# A Finite Dimensional Completely Integrable System Associated with the WKIand Heisenberg Hierarchies 

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$$
\begin{gather*}
\text { Abstract } \\
\text { We consider the following spectral problem } \\
\qquad\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right]_{x}=\zeta\left[\begin{array}{cc}
-w & u \\
v & w
\end{array}\right]\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right] \equiv M\left[\begin{array}{l}
y_{1} \\
y_{2}
\end{array}\right] \tag{1}
\end{gather*}
$$

where $u, v, w$ are smooth functions. It produces a hierarchy of evolution equations with an arbitrary function $A_{m-1}$. This hierarchy includes the WKI [8] and Heisenberg [7] hierarchies by properly selecting the special function $A_{m-1}$. We derive this new evolution equations, and give the finite dimensional completely integrable systems (FDCIS) associated with theses equations.

## 1 The hierarchy and the Lax pair

Let

$$
M=\zeta\left[\begin{array}{cc}
-w & u \\
v & w
\end{array}\right], \quad N_{j}=\left[\begin{array}{cc}
A_{j} & B_{j} \\
C_{j} & -A_{j}
\end{array}\right]
$$

be the smooth matrix functions. Set the pair of Lenard's operators as

$$
K=\left[\begin{array}{ccc}
0 & v & -u \\
2 u & -2 w & 0 \\
-2 v & 0 & 2 w
\end{array}\right], \quad J=\left[\begin{array}{ccc}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right] \partial_{x}
$$

and define the Lenard sequence $\left\{L_{j}\right\}(j=0,1,2, \ldots, m-1)$ recursively:

$$
L_{j}=\left(-A_{j}, B_{j}, C_{j}\right)^{T}
$$

with

$$
\begin{align*}
& L_{0}=\frac{\alpha}{\sqrt{w^{2}+u v}}\left[\begin{array}{l}
w \\
u \\
v
\end{array}\right] \equiv \frac{\alpha}{r}\left[\begin{array}{l}
w \\
u \\
v
\end{array}\right], \quad(\alpha \neq 0 \text { constant }),  \tag{2}\\
& J L_{j}=K L_{j+1}, \quad j=0,1,2, \ldots m-2 .
\end{align*}
$$

Lemma 1. The commutator $\left[M, N_{j}\right]=M N_{j}-N_{j} M$ satisfies:

$$
\begin{equation*}
\left[M, N_{j}\right]=N_{j x}+M_{*}\left(K L_{j}\right)-\zeta M_{*}\left(J L_{j}\right) \tag{3}
\end{equation*}
$$

where

$$
M_{*}(\delta w, \delta u, \delta v)=\left.\frac{\partial}{\partial \varepsilon}\right|_{\varepsilon=0} M(w+\varepsilon \delta w, u+\varepsilon \delta u, v+\varepsilon \delta v)=\zeta\left[\begin{array}{cc}
-\delta w & \delta u \\
\delta v & \delta w
\end{array}\right] .
$$

Notice that $A_{m-1}$ is an arbitrary function. $X_{m} \equiv J L_{m-1}$ is the $m^{t h}$ order vector field of the evolution equation hierarchy

$$
\left[\begin{array}{l}
w  \tag{4}\\
u \\
v
\end{array}\right]_{t_{m}}=X_{m}, \quad m=1,2, \ldots
$$

From Lemma 1 and the fact that $K L_{0}=0$ we get the following:
Theorem 1. Let $\left\{L_{j}\right\}, j=0,1,2, \ldots$ be a Lenard sequence. Each of the vector fields $X_{m}$ $(m=1,2, \ldots)$ has a commutator representation:

$$
M_{*}\left(X_{m}\right)=V_{m x}+\left[V_{m}, M\right]
$$

where

$$
V_{m}=\sum_{j=0}^{m-1} N_{j} \zeta^{m-j}, \quad \zeta_{t_{m}} \equiv 0
$$

Corollary. Each evolution equation (4) has a Lax pair:

$$
\left\{\begin{array}{l}
\phi_{x}=M \phi,  \tag{5}\\
\phi_{t_{m}}=V_{m} \phi,
\end{array} \quad \zeta_{t_{m}}=0\right.
$$

Special choices of the function $A_{m-1}$ and the constraint give us either the $W K I$ or the Heisenberg hierarchy. Indeed for $A_{m-1}=0$ and $w=1, r=\sqrt{u v+1}$ we obtain the WKI hierarchy whereas for $A_{m-1, x}=\frac{1}{2 w}\left(u C_{m-1, x}+v B_{m-1, x}\right)$ and $r=\sqrt{u v+w^{2}}=1$ we obtain the Heisenberg hierarchy. For example, the Lenard sequence is $L_{0}=\frac{\alpha}{r}(w, u, v)^{T}, L_{1}=$ $\frac{\alpha}{4 r^{3}}\left(v u_{x}-u v_{x}, 2\left(u w_{x}-w u_{x}\right), 2\left(w v_{x}-v w_{x}\right)\right)^{T}$, etc. so the second order $W K I$ equation is

$$
\left[\begin{array}{l}
u \\
v
\end{array}\right]_{t_{2}}=\frac{\alpha}{2}\left[\begin{array}{c}
-\frac{u}{r} \\
\frac{v}{r}
\end{array}\right]_{x x}, \quad r=\sqrt{1+u v}
$$

the third order $W K I$ equation is

$$
\left[\begin{array}{c}
u \\
v
\end{array}\right]_{t_{3}}=\frac{\alpha}{4}\left[\begin{array}{c}
\frac{u_{x}}{r^{3}} \\
\frac{v_{x}}{r^{3}}
\end{array}\right]_{x x}
$$

The second order Heisenberg equation is

$$
\left[\begin{array}{l}
u \\
v
\end{array}\right]_{t_{2}}=\frac{\alpha}{2}\left[\begin{array}{c}
u w_{x x}-w u_{x x} \\
w v_{x x}-v w_{x x}
\end{array}\right], \quad r=1
$$

## 2 Associated FDCIS

Using the constraints and nonlinearization of the Lax pairs we derive finite dimensional completely integrable systems (FDCIS) associated with the infinite dimensional hierarchies. From the eigenvalue problem (1), we have

$$
\operatorname{grad} \zeta_{j}=\left[\begin{array}{c}
\delta \zeta_{j} / \delta w \\
\delta \zeta_{j} / \delta u \\
\delta \zeta_{j} / \delta v
\end{array}\right]=\gamma_{j}\left[\begin{array}{c}
-\zeta_{j} y_{1 j} y_{2 j} \\
\zeta_{j} y_{2 j}^{2} \\
-\zeta_{j} y_{1 j}^{2}
\end{array}\right]
$$

where

$$
\gamma_{j}=\left(\int_{\Omega}\left(-v y_{1 j}^{2}-w y_{1 j} y_{2 j}+u y_{2 j}^{2}\right) d x\right)^{-1}
$$

Let $G_{0}=\sum_{j=1}^{N} \operatorname{grad} \zeta_{j}$. We get the constraint

$$
\frac{\alpha}{r} w=-\langle A q, p\rangle, \quad \frac{\alpha}{r} u=\langle A q, q\rangle, \quad \frac{\alpha}{r} v=-\langle A p, p\rangle,
$$

where $p=\left(y_{11}, \ldots, y_{1 N}\right)^{T}, q=\left(y_{21}, \ldots, y_{2 N}\right)^{T}$ and $A=\operatorname{diag}\left(\zeta_{1}, \ldots, \zeta_{N}\right)$. In the case of Heisenberg, $r=\sqrt{u v+w^{2}}=1$, the constraint becomes

$$
\begin{equation*}
w=-\langle A q, p\rangle, \quad u=\langle A q, q\rangle, \quad v=-\langle A p, p\rangle . \tag{6}
\end{equation*}
$$

In the case of WKI, $w=1, r=\sqrt{w^{2}+u v}=\sqrt{1+u v}$, we have the following constraint:

$$
\begin{equation*}
u=\langle A q, p\rangle^{-1}\langle A q, q\rangle, \quad v=\langle A q, p\rangle^{-1}\langle A p, p\rangle . \tag{7}
\end{equation*}
$$

Now we nonlinearize the Lax pairs by plugging the constraint (7) into the Lax pairs. Then (1) becomes the restricted flow

$$
\begin{equation*}
p_{x}=-w A p+u A p, \quad q_{x}=v A p+w A q . \tag{8}
\end{equation*}
$$

Now plugging in the constraint (7) into (8), we get

$$
\begin{equation*}
p_{x}=-A p+\langle A q, p\rangle^{-1}\langle A q, q\rangle A q, \quad q_{x}=A q-\langle A q, p\rangle^{-1}\langle A p, p\rangle A p . \tag{9}
\end{equation*}
$$

The equation (9) is the nonlinearization of the eigenvalue problem (1), which can be written in canonical Hamiltonian form

$$
\begin{equation*}
q_{x}=\frac{\partial H_{0}}{\partial p}, \quad p_{x}=-\frac{\partial H_{0}}{\partial q} \tag{10}
\end{equation*}
$$

where $H_{0}=-\langle A q, p\rangle+\sqrt{\alpha^{2}+\langle A q, q\rangle\langle A p, p\rangle}$ with $\alpha \neq 0$ the constant given by the Lenard sequence (2).
Theorem 2. The Hamiltonian system (10) is completely integrable (in the Liouville sense) with the following $N$ functions in involution: $H_{0}, H_{2}, \ldots H_{N}$

$$
\begin{aligned}
H_{m} & =-\frac{1}{2} \sum_{j=0}^{m-1}\left|\begin{array}{cc}
\left\langle A^{j+1} q, q\right\rangle & \left\langle A^{j+1} q, p\right\rangle \\
\left\langle A^{m-j} p, q\right\rangle & \left\langle A^{m-j} p, p\right\rangle
\end{array}\right|+\left\langle A^{m} q, p\right\rangle H_{0} \\
& =G_{m}+\left\langle A^{m} q, p\right\rangle H_{0}, \quad m=2,3, \ldots, N .
\end{aligned}
$$

where $\left\{G_{m}\right\}$ is a confocal involutive system, Cao [2], Moser [5]. The level sets are

$$
M_{f}=\left\{(q, p) \in \mathbf{R}^{2 N} \mid H_{0}(q, p)=0, H_{m}(q, p)=f_{m}, m=2,3, \ldots N\right\} .
$$

## 3 The relation between the higher order WKI and Heisenberg equations and the system ( $\boldsymbol{H}_{0}$ )

Define the involutive solution of $H_{0}$ and $H_{m}$ :

$$
\left[\begin{array}{l}
q \\
p
\end{array}\right] \equiv\left[\begin{array}{l}
q\left(x, t_{m}\right) \\
p\left(x, t_{m}\right)
\end{array}\right]=g_{0}^{x} \circ g_{m}^{t_{m}}\left[\begin{array}{l}
q(0,0) \\
p(0,0)
\end{array}\right], \quad\left[\begin{array}{l}
q(0,0) \\
p(0,0)
\end{array}\right] \in M_{f},
$$

where $g_{0}^{x}$ and $g_{m}^{t_{m}}$ are respectively the phase flows with Hamiltonian function $\left(H_{0}\right)$ and $\left(H_{m}\right)$.
Lemma 2. Let $\left[\begin{array}{l}q \\ p\end{array}\right]$ be an involutive solution of $\left(H_{0}\right)$ and $\left(H_{m}\right)$

$$
(u, v)^{T}=\langle A q, p\rangle^{-1}(\langle A q, q\rangle,-\langle A p, p\rangle)^{T}=f(q, p),
$$

then there exist constants $\alpha_{0}, \alpha_{1}, \ldots, \alpha_{m-2}$ such that

$$
\begin{equation*}
\sum_{l=0}^{j} \alpha_{j} G_{j-l}=\left(-\left\langle A^{j+1} q, p\right\rangle,-\left\langle A^{j+1} q, q\right\rangle,\left\langle A^{j+1} p, p\right\rangle\right)^{T}, \quad j=0,1, \ldots, m-2 . \tag{11}
\end{equation*}
$$

Theorem 3. Let $\left[\begin{array}{l}q \\ p\end{array}\right]$ be an involutive solution of $\left(H_{0}\right)$ and $\left(H_{m}\right)(m=2,3, \ldots, N)$ on $M_{f}$, and $\left[\begin{array}{l}u \\ v\end{array}\right]=\langle A q, p\rangle^{-1}(\langle A q, q\rangle,-\langle A p, p\rangle)^{T}=f(q, p)$. Then

1. $\left(H_{0}\right)$ and $\left(H_{m}\right)$ are reduced to the spatial and time part respectively of the Lax pair of the higher order WKI equation (with potential $(u, v)^{T}$ )

$$
\left[\begin{array}{c}
u  \tag{12}\\
v
\end{array}\right]_{t_{m}}=\sum_{l=0}^{m-2} \alpha_{l} \bar{X}_{m-l}(u, v)
$$

( $\alpha_{0}, \alpha_{1}, \ldots, \alpha_{m-2}$ are given by Lemma 2)

$$
\left[\begin{array}{l}
q  \tag{13}\\
p
\end{array}\right]_{x}=\left[\begin{array}{cc}
-A & u A \\
v A & A
\end{array}\right]\left[\begin{array}{l}
q \\
p
\end{array}\right]=M(f(q, p))\left[\begin{array}{l}
q \\
p
\end{array}\right]
$$

$$
\left[\begin{array}{c}
q  \tag{14}\\
p
\end{array}\right]_{t_{m}}=\sum_{l=0}^{m-2} \alpha_{l} V_{m-l}(f(q, p))\left[\begin{array}{l}
q \\
p
\end{array}\right] .
$$

2. $\left[\begin{array}{l}u \\ v\end{array}\right]=f(q, p)$ satisfy the higher order WKI equation (12).

Remark. As $\alpha>0$, let $\left[\begin{array}{l}u \\ v\end{array}\right]=-f(q, p), \bar{H}_{m}=-H_{m}(m=0,2, \ldots, N)$, Theorem 3 is still true.
Theorem 4. Let $\left[\begin{array}{l}q \\ p\end{array}\right]$ be an involutive solution of $\left(G_{1}\right)$ and $\left(G_{m}\right)$ of the canonical system:

$$
G_{m}=-\frac{1}{2} \sum_{i+j=m-1}\left|\begin{array}{cc}
\left\langle A^{j+1} q, q\right\rangle & \left\langle A^{j+1} q, p\right\rangle \\
\left\langle A^{i+1} p, q\right\rangle & \left\langle A^{i+1} p, p\right\rangle
\end{array}\right|, \quad m=1,2, \ldots, N
$$

on the level set $\Omega_{h}=\left\{(q, p) \in \mathbf{R}^{2 N}, G_{m}=h_{m}, m=1, \ldots, N, h_{1}=\frac{1}{2}\right\}$ and

$$
\left[\begin{array}{c}
w \\
u \\
v
\end{array}\right]\left[\begin{array}{c}
-\langle A q, p\rangle \\
-\langle A q, q\rangle \\
\langle A p, p\rangle
\end{array}\right]=g(q, p)
$$

Then

1. $\left(G_{1}\right)$ and $\left(G_{m}\right)$ are reduced to the spatial and time part respectively of the Lax pair of higher order Heisenberg equation (with potential $(w, u, v), w^{2}+u v=1, \alpha=1$ ),

$$
\left[\begin{array}{l}
w  \tag{15}\\
u \\
v
\end{array}\right]_{t_{m}}=\sum_{j=0}^{m-1} \beta_{i} \tilde{X}_{m-j}(w, u, v)
$$

$\left(\beta_{0}=1, \beta_{n}(n=1,2, \ldots, m-1)\right.$ are some constants $)$ :

$$
\begin{align*}
& {\left[\begin{array}{l}
q \\
p
\end{array}\right]_{x}=\left[\begin{array}{ll}
\langle A q, p\rangle A & -\langle A q, q\rangle A \\
\langle A p, p\rangle A & -\langle A q, p\rangle A
\end{array}\right]\left[\begin{array}{l}
q \\
p
\end{array}\right]}  \tag{16}\\
& {\left[\begin{array}{l}
q \\
p
\end{array}\right]_{t_{m}}=\sum_{j=0}^{m-1} \beta_{j} V_{m-j}(g(q, p))\left[\begin{array}{l}
q \\
p
\end{array}\right]} \tag{17}
\end{align*}
$$

2. $(w, u, v)^{T}=g(q, p)$ satisfies the higher order Heisenberg equation (15).

For details and proofs we refer to $[6,9]$.

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