2} + r^{2k-4} - \dots - (-1)^k r^2 + (-1)^k = 0.$$

The solution of this equation is

 $r_i = \pm \alpha_i \pm i\beta_i (\alpha_i^2 + \beta_i^2 = 1), \text{ when } k \text{ is}$ even, the subscript $i = 1, 2, 3, \dots, \frac{k}{2}$, when k is odd, the subscript $i = 1, 2, 3, \dots, \frac{k+1}{2}$ and $r_{(k+1)/2} = \pm \alpha_{(k+1)/2} \pm \beta_{(k+1)/2} = \pm 1$.

Moreover, when k = 1, the travelling wave solution is $u(x,t) = c_1 e^{-|x-ct|}$ (c_1 is an arbitrary real number). It is the soliton solution^[7] of Camassa-Holm equation which is obtained by Camassa and Holm.

5. References

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